

# Gauss-Jordan algorithm and its applications

By Jose Divasón and Jesús Aransay\*

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## Abstract

In this contribution, we present a formalization of the well-known Gauss-Jordan algorithm. It states that any matrix over a field can be transformed by means of elementary row operations to a matrix in reduced row echelon form. The formalization is based on the Rank Nullity Theorem entry of the AFP and on the HOL-Multivariate-Analysis session of Isabelle, where matrices are represented as functions over finite types. We have set up properly the code generator to make this representation executable. In order to improve the performance, a refinement to immutable arrays has been carried out. We have formalized some of the applications of the Gauss-Jordan algorithm. Thanks to this development, the following facts can be computed over matrices whose elements belong to a field:

- Ranks
- Determinants
- Inverses
- Bases and dimensions of the null space, left null space, column space and row space of a matrix
- Solutions of systems of linear equations (considering any case, including systems with one solution, multiple solutions and with no solution)

Code can be exported to both SML and Haskell. In addition, we have introduced some serializations (for instance, from *bit* in Isabelle to booleans in SML and Haskell, and from *rat* in Isabelle to the corresponding one in Haskell), that speed up the performance.

## Contents

|  |          |
|--|----------|
| <b>1 Reduced row echelon form</b>                              | <b>6</b> |
| 1.1 Defining the concept of Reduced Row Echelon Form . . . . . | 6        |

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|          |   |           |
|----------|---|-----------|
| 1.1.1    | Previous definitions and properties . . . . .   | 6         |
| 1.1.2    | Definition of reduced row echelon form up to a column . . . . .                       | 7         |
| 1.1.3    | The definition of reduced row echelon form . . . . .                                  | 9         |
| 1.2      | Properties of the reduced row echelon form of a matrix . . . . .                      | 9         |
| <b>2</b> | <b>Code set</b>   | <b>11</b> |
| <b>3</b> | <b>Code generation for vectors and matrices</b>                                       | <b>12</b> |
| <b>4</b> | <b>Elementary Operations over matrices</b>  | <b>14</b> |
| 4.1      | Some previous results: . . . . .  | 14        |
| 4.2      | Definitions of elementary row and column operations . . . . .                         | 14        |
| 4.3      | Properties about elementary row operations . . . . .                                  | 15        |
| 4.3.1    | Properties about interchanging rows . . . . .   | 15        |
| 4.3.2    | Properties about multiplying a row by a constant . . . . .                            | 15        |
| 4.3.3    | Properties about adding a row multiplied by a constant to another row . . . . .       | 16        |
| 4.4      | Properties about elementary column operations . . . . .                               | 16        |
| 4.4.1    | Properties about interchanging columns . . . . .                                      | 16        |
| 4.4.2    | Properties about multiplying a column by a constant . . . . .                         | 16        |
| 4.4.3    | Properties about adding a column multiplied by a constant to another column . . . . . | 16        |
| 4.5      | Relationships amongst the definitions . . . . .                                       | 17        |
| 4.6      | Code Equations . . . . .  | 17        |
| <b>5</b> | <b>Rank of a matrix</b>   | <b>19</b> |
| 5.1      | Row rank, column rank and rank . . . . .  | 19        |
| 5.2      | Properties . . . . .  | 19        |
| <b>6</b> | <b>Gauss Jordan algorithm over abstract matrices</b>                                  | <b>20</b> |
| 6.1      | The Gauss-Jordan Algorithm . . . . .  | 20        |
| 6.2      | Properties about rref and the greatest nonzero row. . . . .                           | 21        |
| 6.3      | The proof of its correctness . . . . .  | 22        |
| 6.4      | Lemmas for code generation and rank computation . . . . .                             | 38        |
| <b>7</b> | <b>Linear Maps</b>  | <b>38</b> |
| 7.1      | Properties about ranks and linear maps . . . . .                                      | 39        |
| 7.2      | Invertible linear maps . . . . .  | 39        |
| 7.3      | Definition and properties of the set of a vector . . . . .                            | 41        |
| 7.4      | Coordinates of a vector . . . . .   | 43        |
| 7.5      | Matrix of change of basis and coordinate matrix of a linear map . . . . .             | 44        |
| 7.6      | Equivalent Matrices . . . . .   | 47        |
| 7.7      | Similar matrices . . . . .  | 48        |

