

# Linear-Programming

Julian Parsert

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## Abstract

We use the previous formalization of the general simplex algorithm to formulate an algorithm for solving linear programs. We encode the linear programs using only linear constraints. Solving these constraints also solves the original linear program. This algorithm is proven to be sound by applying the weak duality theorem which is also part of this formalization [5].

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## 1 Related work

Our work is based on a formalization of the general simplex algorithm described in [3, 6]. However, the general simplex algorithm lacks the ability to optimize a function. Boulmé and Maréchal [2] describe a formalization and implementation of Coq tactics for linear integer programming and linear

arithmetic over rationals. More closely related is the formalization by Al-lamigeon et al. [1] which formalizes the simplex method and related results. As part of Flyspeck project Obua and Nipkow [4] created a verification mechanism for linear programs using the HOL computing library and external solvers.

```
theory More-Jordan-Normal-Forms
imports
  Jordan-Normal-Form.Matrix-Impl
begin
```

```
lemma set-comprehension-list-comprehension:
  set [f i . i <- [x..] = {f i |i. i ∈ {x..}}
  ⟨proof⟩
```

```
lemma in-second-append-list: i ≥ length a ⇒ i < length (a@b) ⇒ (a@b)!i ∈ set b
  ⟨proof⟩
```

## 2 General Theorems used later, that could be moved

```
lemma split-four-block-dual-fst-lst:
  assumes split-block (four-block-mat A B C D) (dim-row A) (dim-col A) = (U, X, Y, V)
  shows U = A V = D
  ⟨proof⟩
```

```
lemma append-split-vec-distrib-scalar-prod:
  assumes dim-vec (u @v w) = dim-vec x
  shows (u @v w) · x = u · (vec-first x (dim-vec u)) + w · (vec-last x (dim-vec w))
  ⟨proof⟩
```

```
lemma append-dot-product-split:
  assumes dim-vec (u @v w) = dim-vec x
  shows (u @v w) · x = (∑ i ∈ {0..< dim-vec u}. u\$i * x\$i) + (∑ i ∈ {0..< dim-vec w}. w\$i * x\$i + dim-vec u))
  ⟨proof⟩
```

```
lemma assoc-scalar-prod-mult-mat-vec:
  fixes A :: 'a::comm-semiring-1 mat
  assumes y ∈ carrier-vec n
  assumes x ∈ carrier-vec m
  assumes A ∈ carrier-mat n m
  shows (A *v x) · y = (AT *v y) · x
  ⟨proof⟩
```

### 3 Vectors

**abbreviation** *singletonV* ( $\langle [-]_v \rangle$ ) **where** *singletonV e*  $\equiv$  (*vec 1* ( $\lambda i. e$ ))

**lemma** *elem-in-singleton* [*simp*]:  $[a]_v \$ 0 = a$   
 $\langle proof \rangle$

**lemma** *elem-in-singleton-append* [*simp*]:  $(x @_v [a]_v) \$ dim\text{-}vec x = a$   
 $\langle proof \rangle$

**lemma** *vector-cases-append*:  
**fixes**  $x :: 'a vec$   
**shows**  $x = vNil \vee (\exists v a. x = v @_v [a]_v)$   
 $\langle proof \rangle$

**lemma** *vec-rev-induct* [*case-names vNil append, induct type: vec*]:  
**assumes**  $P vNil$  **and**  $\bigwedge a v. P v \implies P (v @_v [a]_v)$   
**shows**  $P v$   
 $\langle proof \rangle$

**lemma** *singleton-append-dotP*:  
**assumes**  $dim\text{-}vec z = dim\text{-}vec y + 1$   
**shows**  $(y @_v [x]_v) \cdot z = (\sum_{i \in \{0..<dim\text{-}vec y\}} y \$ i * z \$ i) + x * z \$ dim\text{-}vec y$   
 $\langle proof \rangle$

**lemma** *map-vec-append*:  $map\text{-}vec f (a @_v b) = map\text{-}vec f a @_v map\text{-}vec f b$   
 $\langle proof \rangle$

**lemma** *map-mat-map-vec*:  
**assumes**  $i < dim\text{-}row P$   
**shows**  $row (map\text{-}mat f P) i = map\text{-}vec f (row P i)$   
 $\langle proof \rangle$

**lemma** *append-rows-access1* [*simp*]:  
**assumes**  $i < dim\text{-}row A$   
**assumes**  $dim\text{-}col A = dim\text{-}col B$   
**shows**  $row (A @_r B) i = row A i$   
 $\langle proof \rangle$

**lemma** *append-rows-access2* [*simp*]:  
**assumes**  $i \geq dim\text{-}row A$   
**assumes**  $i < dim\text{-}row A + dim\text{-}row B$   
**assumes**  $dim\text{-}col A = dim\text{-}col B$   
**shows**  $row (A @_r B) i = row B (i - dim\text{-}row A)$   
 $\langle proof \rangle$