|   |           |
|---|-----------|
| <b>8 Obtaining explicitly the invertible matrix which transforms a matrix to its reduced row echelon form</b> | <b>49</b> |
| 8.1 Definitions . . . . .   | 49        |
| 8.2 Proofs . . . . .  | 50        |
| 8.2.1 Properties about <i>Gauss-Jordan-in-ij-PA</i> . . . . .   | 50        |
| 8.2.2 Properties about <i>Gauss-Jordan-column-k-PA</i> . . . . .  | 50        |
| 8.2.3 Properties about <i>Gauss-Jordan-upt-k-PA</i> . . . . .   | 51        |
| 8.2.4 Properties about <i>Gauss-Jordan-PA</i> . . . . .   | 51        |
| 8.2.5 Proving that the transformation has been carried out by means of elementary operations . . . . .        | 51        |
| <b>9 Computing determinants of matrices using the Gauss Jordan algorithm</b>                                  | <b>53</b> |
| 9.1 Some previous properties . . . . .  | 54        |
| 9.1.1 Relationships between determinants and elementary row operations . . . . .                              | 54        |
| 9.1.2 Relationships between determinants and elementary column operations . . . . .                           | 54        |
| 9.2 Proving that the determinant can be computed by means of the Gauss Jordan algorithm . . . . .             | 55        |
| 9.2.1 Previous properties . . . . .   | 55        |
| 9.2.2 Definitions . . . . .   | 56        |
| 9.2.3 Proofs . . . . .  | 56        |
| <b>10 Inverse of a matrix using the Gauss Jordan algorithm</b>  | <b>60</b> |
| 10.1 Several properties . . . . .   | 60        |
| 10.2 Computing the inverse of a matrix using the Gauss Jordan algorithm . . . . .                             | 61        |
| <b>11 Bases of the four fundamental subspaces</b>   | <b>62</b> |
| 11.1 Computation of the bases of the fundamental subspaces . . . . .  | 62        |
| 11.2 Relationships amongst the bases . . . . .  | 62        |
| 11.3 Code equations . . . . .   | 63        |
| 11.4 Demonstrations that they are bases . . . . .   | 63        |
| <b>12 Solving systems of equations using the Gauss Jordan algorithm</b>                                       | <b>65</b> |
| 12.1 Definitions . . . . .  | 65        |
| 12.2 Relationship between <i>is-solution-def</i> and <i>solve-system-def</i> . . . . .                        | 65        |
| 12.3 Consistent and inconsistent systems of equations . . . . .   | 65        |
| 12.4 Solution set of a system of equations. Dependent and independent systems. . . . .                        | 68        |
| 12.5 Solving systems of linear equations . . . . .  | 70        |

|  |           |
|--|-----------|
| <b>13 Code Generation for Z2</b>   | <b>72</b> |
| <b>14 Examples of computations over abstract matrices</b>  | <b>73</b> |
| 14.1 Transforming a list of lists to an abstract matrix . . . . .  | 73        |
| 14.2 Examples . . . . .  | 74        |
| 14.2.1 Ranks and dimensions . . . . .  | 74        |
| 14.2.2 Inverse of a matrix . . . . .   | 75        |
| 14.2.3 Determinant of a matrix . . . . .   | 75        |
| 14.2.4 Bases of the fundamental subspaces . . . . .  | 75        |
| 14.2.5 Consistency and inconsistency . . . . .   | 76        |
| 14.2.6 Solving systems of linear equations . . . . .   | 76        |
| <b>15 IArrays Addenda</b>  | <b>77</b> |
| 15.1 Some previous instances . . . . .   | 77        |
| 15.2 Some previous definitions and properties for IArrays . . . . .  | 77        |
| 15.3 Code generation . . . . .   | 77        |
| <b>16 Matrices as nested IArrays</b>   | <b>78</b> |
| 16.1 Isomorphism between matrices implemented by vecs and matrices implemented by iarrays . . . . .                                | 78        |
| 16.1.1 Isomorphism between vec and iarray . . . . .  | 78        |
| 16.1.2 Isomorphism between matrix and nested iarrays . . . . .   | 79        |
| 16.2 Definition of operations over matrices implemented by iarrays   | 80        |
| 16.2.1 Properties of previous definitions . . . . .  | 81        |
| 16.3 Definition of elementary operations . . . . .   | 82        |
| 16.3.1 Code generator . . . . .  | 83        |
| <b>17 Gauss Jordan algorithm over nested IArrays</b>   | <b>84</b> |
| 17.1 Definitions and functions to compute the Gauss-Jordan algorithm over matrices represented as nested iarrays . . . . .         | 85        |
| 17.2 Proving the equivalence between Gauss-Jordan algorithm over nested iarrays and over nested vecs (abstract matrices). . . . .  | 85        |
| 17.3 Implementation over IArrays of the computation of the <i>rank</i> of a matrix . . . . .                                       | 87        |
| 17.3.1 Proving the equivalence between <i>rank</i> and <i>rank-iarray</i> . . . . .  | 88        |
| 17.3.2 Code equations for computing the rank over nested iarrays and the dimensions of the elementary subspaces                    | 88        |
| <b>18 Obtaining explicitly the invertible matrix which transforms a matrix to its reduced row echelon form over nested iarrays</b> | <b>89</b> |
| 18.1 Definitions . . . . .   | 89        |
| 18.2 Proofs . . . . .  | 90        |
| 18.2.1 Properties of <i>Gauss-Jordan-in-ij-iarrays-PA</i> . . . . .  | 90        |
| 18.2.2 Properties about <i>Gauss-Jordan-column-k-iarrays-PA</i> .  | 90        |

|           |  |            |
|-----------|--|------------|
| 18.2.3    | Properties about <i>Gauss-Jordan-upt-k-iarrays-PA</i>  | 91         |
| 18.2.4    | Properties about <i>Gauss-Jordan-iarrays-PA</i>  | 91         |
| <b>19</b> | <b>Bases of the four fundamental subspaces over IArrays</b>  | <b>92</b>  |
| 19.1      | Computation of bases of the fundamental subspaces using<br>IArrays   | 92         |
| 19.2      | Code equations   | 93         |
| <b>20</b> | <b>Solving systems of equations using the Gauss Jordan algo-</b><br><b>rithm over nested IArrays</b>       | <b>94</b>  |
| 20.1      | Previous definitions and properties  | 94         |
| 20.2      | Consistency and inconsistency  | 95         |
| 20.3      | Independence and dependence  | 96         |
| 20.4      | Solve a system of equations over nested IArrays  | 96         |
| <b>21</b> | <b>Computing determinants of matrices using the Gauss Jor-</b><br><b>dan algorithm over nested IArrays</b> | <b>97</b>  |
| 21.1      | Definitions  | 97         |
| 21.2      | Proofs   | 98         |
| 21.3      | Code equations   | 99         |
| <b>22</b> | <b>Inverse of a matrix using the Gauss Jordan algorithm over</b><br><b>nested IArrays</b>                  | <b>100</b> |
| 22.1      | Definitions  | 100        |
| 22.2      | Some lemmas and code generation  | 100        |
| <b>23</b> | <b>Examples of computations over matrices represented as nested</b><br><b>IArrays</b>                      | <b>101</b> |
| 23.1      | Transformations between nested lists nested IArrays  | 101        |
| 23.2      | Examples   | 102        |
| 23.2.1    | Ranks, dimensions and Gauss Jordan algorithm   | 102        |
| 23.2.2    | Inverse of a matrix  | 103        |
| 23.2.3    | Determinant of a matrix  | 103        |
| 23.2.4    | Bases of the fundamental subspaces   | 103        |
| 23.2.5    | Consistency and inconsistency  | 105        |
| 23.2.6    | Solving systems of linear equations  | 105        |
| <b>24</b> | <b>Exporting code to SML and Haskell</b>   | <b>106</b> |
| 24.1      | Exporting code   | 106        |
| 24.2      | The Mathematica bug  | 107        |
| <b>25</b> | <b>Exporting code to SML</b>   | <b>108</b> |
| <b>26</b> | <b>Code Generation for rational numbers in Haskell</b>   | <b>110</b> |
| 26.1      | Serializations   | 110        |

## 1 Reduced row echelon form

```

theory Rref
imports
  Rank-Nullity-Theorem.Mod-Type
  Rank-Nullity-Theorem.Miscellaneous
begin

1.1 Defining the concept of Reduced Row Echelon Form

1.1.1 Previous definitions and properties

This function returns True if each position lesser than k in a column contains
a zero.

definition is-zero-row-up-to-k :: 'rows => nat => 'a::{zero} ^'columns:::{mod-type} ^'rows
=> bool
  where is-zero-row-up-to-k i k A = (forall j:'columns. (to-nat j) < k --> A $ i $ j =
0)

definition is-zero-row :: 'rows => 'a::{zero} ^'columns:::{mod-type} ^'rows => bool
  where is-zero-row i A = is-zero-row-up-to-k i (ncols A) A

lemma is-zero-row-up-to-ncols:
  fixes A::'a::{zero} ^'columns:::{mod-type} ^'rows
  shows is-zero-row-up-to-k i (ncols A) A = (forall j:'columns. A $ i $ j = 0) ⟨proof⟩

corollary is-zero-row-def':
  fixes A::'a::{zero} ^'columns:::{mod-type} ^'rows
  shows is-zero-row i A = (forall j:'columns. A $ i $ j = 0) ⟨proof⟩

lemma is-zero-row-eq-row-zero: is-zero-row a A = (row a A = 0)
  ⟨proof⟩

lemma not-is-zero-row-up-to-suc:
  assumes not is-zero-row-up-to-k i (Suc k) A
  and forall i. A $ i $ (from-nat k) = 0
  shows not is-zero-row-up-to-k i k A
  ⟨proof⟩

lemma is-zero-row-up-to-k-suc:
  assumes is-zero-row-up-to-k i k A
  and A $ i $ (from-nat k) = 0
  shows is-zero-row-up-to-k i (Suc k) A
  ⟨proof⟩

lemma is-zero-row-up-to-0:

```

```

shows is-zero-row-up $t$ -k m 0 A ⟨proof⟩

lemma is-zero-row-up $t$ -0':
shows  $\forall m.$  is-zero-row-up $t$ -k m 0 A ⟨proof⟩

lemma is-zero-row-up $t$ -k-le:
assumes is-zero-row-up $t$ -k i (Suc k) A
shows is-zero-row-up $t$ -k i k A
⟨proof⟩

lemma is-zero-row-imp-is-zero-row-up $t$ :
assumes is-zero-row i A
shows is-zero-row-up $t$ -k i k A
⟨proof⟩