**lemma** *append-singleton-access* [*simp*]:  $(Matrix.\text{vec } n f @_v [r]_v) \$ n = r$   
 $\langle proof \rangle$

Move to right place

```
fun mat-append-col where
  mat-append-col A b = mat-of-cols (dim-row A) (cols A @ [b])

fun mat-append-row where
  mat-append-row A c = mat-of-rows (dim-col A) (rows A @ [c])

lemma mat-append-col-dims:
  shows mat-append-col A b ∈ carrier-mat (dim-row A) (dim-col A + 1)
  ⟨proof⟩

lemma mat-append-row-dims:
  shows mat-append-row A c ∈ carrier-mat (dim-row A + 1) (dim-col A)
  ⟨proof⟩

lemma mat-append-col-col:
  assumes dim-row A = dim-vec b
  shows col (mat-append-col A b) (dim-col A) = b
  ⟨proof⟩

lemma mat-append-col-vec-index:
  assumes i < dim-row A
  and dim-row A = dim-vec b
  shows (row (mat-append-col A b) i) $ (dim-col A) = b $ i
  ⟨proof⟩

lemma mat-append-row-row:
  assumes dim-col A = dim-vec c
  shows row (mat-append-row A c) (dim-row A) = c
  ⟨proof⟩

lemma mat-append-row-in-mat:
  assumes i < dim-row A
  shows row (mat-append-row A r) i = row A i
  ⟨proof⟩

lemma mat-append-row-vec-index:
  assumes i < dim-col A
  and dim-col A = dim-vec b
  shows vec-index (col (mat-append-row A b) i) (dim-row A) = vec-index b i
  ⟨proof⟩

lemma mat-append-col-access-in-mat:
  assumes dim-row A = dim-vec b
  and i < dim-row A
  and j < dim-col A
  shows (row (mat-append-col A b) i) $ j = (row A i) $ j
  ⟨proof⟩
```

```

lemma constructing-append-col-row:
  assumes  $i < \text{dim-row } A$ 
  and  $\text{dim-row } A = \text{dim-vec } b$ 
  shows  $\text{row}(\text{mat-append-col } A \ b) \ i = \text{row } A \ i @_v [\text{vec-index } b \ i]_v$ 
   $\langle\text{proof}\rangle$ 

definition one-element-vec where  $\text{one-element-vec } n \ e = \text{vec } n (\lambda i. \ e)$ 

lemma one-element-vec-carrier:  $\text{one-element-vec } n \ e \in \text{carrier-vec } n$ 
   $\langle\text{proof}\rangle$ 

lemma one-element-vec-dim [simp]:  $\text{dim-vec}(\text{one-element-vec } n (\text{r::rat})) = n$ 
   $\langle\text{proof}\rangle$ 

lemma one-element-vec-access [simp]:  $\bigwedge i. \ i < n \implies \text{vec-index}(\text{one-element-vec } n \ e) \ i = e$ 
   $\langle\text{proof}\rangle$ 

fun single-nz-val where  $\text{single-nz-val } n \ i \ v = \text{vec } n (\lambda j. (\text{if } i = j \text{ then } v \text{ else } 0))$ 

lemma single-nz-val-carrier:  $\text{single-nz-val } n \ i \ v \in \text{carrier-vec } n$ 
   $\langle\text{proof}\rangle$ 

lemma single-nz-val-access1 [simp]:  $i < n \implies \text{single-nz-val } n \ i \ v \$ i = v$ 
   $\langle\text{proof}\rangle$ 

lemma single-nz-val-access2 [simp]:  $i < n \implies j < n \implies i \neq j \implies \text{single-nz-val } n \ i \ v \$ j = 0$ 
   $\langle\text{proof}\rangle$ 

lemma  $i < n \implies (v \cdot_v \text{unit-vec } n \ i) \$ i = (v :: 'a :: \{\text{monoid-mult}, \text{times}, \text{zero-neq-one}\})$ 
   $\langle\text{proof}\rangle$ 

lemma single-nz-val-unit-vec:
  fixes  $v :: 'a :: \{\text{monoid-mult}, \text{times}, \text{zero-neq-one}, \text{mult-zero}\}$ 
  shows  $v \cdot_v (\text{unit-vec } n \ i) = \text{single-nz-val } n \ i \ v$ 
   $\langle\text{proof}\rangle$ 

lemma single-nz-valI [intro]:
  fixes  $v \ i \ \text{val}$ 
  assumes  $\bigwedge j. \ j < \text{dim-vec } v \implies j \neq i \implies v \$ j = 0$ 
  assumes  $v \$ i = \text{val}$ 
  shows  $v = \text{single-nz-val } (\text{dim-vec } v) \ i \ \text{val}$ 
   $\langle\text{proof}\rangle$ 

lemma single-nz-val-dotP:

```

```

assumes  $i < n$ 
assumes  $\text{dim-vec } x = n$ 
shows  $\text{single-nz-val } n \ i \ v \cdot x = v * x \$ i$ 
⟨proof⟩

lemma  $\text{single-nz-zero-singleton}: \text{single-nz-val } 1 \ 0 \ v = [v]_v$ 
⟨proof⟩

lemma  $\text{append-one-elem-zero-dotP}:$ 
assumes  $\text{dim-vec } u = m$ 
and  $\text{dim-vec } x = n$ 
shows  $(\text{one-element-vec } n \ e @_v (0_v \ m)) \cdot (x @_v u) = (\sum_{i \in \{0 .. < \text{dim-vec } x\}} e * x \$ i)$ 
⟨proof⟩

lemma  $\text{one-element-vec-dotP}:$ 
assumes  $\text{dim-vec } x = n$ 
shows  $(\text{one-element-vec } n \ e) \cdot x = (\sum_{i \in \{0 .. < \text{dim-vec } x\}} e * x \$ i)$ 
⟨proof⟩

lemma  $\text{singleton-dotP [simp]}: \text{dim-vec } x = 1 \implies [v]_v \cdot x = v * x \$ 0$ 
⟨proof⟩

lemma  $\text{singletons-dotP [simp]}: [v]_v \cdot [w]_v = v * w$ 
⟨proof⟩

lemma  $\text{singleton-appends-dotP [simp]}: \text{dim-vec } x = \text{dim-vec } y \implies (x @_v [v]_v) \cdot (y @_v [w]_v) = x \cdot y + v * w$ 
⟨proof⟩

end
theory Matrix-LinPoly
imports
  Jordan-Normal-Form.Matrix-Impl
  Farkas.Simplex-for-Reals
  Farkas.Matrix-Farkas
begin

Add this to linear polynomials in Simplex

lemma  $\text{eval-poly-with-sum}: (v \{ X \}) = (\sum_{x \in \text{vars } v} \text{coeff } v \ x * X \ x)$ 
⟨proof⟩

lemma  $\text{eval-poly-with-sum-superset}:$ 
assumes  $\text{finite } S$ 
assumes  $S \supseteq \text{vars } v$ 
shows  $(v \{ X \}) = (\sum_{x \in S} \text{coeff } v \ x * X \ x)$ 
⟨proof⟩

```

Get rid of these synonyms

## 4 Translations of Jordan Normal Forms Matrix Library to Simplex polynomials

### 4.1 Vectors

**definition** *list-to-lpoly where*

*list-to-lpoly cs = sum-list (map2 (λ i c. lp-monom c i) [0..<length cs] cs)*

**lemma** *empty-list-0poly:*

**shows** *list-to-lpoly [] = 0*

*{proof}*

**lemma** *sum-list-map-up-to-coeff-limit:*

**assumes** *i ≥ length L*

**shows** *coeff (list-to-lpoly L) i = 0*

*{proof}*

**lemma** *rl-lpoly-coeff-nth-non-empty:*

**assumes** *i < length cs*

**assumes** *cs ≠ []*

**shows** *coeff (list-to-lpoly cs) i = cs!i*

*{proof}*

**lemma** *list-to-lpoly-coeff-nth:*

**assumes** *i < length cs*

**shows** *coeff (list-to-lpoly cs) i = cs ! i*

*{proof}*

**lemma** *rat-list-outside-zero:*

**assumes** *length cs ≤ i*

**shows** *coeff (list-to-lpoly cs) i = 0*

*{proof}*

Transform linear polynomials to rational vectors

**fun** *dim-poly where*

*dim-poly p = (if (vars p) = {} then 0 else Max (vars p)+1)*

**definition** *max-dim-poly-list where*

*max-dim-poly-list lst = Max {Max (vars p) | p. p ∈ set lst}*

**fun** *lpoly-to-vec where*

*lpoly-to-vec p = vec (dim-poly p) (coeff p)*

**lemma** *all-greater-dim-poly-zero[simp]:*

**assumes**  $x \geq \text{dim-poly } p$

**shows**  $\text{coeff } p \ x = 0$

$\langle \text{proof} \rangle$

**lemma**  $\text{lpoly-to-vec-0-iff-zero-poly}$  [iff]:

**shows**  $(\text{lpoly-to-vec } p) = 0_v \ 0 \longleftrightarrow p = 0$

$\langle \text{proof} \rangle$

**lemma**  $\text{dim-poly-dim-vec-equiv}:$

$\text{dim-vec } (\text{lpoly-to-vec } p) = \text{dim-poly } p$

$\langle \text{proof} \rangle$

**lemma**  $\text{dim-poly-greater-ex-coeff}:$   $\text{dim-poly } x > d \implies \exists i \geq d. \text{coeff } x \ i \neq 0$

$\langle \text{proof} \rangle$

**lemma**  $\text{dimpoly-all-zero-limit}:$

**assumes**  $\bigwedge i. i \geq d \implies \text{coeff } x \ i = 0$

**shows**  $\text{dim-poly } x \leq d$

$\langle \text{proof} \rangle$

**lemma**  $\text{construct-poly-from-lower-dim-poly}:$

**assumes**  $\text{dim-poly } x = d+1$

**obtains**  $p \ c$  **where**  $\text{dim-poly } p \leq d \ x = p + \text{lp-monom } c \ d$

$\langle \text{proof} \rangle$

**lemma**  $\text{vars-subset-0-dim-poly}:$

$\text{vars } z \subseteq \{0..<\text{dim-poly } z\}$

$\langle \text{proof} \rangle$

**lemma**  $\text{in-dim-and-not-var-zero}:$   $x \in \{0..<\text{dim-poly } z\} - \text{vars } z \implies \text{coeff } z \ x = 0$

$\langle \text{proof} \rangle$

**lemma**  $\text{valuate-with-dim-poly}:$   $z \ \{\! X \!\} = (\sum_{i \in \{0..<\text{dim-poly } z\}} \text{coeff } z \ i * X \ i)$

$\langle \text{proof} \rangle$

**lemma**  $\text{lin-poly-to-vec-coeff-access}:$

**assumes**  $x < \text{dim-poly } y$

**shows**  $(\text{lpoly-to-vec } y) \$ x = \text{coeff } y \ x$

$\langle \text{proof} \rangle$

**lemma**  $\text{addition-over-lin-poly-to-vec}:$

**fixes**  $x \ y$

**assumes**  $a < \text{dim-poly } x$

**assumes**  $\text{dim-poly } x = \text{dim-poly } y$

**shows**  $(\text{lpoly-to-vec } x + \text{lpoly-to-vec } y) \$ a = \text{coeff } (x + y) \ a$

$\langle \text{proof} \rangle$

**lemma**  $\text{list-to-lpoly-dim-less}:$   $\text{length } cs \geq \text{dim-poly } (\text{list-to-lpoly } cs)$

$\langle \text{proof} \rangle$

Transform rational vectors to linear polynomials

```

fun vec-to-lpoly where
  vec-to-lpoly rv = list-to-lpoly (list-of-vec rv)

lemma vec-to-lin-poly-coeff-access:
  assumes x < dim-vec y
  shows y $ x = coeff (vec-to-lpoly y) x
  ⟨proof⟩

lemma addition-over-vec-to-lin-poly:
  fixes x y
  assumes a < dim-vec x
  assumes dim-vec x = dim-vec y
  shows (x + y) $ a = coeff (vec-to-lpoly x + vec-to-lpoly y) a
  ⟨proof⟩

lemma outside-list-coeff0:
  assumes i ≥ dim-vec xs
  shows coeff (vec-to-lpoly xs) i = 0
  ⟨proof⟩

lemma vec-to-poly-dim-less:
  dim-poly (vec-to-lpoly x) ≤ dim-vec x
  ⟨proof⟩

lemma vec-to-lpoly-from-lpoly-coeff-dual1:
  coeff (vec-to-lpoly (lpoly-to-vec p)) i = coeff p i
  ⟨proof⟩

lemma vec-to-lpoly-from-lpoly-coeff-dual2:
  assumes i < dim-vec (lpoly-to-vec (vec-to-lpoly v))
  shows (lpoly-to-vec (vec-to-lpoly v)) $ i = v $ i
  ⟨proof⟩

lemma vars-subset-dim-vec-to-lpoly-dim: vars (vec-to-lpoly v) ⊆ {0..<dim-vec v}
  ⟨proof⟩

lemma sum-dim-vec-equals-sum-dim-poly:
  shows (∑ a = 0..<dim-vec A. coeff (vec-to-lpoly A) a * X a) =
    (∑ a = 0..<dim-poly (vec-to-lpoly A). coeff (vec-to-lpoly A) a * X a)
  ⟨proof⟩

lemma vec-to-lpoly-vNil [simp]: vec-to-lpoly vNil = 0
  ⟨proof⟩

lemma zero-vector-is-zero-poly: coeff (vec-to-lpoly (0_v n)) i = 0
  ⟨proof⟩

lemma coeff nonzero dim-vec non-zero:
```

```

assumes coeff (vec-to-lpoly v) i ≠ 0
shows v $ i ≠ 0 i < dim-vec v
⟨proof⟩

lemma lpoly-of-v-equals-v-append0:
vec-to-lpoly v = vec-to-lpoly (v @v 0v a) (is ?lhs = ?rhs)
⟨proof⟩

lemma vec-to-lpoly-eval-dot-prod:
(vec-to-lpoly v) {x} = v · (vec (dim-vec v) x)
⟨proof⟩

lemma dim-poly-of-append-vec:
dim-poly (vec-to-lpoly (a @v b)) ≤ dim-vec a + dim-vec b
⟨proof⟩

lemma vec-coeff-append1: i ∈ {0..<dim-vec a} ⇒ coeff (vec-to-lpoly (a @v b)) i
= a$i
⟨proof⟩

lemma vec-coeff-append2:
i ∈ {dim-vec a..<dim-vec (a @v b)} ⇒ coeff (vec-to-lpoly (a @v b)) i = b$(i - dim-vec
a)
⟨proof⟩

```

Maybe Code Equation

```

lemma vec-to-lpoly-poly-of-vec-eq: vec-to-lpoly v = poly-of-vec v
⟨proof⟩

```

```

lemma vars-vec-append-subset: vars (vec-to-lpoly (0v n @v v)) ⊆ {n..<n+dim-vec
v}
⟨proof⟩

```

## 5 Matrices

```

fun matrix-to-lpolies where
matrix-to-lpolies A = map vec-to-lpoly (rows A)

lemma matrix-to-lpolies-vec-of-row:
i < dim-row A ⇒ matrix-to-lpolies A ! i = vec-to-lpoly (row A i)
⟨proof⟩

lemma outside-of-col-range-is-0:
assumes i < dim-row A and j ≥ dim-col A
shows coeff ((matrix-to-lpolies A)!i) j = 0
⟨proof⟩

lemma polys-greater-col-zero:
assumes x ∈ set (matrix-to-lpolies A)

```

```

assumes  $j \geq \dim\text{-}col A$ 
shows  $\text{coeff } x j = 0$ 
 $\langle proof \rangle$ 

lemma matrix-to-lp-vec-to-lpoly-row [simp]:
assumes  $i < \dim\text{-}row A$ 
shows  $(\text{matrix-to-lpolies } A)!i = \text{vec-to-lpoly } (\text{row } A i)$ 
 $\langle proof \rangle$ 

lemma matrix-to-lpolies-coeff-access:
assumes  $i < \dim\text{-}row A$  and  $j < \dim\text{-}col A$ 
shows  $\text{coeff } (\text{matrix-to-lpolies } A ! i) j = A \$\$ (i,j)$ 
 $\langle proof \rangle$ 

```

From linear polynomial list to matrix

```

definition lin-polies-to-mat where
lin-polies-to-mat lst = mat (length lst) (max-dim-poly-list lst)  $(\lambda(x,y).\text{coeff } (\text{lst}!x))$ 
 $y$ 