```

### 1.1.2 Definition of reduced row echelon form up to a column

This definition returns True if a matrix is in reduced row echelon form up to the column k (not included), otherwise False.

```

definition reduced-row-echelon-form-up $t$ -k :: 'a::{zero, one} ^'m::{mod-type} ^'n::{finite,
ord, plus, one} => nat => bool
where reduced-row-echelon-form-up $t$ -k A k =
(
  ( $\forall i.$  is-zero-row-up $t$ -k i k A  $\longrightarrow \neg (\exists j. j > i \wedge \neg$  is-zero-row-up $t$ -k j k A))  $\wedge$ 
  ( $\forall i.$   $\neg$  (is-zero-row-up $t$ -k i k A)  $\longrightarrow A \$ i \$ (LEAST k. A \$ i \$ k \neq 0) = 1$ )  $\wedge$ 
  ( $\forall i.$   $i < i+1 \wedge \neg$  (is-zero-row-up $t$ -k i k A)  $\wedge \neg$  (is-zero-row-up $t$ -k (i+1) k A)
 $\longrightarrow ((LEAST n. A \$ i \$ n \neq 0) < (LEAST n. A \$ (i+1) \$ n \neq 0)) \wedge$ 
  ( $\forall i.$   $\neg$  (is-zero-row-up $t$ -k i k A)  $\longrightarrow (\forall j. i \neq j \longrightarrow A \$ j \$ (LEAST n. A \$ i \$$ 
 $n \neq 0) = 0))$ 
)
)
```

```

lemma rref-up $t$ -0: reduced-row-echelon-form-up $t$ -k A 0
⟨proof⟩

lemma rref-up $t$ -condition1:
assumes r: reduced-row-echelon-form-up $t$ -k A k
shows ( $\forall i.$  is-zero-row-up $t$ -k i k A  $\longrightarrow \neg (\exists j. j > i \wedge \neg$  is-zero-row-up $t$ -k j k A))
⟨proof⟩

lemma rref-up $t$ -condition2:
assumes r: reduced-row-echelon-form-up $t$ -k A k
shows ( $\forall i.$   $\neg$  (is-zero-row-up $t$ -k i k A)  $\longrightarrow A \$ i \$ (LEAST k. A \$ i \$ k \neq 0)$ 
= 1)
⟨proof⟩

lemma rref-up $t$ -condition3:
assumes r: reduced-row-echelon-form-up $t$ -k A k
shows ( $\forall i.$   $i < i+1 \wedge \neg$  (is-zero-row-up $t$ -k i k A)  $\wedge \neg$  (is-zero-row-up $t$ -k (i+1) k

```

$A) \longrightarrow ((\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i+1) \$ n \neq 0)))$   
 $\langle \text{proof} \rangle$

**lemma rref-up-t-condition4:**

**assumes**  $r: \text{reduced-row-echelon-form-up-t-k } A k$   
**shows**  $(\forall i. \neg (\text{is-zero-row-up-t-k } i k A) \longrightarrow (\forall j. i \neq j \longrightarrow A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0))$   
 $\langle \text{proof} \rangle$

Explicit lemmas for each condition

**lemma rref-up-t-condition1-explicit:**

**assumes**  $\text{reduced-row-echelon-form-up-t-k } A k$   
**and**  $\text{is-zero-row-up-t-k } i k A$   
**and**  $j > i$   
**shows**  $\text{is-zero-row-up-t-k } j k A$   
 $\langle \text{proof} \rangle$

**lemma rref-up-t-condition2-explicit:**

**assumes**  $rref-A: \text{reduced-row-echelon-form-up-t-k } A k$   
**and**  $\neg \text{is-zero-row-up-t-k } i k A$   
**shows**  $A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1$   
 $\langle \text{proof} \rangle$

**lemma rref-up-t-condition3-explicit:**

**assumes**  $\text{reduced-row-echelon-form-up-t-k } A k$   
**and**  $i < i + 1$   
**and**  $\neg \text{is-zero-row-up-t-k } i k A$   
**and**  $\neg \text{is-zero-row-up-t-k } (i + 1) k A$   
**shows**  $(\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i + 1) \$ n \neq 0)$   
 $\langle \text{proof} \rangle$

**lemma rref-up-t-condition4-explicit:**

**assumes**  $\text{reduced-row-echelon-form-up-t-k } A k$   
**and**  $\neg \text{is-zero-row-up-t-k } i k A$   
**and**  $i \neq j$   
**shows**  $A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0$   
 $\langle \text{proof} \rangle$

Intro lemma and general properties

**lemma reduced-row-echelon-form-up-t-k-intro:**

**assumes**  $(\forall i. \text{is-zero-row-up-t-k } i k A \longrightarrow \neg (\exists j. j > i \wedge \neg \text{is-zero-row-up-t-k } j k A))$   
**and**  $(\forall i. \neg (\text{is-zero-row-up-t-k } i k A) \longrightarrow A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1)$   
**and**  $(\forall i. i < i + 1 \wedge \neg (\text{is-zero-row-up-t-k } i k A) \wedge \neg (\text{is-zero-row-up-t-k } (i + 1) k A) \longrightarrow ((\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i + 1) \$ n \neq 0)))$   
**and**  $(\forall i. \neg (\text{is-zero-row-up-t-k } i k A) \longrightarrow (\forall j. i \neq j \longrightarrow A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0))$   
**shows**  $\text{reduced-row-echelon-form-up-t-k } A k$

$\langle proof \rangle$

```

lemma rref-suc-imp-rref:
  fixes A::'a::{semiring_1} ^'n::{mod-type} ^'m::{mod-type}
  assumes r: reduced-row-echelon-form-upt-k A (Suc k)
  and k-le-card: Suc k < ncols A
  shows reduced-row-echelon-form-upt-k A k
   $\langle proof \rangle$ 

```

```

lemma reduced-row-echelon-if-all-zero:
  assumes all-zero:  $\forall n. \text{is-zero-row-upt-}k\ n\ k\ A$ 
  shows reduced-row-echelon-form-upt-k A k
   $\langle proof \rangle$ 

```

### 1.1.3 The definition of reduced row echelon form

Definition of reduced row echelon form, based on *reduced-row-echelon-form-upt-k-def*

```

definition reduced-row-echelon-form :: 'a::{zero, one} ^'m::{mod-type} ^'n::{finite,
ord, plus, one} => bool
  where reduced-row-echelon-form A = reduced-row-echelon-form-upt-k A (ncols A)