```

```

lemma lin-polies-to-rat-mat-coeff-index:
assumes  $i < \text{length } L$  and  $j < (\text{max-dim-poly-list } L)$ 
shows  $\text{coeff } (L ! i) j = (\text{lin-polies-to-mat } L) \$\$ (i,j)$ 
 $\langle proof \rangle$ 

```

```

lemma vec-to-lpoly-evaluate-equiv-dot-prod:
assumes  $\dim\text{-}vec y = \dim\text{-}vec x$ 
shows  $(\text{vec-to-lpoly } y) \{ (\$)x \} = y \cdot x$ 
 $\langle proof \rangle$ 

```

```

lemma matrix-to-lpolies-evaluate-scalarP:
assumes  $i < \dim\text{-}row A$ 
assumes  $\dim\text{-}col A = \dim\text{-}vec x$ 
shows  $(\text{matrix-to-lpolies } A!i) \{ (\$)x \} = (\text{row } A i) \cdot x$ 
 $\langle proof \rangle$ 

```

```

lemma matrix-to-lpolies-lambda-evaluate-scalarP:
assumes  $i < \dim\text{-}row A$ 
assumes  $\dim\text{-}col A = \dim\text{-}vec x$ 
shows  $(\text{matrix-to-lpolies } A!i) \{ (\lambda i. (\text{if } i < \dim\text{-}vec x \text{ then } x\$i \text{ else } 0)) \} = (\text{row } A i) \cdot x$ 
 $\langle proof \rangle$ 

```

```

end
theory LP-Preliminaries
imports
More-Jordan-Normal-Forms

```

```

Matrix-LinPoly
Jordan-Normal-Form.Matrix-Impl
Farkas.Simplex-for-Reals
HOL-Library.Mapping
begin

fun vars-from-index-geq-vec where
  vars-from-index-geq-vec index b = [GEQ (lp-monom 1 (i+index)) (b$i). i ← [0..<dim-vec b]]

lemma constraints-set-vars-geq-vec-def:
  set (vars-from-index-geq-vec start b) =
  {GEQ (lp-monom 1 (i+start)) (b$i) | i. i ∈ {0..<dim-vec b}}

  ⟨proof⟩

lemma vars-from-index-geq-sat:
  assumes ⟨x⟩ ⊨cs set (vars-from-index-geq-vec start b)
  assumes i < dim-vec b
  shows ⟨x⟩ (i+start) ≥ b$i
  ⟨proof⟩

fun mat-x-leq-vec where
  mat-x-leq-vec A b = [LEQ (matrix-to-lpolies A!i) (b$i) . i <- [0..<dim-vec b]]

lemma mat-x-leq-vec-sol:
  assumes ⟨x⟩ ⊨cs set (mat-x-leq-vec A b)
  assumes i < dim-vec b
  shows ((matrix-to-lpolies A)!i) {⟨x⟩} ≤ b$i
  ⟨proof⟩

fun x-mat-eq-vec where
  x-mat-eq-vec b A = [EQ (matrix-to-lpolies A!i) (b$i) . i <- [0..<dim-vec b]]

lemma x-mat-eq-vec-sol:
  assumes x ⊨cs set (x-mat-eq-vec b A)
  assumes i < dim-vec b
  shows ((matrix-to-lpolies A)!i) {⟨x⟩} = b$i
  ⟨proof⟩

```

## 6 Get different matrices into same space, without interference

```

fun two-block-non-interfering where
  two-block-non-interfering A B = (let z1 = 0m (dim-row A) (dim-col B);
                                    z2 = 0m (dim-row B) (dim-col A) in
                                    four-block-mat A z1 z2 B)

lemma split-two-block-non-interfering:
  assumes split-block (two-block-non-interfering A B) (dim-row A) (dim-col A) =
  (Q1, Q2, Q3, Q4)
  shows Q1 = A Q4 = B
  ⟨proof⟩

lemma two-block-non-interfering-dims:
  dim-row (two-block-non-interfering A B) = dim-row A + dim-row B
  dim-col (two-block-non-interfering A B) = dim-col A + dim-col B
  ⟨proof⟩

lemma two-block-non-interfering-zeros-are-0:
  assumes i < dim-row A
  and j ≥ dim-col A
  and j < dim-col (two-block-non-interfering A B)
  shows (two-block-non-interfering A B)${}_{i,j} = 0$ (two-block-non-interfering A
B)${}_{i,j} = 0$
  ⟨proof⟩

lemma two-block-non-interfering-row-comp1:
  assumes i < dim-row A
  shows row (two-block-non-interfering A B) i = row A i @v (0v (dim-col B))
  ⟨proof⟩

lemma two-block-non-interfering-row-comp2:
  assumes i < dim-row (two-block-non-interfering A B)
  and i ≥ dim-row A
  shows row (two-block-non-interfering A B) i = (0v (dim-col A)) @v row B (i -
dim-row A)
  ⟨proof⟩

lemma first-vec-two-block-non-inter-is-first-vec:
  assumes dim-col A + dim-col B = dim-vec v
  assumes dim-row A = n
  shows vec-first (two-block-non-interfering A B *v v) n = A *v (vec-first v (dim-col
A))
  ⟨proof⟩

lemma last-vec-two-block-non-inter-is-last-vec:
  assumes dim-col A + dim-col B = dim-vec v
  assumes dim-row B = n

```

```

shows vec-last ((two-block-non-interfering A B) *_v v) n = B *_v (vec-last v
(dim-col B))
⟨proof⟩

lemma two-block-non-interfering-mult-decomposition:
assumes dim-col A + dim-col B = dim-vec v
shows two-block-non-interfering A B *_v v =
A *_v vec-first v (dim-col A) @_v B *_v vec-last v (dim-col B)
⟨proof⟩

fun mat-leqb-eqc where
mat-leqb-eqc A b c = (let lst = matrix-to-lpolies (two-block-non-interfering A
AT) in
[LEQ (lst!i) (b\$i) . i <- [0..<dim-vec b]] @
[EQ (lst!i) ((b @_v c) \$i) . i <- [dim-vec b ..< dim-vec (b @_v c)]])

lemma mat-leqb-eqc-for-LEQ:
assumes i < dim-vec b
assumes i < dim-row A
shows (mat-leqb-eqc A b c)!i = LEQ ((matrix-to-lpolies A)!i) (b\$i)
⟨proof⟩

lemma mat-leqb-eqc-for-EQ:
assumes dim-vec b ≤ i and i < dim-vec (b @_v c)
assumes dim-row A = dim-vec b and dim-col A ≥ dim-vec c
shows (mat-leqb-eqc A b c)!i =
EQ (vec-to-lpoly (0_v (dim-col A) @_v row AT (i - dim-vec b))) (c \$ (i - dim-vec b))
⟨proof⟩

lemma mat-leqb-eqc-satisfies1:
assumes x ⊨cs set (mat-leqb-eqc A b c)
assumes i < dim-vec b
and i < dim-row A
shows (matrix-to-lpolies A)!i {x} ≤ b\$i
⟨proof⟩

lemma mat-leqb-eqc-satisfies2:
assumes x ⊨cs set (mat-leqb-eqc A b c)
assumes dim-vec b ≤ i and i < dim-vec (b @_v c)
and dim-row A = dim-vec b and dim-vec c ≤ dim-col A
shows (matrix-to-lpolies (two-block-non-interfering A AT) ! i) {x} = (b @_v c) \$  
i
⟨proof⟩

lemma mat-leqb-eqc-simplex-satisfies2:
assumes simplex (mat-leqb-eqc A b c) = Sat x
assumes dim-vec b ≤ i and i < dim-vec (b @_v c)