```

Equivalence between our definition of reduced row echelon form and the one presented in Steven Roman's book: Advanced Linear Algebra.

```

lemma reduced-row-echelon-form-def':
reduced-row-echelon-form A =
  (
    ( $\forall i. \text{is-zero-row } i\ A \longrightarrow \neg (\exists j. j > i \wedge \neg \text{is-zero-row } j\ A)$ )  $\wedge$ 
    ( $\forall i. \neg (\text{is-zero-row } i\ A) \longrightarrow A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1$ )  $\wedge$ 
    ( $\forall i. i < i+1 \wedge \neg (\text{is-zero-row } i\ A) \wedge \neg (\text{is-zero-row } (i+1)\ A) \longrightarrow ((\text{LEAST } k.$ 
     $A \$ i \$ k \neq 0) < (\text{LEAST } k. A \$ (i+1) \$ k \neq 0))$ )  $\wedge$ 
    ( $\forall i. \neg (\text{is-zero-row } i\ A) \longrightarrow (\forall j. i \neq j \longrightarrow A \$ j \$ (\text{LEAST } k. A \$ i \$ k \neq 0)$ 
     $= 0))$ )
   $\langle proof \rangle$ 

```

## 1.2 Properties of the reduced row echelon form of a matrix

```

lemma rref-condition1:
  assumes r: reduced-row-echelon-form A
  shows ( $\forall i. \text{is-zero-row } i\ A \longrightarrow \neg (\exists j. j > i \wedge \neg \text{is-zero-row } j\ A)$ )  $\langle proof \rangle$ 

```

```

lemma rref-condition2:
  assumes r: reduced-row-echelon-form A
  shows ( $\forall i. \neg (\text{is-zero-row } i\ A) \longrightarrow A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1$ )
   $\langle proof \rangle$ 

```

```

lemma rref-condition3:
  assumes r: reduced-row-echelon-form A

```

**shows**  $(\forall i. i < i+1 \wedge \neg (\text{is-zero-row } i A) \wedge \neg (\text{is-zero-row } (i+1) A) \longrightarrow ((\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i+1) \$ n \neq 0)))$   
 $\langle \text{proof} \rangle$

**lemma rref-condition4:**

**assumes**  $r: \text{reduced-row-echelon-form } A$   
**shows**  $(\forall i. \neg (\text{is-zero-row } i A) \longrightarrow (\forall j. i \neq j \longrightarrow A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0))$   
 $\langle \text{proof} \rangle$

Explicit lemmas for each condition

**lemma rref-condition1-explicit:**

**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $\text{is-zero-row } i A$   
**shows**  $\forall j > i. \text{is-zero-row } j A$   
 $\langle \text{proof} \rangle$

**lemma rref-condition2-explicit:**

**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $\neg \text{is-zero-row } i A$   
**shows**  $A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1$   
 $\langle \text{proof} \rangle$

**lemma rref-condition3-explicit:**

**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $i\text{-le: } i < i + 1$   
**and**  $\neg \text{is-zero-row } i A \text{ and } \neg \text{is-zero-row } (i + 1) A$   
**shows**  $(\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i + 1) \$ n \neq 0)$   
 $\langle \text{proof} \rangle$

**lemma rref-condition4-explicit:**

**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $\neg \text{is-zero-row } i A$   
**and**  $i \neq j$   
**shows**  $A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0$   
 $\langle \text{proof} \rangle$

Other properties and equivalences

**lemma rref-condition3-equiv1:**

**fixes**  $A::'a::\{\text{one, zero}\}^{\wedge}\text{cols}::\{\text{mod-type}\}^{\wedge}\text{rows}::\{\text{mod-type}\}$   
**assumes**  $rref: \text{reduced-row-echelon-form } A$   
**and**  $i\text{-less-j: } i < j$   
**and**  $j\text{-less-nrows: } j < \text{nrows } A$   
**and**  $\text{not-zero-i: } \neg \text{is-zero-row } (\text{from-nat } i) A$   
**and**  $\text{not-zero-j: } \neg \text{is-zero-row } (\text{from-nat } j) A$   
**shows**  $(\text{LEAST } n. A \$ (\text{from-nat } i) \$ n \neq 0) < (\text{LEAST } n. A \$ (\text{from-nat } j) \$ n \neq 0)$   
 $\langle \text{proof} \rangle$

```

corollary rref-condition3-equiv:
fixes A::'a::{one, zero} ^'cols::{mod-type} ^'rows::{mod-type}
assumes rref: reduced-row-echelon-form A
and i-less-j: i < j
and i: ¬ is-zero-row i A
and j: ¬ is-zero-row j A
shows (LEAST n. A $ i $ n ≠ 0) < (LEAST n. A $ j $ n ≠ 0)
⟨proof⟩

```

```

lemma rref-implies-rref-up:
fixes A::'a::{one,zero} ^'cols::{mod-type} ^'rows::{mod-type}
assumes rref: reduced-row-echelon-form A
shows reduced-row-echelon-form-up-k A k
⟨proof⟩

```

```

lemma rref-first-position-zero-imp-column-0:
fixes A::'a::{one,zero} ^'cols::{mod-type} ^'rows::{mod-type}
assumes rref: reduced-row-echelon-form A
and A-00: A $ 0 $ 0 = 0
shows column 0 A = 0
⟨proof⟩

```

```

lemma rref-first-element:
fixes A::'a::{one,zero} ^'cols::{mod-type} ^'rows::{mod-type}
assumes rref: reduced-row-echelon-form A
and column-not-0: column 0 A ≠ 0
shows A $ 0 $ 0 = 1
⟨proof⟩

```

end

## 2 Code set

```

theory Code-Set
imports
  HOL-Library.Code-Cardinality
begin

```

The following setup could help to get code generation for List.coset, but it neither works correctly it complains that code equations for remove are missed, even when List.coset should be rewritten to an enum:

```

declare minus-coset-filter [code del]
declare remove-code(2) [code del]
declare insert-code(2) [code del]
declare inter-coset-fold [code del]

```

```

declare compl-coset[code del]
declare Code-Cardinality.card'-code(2)[code del]

code-datatype set

```

The following code equation could be useful to avoid the problem of code generation for List.coset []:

```

lemma [code]: List.coset (l::'a::enum list) = set (enum-class.enum) – set l
    {proof}

```

Now the following examples work:

```

value UNIV::bool set
value List.coset ([]::bool list)
value UNIV::Enum.finite-2 set
value List.coset ([]::Enum.finite-2 list)
value List.coset ([]::Enum.finite-5 list)

end

```

### 3 Code generation for vectors and matrices

```

theory Code-Matrix
imports
    Rank-Nullity-Theorem.Miscellaneous
    Code-Set
begin

```

In this file the code generator is set up properly to allow the execution of matrices represented as functions over finite types.

```

lemmas vec.vec-nth-inverse[code abstype]

lemma [code abstract]: vec-nth 0 = (%x. 0) {proof}
lemma [code abstract]: vec-nth 1 = (%x. 1) {proof}
lemma [code abstract]: vec-nth (a + b) = (%i. a$i + b$i) {proof}
lemma [code abstract]: vec-nth (a - b) = (%i. a$i - b$i) {proof}
lemma [code abstract]: vec-nth (vec n) = (%i. n) {proof}
lemma [code abstract]: vec-nth (a * b) = (%i. a$i * b$i) {proof}
lemma [code abstract]: vec-nth (c * s x) = (%i. c * (x$i)) {proof}
lemma [code abstract]: vec-nth (a - b) = (%i. a$i - b$i) {proof}

definition mat-mult-row
    where mat-mult-row m m' f = vec-lambda (%c. sum (%k. ((m$f)$k) * ((m'$k)$c))
        (UNIV :: 'n::finite set))

lemma mat-mult-row-code [code abstract]:
    vec-nth (mat-mult-row m m' f) = (%c. sum (%k. ((m$f)$k) * ((m'$k)$c)) (UNIV :: 'n::finite set))
    {proof}

```

```

lemma mat-mult [code abstract]: vec-nth (m ** m') = mat-mult-row m m'
  ⟨proof⟩

lemma matrix-vector-mult-code [code abstract]:
  vec-nth (A *v x) = (%i. (∑ j ∈ UNIV. A $ i $ j * x $ j)) ⟨proof⟩

lemma vector-matrix-mult-code [code abstract]:
  vec-nth (x v* A) = (%j. (∑ i ∈ UNIV. x $ i * A $ i $ j)) ⟨proof⟩

definition mat-row
  where mat-row k i = vec-lambda (%j. if i = j then k else 0)

lemma mat-row-code [code abstract]:
  vec-nth (mat-row k i) = (%j. if i = j then k else 0) ⟨proof⟩

lemma [code abstract]: vec-nth (mat k) = mat-row k
  ⟨proof⟩

definition transpose-row
  where transpose-row A i = vec-lambda (%j. A $ j $ i)

lemma transpose-row-code [code abstract]:
  vec-nth (transpose-row A i) = (%j. A $ j $ i) ⟨proof⟩

lemma transpose-code[code abstract]:
  vec-nth (transpose A) = transpose-row A
  ⟨proof⟩

lemma [code abstract]: vec-nth (row i A) = ((\$) (A $ i)) ⟨proof⟩
lemma [code abstract]: vec-nth (column j A) = (%i. A $ i $ j) ⟨proof⟩

definition rowvector-row v i = vec-lambda (%j. (v\$j))

lemma rowvector-row-code [code abstract]:
  vec-nth (rowvector-row v i) = (%j. (v\$j)) ⟨proof⟩

lemma [code abstract]: vec-nth (rowvector v) = rowvector-row v
  ⟨proof⟩

definition columnvector-row v i = vec-lambda (%j. (v\$i))

lemma columnvector-row-code [code abstract]:
  vec-nth (columnvector-row v i) = (%j. (v\$i)) ⟨proof⟩

lemma [code abstract]: vec-nth (columnvector v) = columnvector-row v
  ⟨proof⟩

end

```

## 4 Elementary Operations over matrices

```

theory Elementary-Operations
imports
  Rank-Nullity-Theorem.Fundamental-Subspaces
  Code-Matrix
begin

4.1 Some previous results:

lemma mat-1-fun: mat 1 $ a $ b = ( $\lambda i j. \text{if } i=j \text{ then } 1 \text{ else } 0$ ) a b ⟨proof⟩

lemma mat1-sum-eq:
  shows  $(\sum k \in \text{UNIV}. \text{mat} (1 :: 'a :: \{\text{semiring-1}\}) \$ s \$ k * \text{mat} 1 \$ k \$ t) = \text{mat} 1 \$ s \$ t$ 
⟨proof⟩

lemma invertible-mat-n:
  fixes n :: 'a :: {field}
  assumes n:  $n \neq 0$ 
  shows invertible  $((\text{mat} n) :: 'a ^n \wedge n)$ 
⟨proof⟩

corollary invertible-mat-1:
  shows invertible  $(\text{mat} (1 :: 'a :: \{\text{field}\}))$  ⟨proof⟩