```

```

and dim-row A = dim-vec b and dim-vec c ≤ dim-col A
shows (matrix-to-lpolies (two-block-non-interfering A AT) ! i) {⟨x⟩} = (b @v c)
\$ i
⟨proof⟩

fun index-geq-n where
  index-geq-n i n = GEQ (lp-monom 1 i) n

lemma index-geq-n-simplex:
  assumes ⟨x⟩ ⊨c (index-geq-n i n)
  shows ⟨x⟩ i ≥ n
  ⟨proof⟩

fun from-index-geq0-vector where
  from-index-geq0-vector i v = [GEQ (lp-monom 1 (i+j)) (v$j) . j <-[0..<dim-vec v]]

lemma from-index-geq-vector-simplex:
  assumes x ⊨cs set (from-index-geq0-vector i v)
  j < dim-vec v
  shows x (i + j) ≥ v$j
  ⟨proof⟩

lemma from-index-geq0-vector-simplex2:
  assumes ⟨x⟩ ⊨cs set (from-index-geq0-vector i v)
  assumes i ≤ j and j < (dim-vec v) + i
  shows ⟨x⟩ j ≥ v$(j - i)
  ⟨proof⟩

definition x-times-c-geq-y-times-b where
  x-times-c-geq-y-times-b c b = GEQ (
    vec-to-lpoly (c @v 0v (dim-vec b)) - vec-to-lpoly (0v (dim-vec c) @v b)) 0

lemma x-times-c-geq-y-times-b-correct:
  assumes simplex [x-times-c-geq-y-times-b c b] = Sat x
  shows ((vec-to-lpoly (c @v 0v (dim-vec b))) {⟨x⟩}) ≥
    ((vec-to-lpoly (0v (dim-vec c) @v b)) {⟨x⟩})
  ⟨proof⟩

definition split-i-j-x where
  split-i-j-x i j x = (vec i ⟨x⟩, vec (j - i) (λy. ⟨x⟩ (y+i)))

```

```

abbreviation split-n-m-x where
  split-n-m-x n m x ≡ split-i-j-x n (n+m) x

lemma split-vec-dims:
  assumes split-i-j-x i j x = (a ,b)
  shows dim-vec a = i dim-vec b = (j - i)
  ⟨proof⟩

lemma split-n-m-x-abbrev-dims:
  assumes split-n-m-x n m x = (a, b)
  shows dim-vec a = n dim-vec b = m
  ⟨proof⟩

lemma split-access-fst-1:
  assumes k < i
  assumes split-i-j-x i j x = (a, b)
  shows a $ k = ⟨x⟩ k
  ⟨proof⟩

lemma split-access-snd-1:
  assumes i ≤ k and k < j
  assumes split-i-j-x i j x = (a, b)
  shows b $ (k - i) = ⟨x⟩ k
  ⟨proof⟩

lemma split-access-fst-2:
  assumes (x, y) = split-i-j-x i j Z
  assumes k < dim-vec x
  shows x$k = ⟨Z⟩ k
  ⟨proof⟩

lemma split-access-snd-2:
  assumes (x, y) = split-i-j-x i j Z
  assumes k < dim-vec y
  shows y$k = ⟨Z⟩ (k+dim-vec x)
  ⟨proof⟩

lemma from-index-geq0-vector-split-snd:
  assumes ⟨X⟩ ⊨cs set (from-index-geq0-vector d v)
  assumes (x, y) = split-n-m-x d m X
  shows ∏ i. i < dim-vec v ⇒ i < m ⇒ y$i ≥ v$i
  ⟨proof⟩

lemma split-coeff-vec-index-sum:
  assumes (x,y) = split-i-j-x (dim-vec (lpoly-to-vec v)) l X
  shows (∑ i = 0..<dim-vec x. Abstract-Linear-Poly.coeff v i * ⟨X⟩ i) =
    (∑ i = 0..<dim-vec x. lpoly-to-vec v $ i * x $ i)

```

$\langle proof \rangle$

**lemma** *scalar-prod-valuation-after-split-equiv1*:  
**assumes**  $(x,y) = split\text{-}i\text{-}j\text{-}x (dim\text{-}vec (lpoly\text{-}to\text{-}vec v)) l X$   
**shows**  $(lpoly\text{-}to\text{-}vec v) \cdot x = (v \{\langle X \rangle\})$   
 $\langle proof \rangle$

**definition** *mat-times-vec-leq* ( $\langle [-*_v -] \leq - \rangle [1000, 1000, 100]$ )

**where**

$$[A *_v x] \leq b \longleftrightarrow (\forall i < dim\text{-}vec b. (A *_v x)\$i \leq b\$i) \wedge \\ (dim\text{-}row A = dim\text{-}vec b) \wedge \\ (dim\text{-}col A = dim\text{-}vec x)$$

**definition** *vec-times-mat-eq* ( $\langle [-_v * -] = - \rangle [1000, 1000, 100]$ )

**where**

$$[y *_v A] = c \longleftrightarrow (\forall i < dim\text{-}vec c. (A^T *_v y)\$i = c\$i) \wedge \\ (dim\text{-}col A^T = dim\text{-}vec y) \wedge \\ (dim\text{-}row A^T = dim\text{-}vec c)$$

**definition** *vec-times-mat-leq* ( $\langle [-_v * -] \leq - \rangle [1000, 1000, 100]$ )

**where**

$$[y *_v A] \leq c \longleftrightarrow (\forall i < dim\text{-}vec c. (A^T *_v y)\$i \leq c\$i) \wedge \\ (dim\text{-}col A^T = dim\text{-}vec y) \wedge \\ (dim\text{-}row A^T = dim\text{-}vec c)$$

**lemma** *mat-times-vec-leqI[intro]*:

**assumes**  $dim\text{-}row A = dim\text{-}vec b$   
**assumes**  $dim\text{-}col A = dim\text{-}vec x$   
**assumes**  $\bigwedge i. i < dim\text{-}vec b \implies (A *_v x)\$i \leq b\$i$   
**shows**  $[A *_v x] \leq b$   
 $\langle proof \rangle$

**lemma** *mat-times-vec-leqD[dest]*:

**assumes**  $[A *_v x] \leq b$   
**shows**  $dim\text{-}row A = dim\text{-}vec b \wedge dim\text{-}col A = dim\text{-}vec x \wedge \bigwedge i. i < dim\text{-}vec b \implies (A *_v x)\$i \leq b\$i$   
 $\langle proof \rangle$

**lemma** *vec-times-mat-eqD[dest]*:

**assumes**  $[y *_v A] = c$   
**shows**  $(\forall i < dim\text{-}vec c. (A^T *_v y)\$i = c\$i) \wedge (dim\text{-}col A^T = dim\text{-}vec y) \wedge (dim\text{-}row A^T = dim\text{-}vec c)$   
 $\langle proof \rangle$