```

### 4.2 Definitions of elementary row and column operations

Definitions of elementary row operations

```

definition interchange-rows :: 'a ^n ^m => 'm => 'm => 'a ^n ^m
  where interchange-rows A a b = ( $\chi i j. \text{if } i=a \text{ then } A \$ b \$ j \text{ else if } i=b \text{ then } A \$ a \$ j \text{ else } A \$ i \$ j$ )

definition mult-row :: ('a :: times) ^n ^m => 'm => 'a => 'a ^n ^m
  where mult-row A a q = ( $\chi i j. \text{if } i=a \text{ then } q * (A \$ a \$ j) \text{ else } A \$ i \$ j$ )

```

```

definition row-add :: ('a :: {plus, times}) ^n ^m => 'm => 'm => 'a => 'a ^n ^m
  where row-add A a b q = ( $\chi i j. \text{if } i=a \text{ then } (A \$ a \$ j) + q * (A \$ b \$ j) \text{ else } A \$ i \$ j$ )

```

Definitions of elementary column operations

```

definition interchange-columns :: 'a ^n ^m => 'n => 'n => 'a ^n ^m
  where interchange-columns A n m = ( $\chi i j. \text{if } j=n \text{ then } A \$ i \$ m \text{ else if } j=m \text{ then } A \$ i \$ n \text{ else } A \$ i \$ j$ )

definition mult-column :: ('a :: times) ^n ^m => 'n => 'a => 'a ^n ^m
  where mult-column A n q = ( $\chi i j. \text{if } j=n \text{ then } (A \$ i \$ j) * q \text{ else } A \$ i \$ j$ )

```

```

definition column-add :: ('a:::{plus, times}) ^'n ^'m => 'n => 'n => 'a => 'a
^'n ^'m
where column-add A n m q = ( $\chi$  i j. if  $j=n$  then ((A $ i $ n) + (A $ i $ m)*q)
else A $ i $ j)

```

### 4.3 Properties about elementary row operations

#### 4.3.1 Properties about interchanging rows

Properties about *interchange-rows*

```

lemma interchange-same-rows: interchange-rows A a a = A
⟨proof⟩

```

```

lemma interchange-rows-i[simp]: interchange-rows A i j $ i = A $ j
⟨proof⟩

```

```

lemma interchange-rows-j[simp]: interchange-rows A i j $ j = A $ i
⟨proof⟩

```

```

lemma interchange-rows-preserves:
assumes i ≠ a and j ≠ a
shows interchange-rows A i j $ a = A $ a
⟨proof⟩

```

```

lemma interchange-rows-mat-1:
shows interchange-rows (mat 1) a b ** A = interchange-rows A a b
⟨proof⟩

```

```

lemma invertible-interchange-rows: invertible (interchange-rows (mat 1) a b)
⟨proof⟩

```

#### 4.3.2 Properties about multiplying a row by a constant

Properties about *mult-row*

```

lemma mult-row-mat-1: mult-row (mat 1) a q ** A = mult-row A a q
⟨proof⟩

```

```

lemma invertible-mult-row:
assumes qk: q * k = 1 and kq: k*q=1
shows invertible (mult-row (mat 1) a q)
⟨proof⟩

```

```

corollary invertible-mult-row':
assumes q-not-zero: q ≠ 0
shows invertible (mult-row (mat (1::'a:::{field}))) a q
⟨proof⟩

```

### 4.3.3 Properties about adding a row multiplied by a constant to another row

Properties about *row-add*

**lemma** *row-add-mat-1*: *row-add* (*mat 1*)  $a b q \star\star A = \text{row-add } A a b q$   
*(proof)*

**lemma** *invertible-row-add*:  
  **assumes** *a-noteq-b*:  $a \neq b$   
  **shows** *invertible* (*row-add* (*mat* ( $1::'a::\{\text{ring-1}\}$ )))  $a b q$   
*(proof)*

## 4.4 Properties about elementary column operations

### 4.4.1 Properties about interchanging columns

Properties about *interchange-columns*

**lemma** *interchange-columns-mat-1*:  $A \star\star \text{interchange-columns} (\text{mat 1}) a b = \text{interchange-columns } A a b$   
*(proof)*

**lemma** *invertible-interchange-columns*: *invertible* (*interchange-columns* (*mat 1*)  $a b$ )  
*(proof)*

### 4.4.2 Properties about multiplying a column by a constant

Properties about *mult-column*

**lemma** *mult-column-mat-1*:  $A \star\star \text{mult-column} (\text{mat 1}) a q = \text{mult-column } A a q$   
*(proof)*

**lemma** *invertible-mult-column*:  
  **assumes** *qk*:  $q * k = 1$  **and** *kq*:  $k * q = 1$   
  **shows** *invertible* (*mult-column* (*mat 1*)  $a q$ )  
*(proof)*

**corollary** *invertible-mult-column'*:  
  **assumes** *q-not-zero*:  $q \neq 0$   
  **shows** *invertible* (*mult-column* (*mat* ( $1::'a::\{\text{field}\}$ )))  $a q$ )  
*(proof)*