**lemma** *vec-times-mat-leqD[dest]*:

**assumes**  $[y *_v A] \leq c$   
**shows**  $(\forall i < dim\text{-}vec c. (A^T *_v y)\$i \leq c\$i) \wedge (dim\text{-}col A^T = dim\text{-}vec y) \wedge (dim\text{-}row A^T = dim\text{-}vec c)$

$\langle proof \rangle$

**lemma** *mat-times-vec-eqI[intro]*:  
  **assumes** *dim-col A<sup>T</sup> = dim-vec x*  
  **assumes** *dim-row A<sup>T</sup> = dim-vec c*  
  **assumes**  $\bigwedge i. i < \text{dim-vec } c \implies (A^T *_v x)_i = c_i$   
  **shows**  $[x * A] = c$   
 $\langle proof \rangle$

**lemma** *mat-leqb-eqc-split-correct1*:  
  **assumes** *dim-vec b = dim-row A*  
  **assumes**  $\langle X \rangle \models_{cs} \text{set}(\text{mat-leqb-eqc } A \ b \ c)$   
  **assumes**  $(x, y) = \text{split-i-j-x}(\text{dim-col } A) \ l \ X$   
  **shows**  $[A *_v x] \leq b$   
 $\langle proof \rangle$

**lemma** *mat-leqb-eqc-split-simplex-correct1*:  
  **assumes** *dim-vec b = dim-row A*  
  **assumes** *simplex (mat-leqb-eqc A b c) = Sat X*  
  **assumes**  $(x, y) = \text{split-i-j-x}(\text{dim-col } A) \ l \ X$   
  **shows**  $[A *_v x] \leq b$   
 $\langle proof \rangle$

**lemma** *sat-mono*:  
  **assumes** *set A ⊆ set B*  
  **shows**  $\langle X \rangle \models_{cs} \text{set } B \implies \langle X \rangle \models_{cs} \text{set } A$   
 $\langle proof \rangle$

**lemma** *mat-leqb-eqc-split-subset-correct1*:  
  **assumes** *dim-vec b = dim-row A*  
  **assumes** *set (mat-leqb-eqc A b c) ⊆ set S*  
  **assumes** *simplex S = Sat X*  
  **assumes**  $(x, y) = \text{split-i-j-x}(\text{dim-col } A) \ l \ X$   
  **shows**  $[A *_v x] \leq b$   
 $\langle proof \rangle$

**lemma** *mat-leqb-eqc-split-correct2*:  
  **assumes** *dim-vec c = dim-row A<sup>T</sup>*  
  **assumes** *dim-vec b = dim-col A<sup>T</sup>*  
  **assumes**  $\langle X \rangle \models_{cs} \text{set}(\text{mat-leqb-eqc } A \ b \ c)$   
  **assumes**  $(x, y) = \text{split-n-m-x}(\text{dim-row } A^T) \ (\text{dim-col } A^T) \ X$   
  **shows**  $[y * A] = c$   
 $\langle proof \rangle$

**lemma** *mat-leqb-eqc-split-simplex-correct2*:  
  **assumes** *dim-vec c = dim-row A<sup>T</sup>*  
  **assumes** *dim-vec b = dim-col A<sup>T</sup>*  
  **assumes** *simplex (mat-leqb-eqc A b c) = Sat X*  
  **assumes**  $(x, y) = \text{split-n-m-x}(\text{dim-row } A^T) \ (\text{dim-col } A^T) \ X$

**shows**  $[y \circ * A] = c$   
 $\langle proof \rangle$

**lemma** mat-leqb-eqc-correct:  
**assumes** dim-vec  $c =$  dim-row  $A^T$   
**and** dim-vec  $b =$  dim-col  $A^T$   
**assumes** simplex (mat-leqb-eqc  $A b c$ ) = Sat  $X$   
**assumes**  $(x, y) = split-n-m-x (dim-row A^T) (dim-col A^T) X$   
**shows**  $[y \circ * A] = c$   $[A \circ_v x] \leq b$   
 $\langle proof \rangle$

**lemma** eval-lpoly-eq-dot-prod-split1:  
**assumes**  $(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X$   
**shows** (vec-to-lpoly  $c$ )  $\{\langle X \rangle\} = c \cdot x$   
 $\langle proof \rangle$

**lemma** eval-lpoly-eq-dot-prod-split2:  
**assumes**  $(x, y) = split-n-m-x (dim-vec b) (dim-vec c) X$   
**shows** (vec-to-lpoly  $(0_v (dim-vec b) @_v c)$ )  $\{\langle X \rangle\} = c \cdot y$   
 $\langle proof \rangle$

**lemma** x-times-c-geq-y-times-b-split-dotP:  
**assumes**  $\langle X \rangle \models_c x\text{-times-}c\text{-geq-}y\text{-times-}b c b$   
**assumes**  $(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X$   
**shows**  $c \cdot x \geq b \cdot y$   
 $\langle proof \rangle$

**lemma** mult-right-leq:  
**fixes**  $A :: ('a :: \{comm-semiring-1, ordered-semiring\}) mat$   
**assumes** dim-vec  $y =$  dim-vec  $b$   
**and**  $\forall i < dim-vec y. y\$i \geq 0$   
**and**  $[A \circ_v x] \leq b$   
**shows**  $(A \circ_v x) \cdot y \leq b \cdot y$   
 $\langle proof \rangle$

**lemma** mult-right-eq:  
**assumes** dim-vec  $x =$  dim-vec  $c$   
**and**  $[y \circ * A] = c$   
**shows**  $(A^T \circ_v y) \cdot x = c \cdot x$   
 $\langle proof \rangle$

**lemma** soundness-mat-x-leq:  
**assumes** dim-row  $A =$  dim-vec  $b$   
**assumes** simplex (mat-x-leq-vec  $A b$ ) = Sat  $X$   
**shows**  $\exists x. [A \circ_v x] \leq b$   
 $\langle proof \rangle$

**lemma** completeness-mat-x-leq:  
**assumes**  $\exists x. [A \circ_v x] \leq b$

**shows**  $\exists X. \text{simplex}(\text{mat-x-leq-vec } A \ b) = \text{Sat } X$   
 $\langle \text{proof} \rangle$

**lemma** *soundness-mat-x-eq-vec*:  
**assumes**  $\text{dim-row } A^T = \text{dim-vec } c$   
**assumes**  $\text{simplex}(\text{x-mat-eq-vec } c \ A^T) = \text{Sat } X$   
**shows**  $\exists x. [x \ v* A] = c$   
 $\langle \text{proof} \rangle$

**lemma** *completeness-mat-x-eq-vec*:  
**assumes**  $\exists x. [x \ v* A] = c$   
**shows**  $\exists X. \text{simplex}(\text{x-mat-eq-vec } c \ A^T) = \text{Sat } X$   
 $\langle \text{proof} \rangle$

**lemma** *soundness-mat-leqb-eqc1*:  
**assumes**  $\text{dim-row } A = \text{dim-vec } b$   
**assumes**  $\text{simplex}(\text{mat-leqb-eqc } A \ b \ c) = \text{Sat } X$   
**shows**  $\exists x. [A *_v x] \leq b$   
 $\langle \text{proof} \rangle$

**lemma** *soundness-mat-leqb-eqc2*:  
**assumes**  $\text{dim-row } A^T = \text{dim-vec } c$   
**assumes**  $\text{dim-col } A^T = \text{dim-vec } b$   
**assumes**  $\text{simplex}(\text{mat-leqb-eqc } A \ b \ c) = \text{Sat } X$   
**shows**  $\exists y. [y \ v* A] = c$   
 $\langle \text{proof} \rangle$

**lemma** *completeness-mat-leqb-eqc*:  
**assumes**  $\exists x. [A *_v x] \leq b$   
**and**  $\exists y. [y \ v* A] = c$   
**shows**  $\exists X. \text{simplex}(\text{mat-leqb-eqc } A \ b \ c) = \text{Sat } X$   
 $\langle \text{proof} \rangle$

**lemma** *sound-and-compltete-mat-leqb-eqc [iff]*:  
**assumes**  $\text{dim-row } A^T = \text{dim-vec } c$   
**assumes**  $\text{dim-col } A^T = \text{dim-vec } b$   
**shows**  $(\exists x. [A *_v x] \leq b) \wedge (\exists y. [y \ v* A] = c) \longleftrightarrow (\exists X. \text{simplex}(\text{mat-leqb-eqc } A \ b \ c) = \text{Sat } X)$   
 $\langle \text{proof} \rangle$

## 7 Translate Inequalities to Matrix Form

```
fun nonstrict-constr where
  nonstrict-constr (LEQ p r) = True |
  nonstrict-constr (GEQ p r) = True |
  nonstrict-constr (EQ p r) = True |
  nonstrict-constr - = False
```

**abbreviation** nonstrict-consts cs  $\equiv (\forall a \in \text{set } cs. \text{nonstrict-constr } a)$

```

fun transf-constraint where
  transf-constraint (LEQ p r) = [LEQ p r] |
  transf-constraint (GEQ p r) = [LEQ (-p) (-r)] |
  transf-constraint (EQ p r) = [LEQ p r, LEQ (-p) (-r)] |
  transf-constraint - = []

fun transf-constraints where
  transf-constraints [] = [] |
  transf-constraints (x#xs) = transf-constraint x @ (transf-constraints xs)

lemma trans-constraint-creates-LEQ-only:
  assumes transf-constraint x ≠ []
  shows (∀x ∈ set (transf-constraint x). ∃a b. x = LEQ a b)
  ⟨proof⟩

lemma trans-constraints-creates-LEQ-only:
  assumes transf-constraints xs ≠ []
  assumes x ∈ set (transf-constraints xs)
  shows ∃p r. LEQ p r = x
  ⟨proof⟩

lemma non-strict-constr-no-LT:
  assumes nonstrict-constrs cs
  shows ∀x ∈ set cs. ¬(∃a b. LT a b = x)
  ⟨proof⟩

lemma non-strict-constr-no-GT:
  assumes nonstrict-constrs cs
  shows ∀x ∈ set cs. ¬(∃a b. GT a b = x)
  ⟨proof⟩

lemma non-strict-consts-cond:
  assumes ∀x. x ∈ set cs ⇒ ¬(∃a b. LT a b = x)
  assumes ∀x. x ∈ set cs ⇒ ¬(∃a b. GT a b = x)
  shows nonstrict-constrs cs
  ⟨proof⟩

lemma sat-constr-sat-transf-constrs:
  assumes v ⊨c cs
  shows v ⊨cs set (transf-constraint cs)
  ⟨proof⟩

lemma sat-constrs-sat-transf-constrs:
  assumes v ⊨cs set cs
  shows v ⊨cs set (transf-constraints cs)

```

```

⟨proof⟩

lemma sat-transf-constrs-sat-constr:
  assumes nonstrict-constr cs
  assumes v ⊨cs set (transf-constraint cs)
  shows v ⊨c cs
  ⟨proof⟩

lemma sat-transf-constrs-sat-constrs:
  assumes nonstrict-constrs cs
  assumes v ⊨cs set (transf-constraints cs)
  shows v ⊨cs set cs
  ⟨proof⟩

end
theory Linear-Programming
imports
  HOL-Library.Code-Target-Int
  LP-Preliminaries
  Farkas.Simplex-for-Realss
begin

```

## 8 Abstract LPs

Primal Problem

**definition** sat-primal A b = { x. [A \*<sub>v</sub> x] ≤ b }

Dual Problem

**definition** sat-dual A c = { y. [y \* A] = c ∧ (∀ i < dim-vec y. y \$ i ≥ 0) }

**definition** optimal-set f S = { x ∈ S. (∀ y ∈ S. f x y) }

**abbreviation** max-lp **where**

max-lp A b c ≡ optimal-set (λx y. (y · c) ≤ (x · c)) (sat-primal A b)

**abbreviation** min-lp **where**

min-lp A b c ≡ optimal-set (λx y. (y · c) ≥ (x · c)) (sat-dual A c)

**lemma** optimal-setI[intro]:

**assumes** x ∈ S

**assumes** ⋀y. y ∈ S ⇒ (λx y. (y · c) ≥ (x · c)) x y

**shows** x ∈ optimal-set (λx y. (y · c) ≥ (x · c)) S

⟨proof⟩

**lemma** max-lpI [intro]:

**assumes** [A \*<sub>v</sub> x] ≤ b

**assumes** (⋀y. [A \*<sub>v</sub> y] ≤ b ⇒ (λx y. (y · c) ≥ (x · c)) y x)

**shows**  $x \in \text{max-lp } A \ b \ c$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{min-lpI}$  [*intro*]:  
**assumes**  $[y \ v* A] = c$   
**and**  $(\bigwedge i. i < \text{dim-vec } y \implies y \$ i \geq 0)$   
**assumes**  $(\bigwedge x. x \in \text{sat-dual } A \ c \implies (\lambda x. y. (y \cdot c) \geq (x \cdot c)) y x)$   
**shows**  $y \in \text{min-lp } A \ b \ c$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sat-primalD}$  [*dest*]:  
**assumes**  $x \in \text{sat-primal } A \ b$   
**shows**  $[A *_v x] \leq b$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sat-primalI}$  [*intro*]:  
**assumes**  $[A *_v x] \leq b$   
**shows**  $x \in \text{sat-primal } A \ b$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sat-dualD}$  [*dest*]:  
**assumes**  $y \in \text{sat-dual } A \ c$   
**shows**  $[y \ v* A] = c \ (\forall i < \text{dim-vec } y. y \$ i \geq 0)$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sat-dualI}$  [*intro*]:  
**assumes**  $[y \ v* A] = c \ (\forall i < \text{dim-vec } y. y \$ i \geq 0)$   
**shows**  $y \in \text{sat-dual } A \ c$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sol-dim-in-sat-primal}$ :  $x \in \text{sat-primal } A \ b \implies \text{dim-vec } x = \text{dim-col } A$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sol-dim-in-max-lp}$ :  $x \in \text{max-lp } A \ b \ c \implies \text{dim-vec } x = \text{dim-col } A$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sol-dim-in-sat-dual}$ :  $x \in \text{sat-dual } A \ c \implies \text{dim-vec } x = \text{dim-row } A$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{sol-dim-in-min-lp}$ :  $x \in \text{min-lp } A \ b \ c \implies \text{dim-vec } x = \text{dim-row } A$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{min-lp-in-sat-dual}$ :  $x \in \text{min-lp } A \ b \ c \implies x \in \text{sat-dual } A \ c$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{max-lp-in-sat-primal}$ :  $x \in \text{max-lp } A \ b \ c \implies x \in \text{sat-primal } A \ b$   
 $\langle \text{proof} \rangle$

```

locale abstract-LP =
  fixes A :: ('a::{comm-semiring-1,ordered-semiring,linorder}) mat
  fixes b :: 'a vec
  fixes c :: 'a vec
  fixes m
  fixes n
  assumes b ∈ carrier-vec m
  assumes c ∈ carrier-vec n
  assumes A ∈ carrier-mat m n
begin

lemma dim-b-row-A: dim-vec b = dim-row A
  ⟨proof⟩

lemma dim-b-col-A: dim-vec c = dim-col A
  ⟨proof⟩

lemma weak-duality-aux:
  fixes i j
  assumes i ∈ {c · x | x. x ∈ sat-primal A b}
  and j ∈ {b · y | y. y ∈ sat-dual A c}
  shows i ≤ j
  ⟨proof⟩

theorem weak-duality-theorem:
  assumes x ∈ max-lp A b c
  assumes y ∈ min-lp A b c
  shows x · c ≤ y · b
  ⟨proof⟩

end

fun create-optimal-solutions where
  create-optimal-solutions A b c =
    (case simplex (x-times-c-geq-y-times-b c b #
      mat-leqb-eqc A b c @
      from-index-geq0-vector (dim-vec c) (0_v (dim-vec b)))
     of
       Unsat X ⇒ Unsat X
     | Sat X ⇒ Sat X)

fun optimize-no-cond where optimize-no-cond A b c = (case create-optimal-solutions
  A b c of
    Unsat X ⇒ Unsat X
    | Sat X ⇒ Sat (fst (split-n-m-x (dim-vec c) (dim-vec b) X)))

lemma create-opt-sol-satisfies:
  assumes create-optimal-solutions A b c = Sat X
  shows ⟨X⟩ ⊨cs set ((x-times-c-geq-y-times-b c b #
    mat-leqb-eqc A b c @

```

*from-index-geq0-vector (dim-vec c) (0<sub>v</sub> (dim-vec b)))*

*(proof)*

**lemma** *create-opt-sol-sat-leq-mat*:

**assumes** *dim-vec b = dim-row A*  
**assumes** *create-optimal-solutions A b c = Sat X*  
**and** *(x, y) = split-i-j-x (dim-col A) (dim-vec b) X*  
**shows** *[A \*<sub>v</sub> x] ≤ b*

*(proof)*

**lemma** *create-opt-sol-sat-eq-mat*:

**assumes** *dim-vec c = dim-row A<sup>T</sup>*  
**and** *dim-vec b = dim-col A<sup>T</sup>*  
**assumes** *create-optimal-solutions A b c = Sat X*  
**and** *(x, y) = split-i-j-x (dim-vec c) (dim-vec c + dim-vec b) X*  
**shows** *[y \*<sub>v</sub> A] = c*

*(proof)*

**lemma** *create-opt-sol-satisfies-leq*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes** *(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X*  
**shows** *x · c ≥ y · b*

*(proof)*

**lemma** *create-opt-sol-satisfies-geq0*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes** *(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X*  
**shows** *⋀ i. i < dim-vec y ==> y\\$i ≥ 0*

*(proof)*

**locale** *rat-LP = abstract-LP A b c m n*

**for** *A ::rat mat*  
**and** *b :: rat vec*  
**and** *c :: rat vec*  
**and** *m :: nat*  
**and** *n :: nat*

**begin**

**lemma** *create-opt-sol-in-LP*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes** *(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X*  
**shows** *[A \*<sub>v</sub> x] ≤ b [y \*<sub>v</sub> A] = c x · c ≥ y · b ⋀ i. i < dim-vec y ==> y\\$i ≥ 0*

*(proof)*

**lemma** *create-optim-in-sols*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes** *(x, y) = split-n-m-x (dim-vec c) (dim-vec b) X*  
**shows** *c · x ∈ {c · x | x. [A \*<sub>v</sub> x] ≤ b}*

$b \cdot y \in \{b \cdot y \mid y. [y \_v* A] = c \wedge (\forall i < \text{dim-vec } y. y\$i \geq 0)\}$   
 $\langle \text{proof} \rangle$

**lemma** *cx-leq-bx-in-creating-opt*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes**  $(x, y) = \text{split-n-m-x}(\text{dim-vec } c)(\text{dim-vec } b) X$   
**shows**  $c \cdot x \leq b \cdot y$   
 $\langle \text{proof} \rangle$

**lemma** *min-max-for-sol*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes**  $(x, y) = \text{split-n-m-x}(\text{dim-vec } c)(\text{dim-vec } b) X$   
**shows**  $c \cdot x = b \cdot y$   
 $\langle \text{proof} \rangle$

**lemma** *create-opt-solutions-correct*:

**assumes** *create-optimal-solutions A b c = Sat X*  
**assumes**  $(x, y) = \text{split-n-m-x}(\text{dim-vec } c)(\text{dim-vec } b) X$   
**shows**  $x \in \text{max-lp } A \ b \ c$   
 $\langle \text{proof} \rangle$

**lemma** *optimize-no-cond-correct*:

**assumes** *optimize-no-cond A b c = Sat x*  
**shows**  $x \in \text{max-lp } A \ b \ c$   
 $\langle \text{proof} \rangle$

**lemma** *optimize-no-cond-sol-sat*:

**assumes** *optimize-no-cond A b c = Sat x*  
**shows**  $x \in \text{sat-primal } A \ b$   
 $\langle \text{proof} \rangle$

**end**

**fun** *maximize where*

*maximize A b c = (if dim-vec b = dim-row A  $\wedge$  dim-vec c = dim-col A then  
Some (optimize-no-cond A b c)  
else None)*

**lemma** *optimize-sound*:

**assumes** *maximize A b c = Some (Sat x)*  
**shows**  $x \in \text{max-lp } A \ b \ c$   
 $\langle \text{proof} \rangle$

**lemma** *maximize-option-elim*:

**assumes** *maximize A b c = Some x*  
**shows** *dim-vec b = dim-row A dim-vec c = dim-col A*  
 $\langle \text{proof} \rangle$

```

lemma optimize-sol-dimension:
  assumes maximize A b c = Some (Sat x)
  shows x ∈ carrier-vec (dim-col A)
  ⟨proof⟩

lemma optimize-sat:
  assumes maximize A b c = Some (Sat x)
  shows [A *v x] ≤ b
  ⟨proof⟩

derive (eq) ceq rat
derive (linorder) compare rat
derive (compare) ccompare rat
derive (rbt) set-impl rat

derive (eq) ceq atom QDelta
derive (linorder) compare-order QDelta
derive compare-order atom
derive ccompare atom QDelta
derive (rbt) set-impl atom QDelta

end

```

**lemma** of-rat-val: simplex cs = (Sat v)  $\implies$  of-rat-val ⟨v⟩  $\models_{rcs}$  set cs  
 ⟨proof⟩

**end**

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