### 4.4.3 Properties about adding a column multiplied by a constant to another column

Properties about *column-add*

**lemma** *column-add-mat-1*:  $A \star\star \text{column-add} (\text{mat 1}) a b q = \text{column-add } A a b q$   
*(proof)*

```

lemma invertible-column-add:
  assumes a-noteq-b:  $a \neq b$ 
  shows invertible (column-add (mat (1::'a::{ring-1})) a b q)
  ⟨proof⟩

```

## 4.5 Relationships amongst the definitions

Relationships between *interchange-rows* and *interchange-columns*

```

lemma interchange-rows-transpose:
  shows interchange-rows (transpose A) a b = transpose (interchange-columns A
a b)
  ⟨proof⟩

```

```

lemma interchange-rows-transpose':
  shows interchange-rows A a b = transpose (interchange-columns (transpose A)
a b)
  ⟨proof⟩

```

```

lemma interchange-columns-transpose:
  shows interchange-columns (transpose A) a b = transpose (interchange-rows A
a b)
  ⟨proof⟩

```

```

lemma interchange-columns-transpose':
  shows interchange-columns A a b = transpose (interchange-rows (transpose A)
a b)
  ⟨proof⟩

```

## 4.6 Code Equations

Code equations for *interchange-rows*  $?A ?a ?b = (\chi i j. \text{if } i = ?a \text{ then } ?A \$ ?b \$ j \text{ else if } i = ?b \text{ then } ?A \$ ?a \$ j \text{ else } ?A \$ i \$ j)$ , *interchange-columns*  $?A ?n ?m = (\chi i j. \text{if } j = ?n \text{ then } ?A \$ i \$ ?m \text{ else if } j = ?m \text{ then } ?A \$ i \$ ?n \text{ else } ?A \$ i \$ j)$ , *row-add*  $?A ?a ?b ?q = (\chi i j. \text{if } i = ?a \text{ then } ?A \$ ?a \$ j + ?q * ?A \$ ?b \$ j \text{ else } ?A \$ i \$ j)$ , *column-add*  $?A ?n ?m ?q = (\chi i j. \text{if } j = ?n \text{ then } ?A \$ i \$ ?n + ?A \$ i \$ ?m * ?q \text{ else } ?A \$ i \$ j)$ , *mult-row*  $?A ?a ?q = (\chi i j. \text{if } i = ?a \text{ then } ?q * ?A \$ ?a \$ j \text{ else } ?A \$ i \$ j)$  and *mult-column*  $?A ?n ?q = (\chi i j. \text{if } j = ?n \text{ then } ?A \$ i \$ j * ?q \text{ else } ?A \$ i \$ j)$ :

**definition** interchange-rows-row

**where** interchange-rows-row  $A a b i = \text{vec-lambda } (\%j. \text{if } i = a \text{ then } A \$ b \$ j \text{ else if } i = b \text{ then } A \$ a \$ j \text{ else } A \$ i \$ j)$

```

lemma interchange-rows-code [code abstract]:
  vec-nth (interchange-rows-row A a b i) = (%j. \text{if } i = a \text{ then } A \$ b \$ j \text{ else if } i =
b \text{ then } A \$ a \$ j \text{ else } A \$ i \$ j)

```

$\langle proof \rangle$

**lemma** *interchange-rows-code-nth* [code abstract]: *vec-nth* (*interchange-rows A a b*) = *interchange-rows-row A a b*  
 $\langle proof \rangle$

**definition** *interchange-columns-row*

**where** *interchange-columns-row A n m i* = *vec-lambda* (%j. if  $j = n$  then  $A \$ i \$ m$  else if  $j = m$  then  $A \$ i \$ n$  else  $A \$ i \$ j$ )

**lemma** *interchange-columns-code* [code abstract]:

*vec-nth* (*interchange-columns-row A n m i*) = (%j. if  $j = n$  then  $A \$ i \$ m$  else if  $j = m$  then  $A \$ i \$ n$  else  $A \$ i \$ j$ )  
 $\langle proof \rangle$

**lemma** *interchange-columns-code-nth* [code abstract]: *vec-nth* (*interchange-columns A a b*) = *interchange-columns-row A a b*

$\langle proof \rangle$

**definition** *row-add-row*

**where** *row-add-row A a b q i* = *vec-lambda* (%j. if  $i = a$  then  $A \$ a \$ j + q * A \$ b \$ j$  else  $A \$ i \$ j$ )

**lemma** *row-add-code* [code abstract]:

*vec-nth* (*row-add-row A a b q i*) = (%j. if  $i = a$  then  $A \$ a \$ j + q * A \$ b \$ j$  else  $A \$ i \$ j$ )  
 $\langle proof \rangle$

**lemma** *row-add-code-nth* [code abstract]: *vec-nth* (*row-add A a b q*) = *row-add-row A a b q*

$\langle proof \rangle$

**definition** *column-add-row*

**where** *column-add-row A n m q i* = *vec-lambda* (%j. if  $j = n$  then  $A \$ i \$ n + A \$ i \$ m * q$  else  $A \$ i \$ j$ )

**lemma** *column-add-code* [code abstract]:

*vec-nth* (*column-add-row A n m q i*) = (%j. if  $j = n$  then  $A \$ i \$ n + A \$ i \$ m * q$  else  $A \$ i \$ j$ )  
 $\langle proof \rangle$

**lemma** *column-add-code-nth* [code abstract]: *vec-nth* (*column-add A a b q*) = *column-add-row A a b q*

$\langle proof \rangle$

**definition** *mult-row-row*

**where** *mult-row-row A a q i* = *vec-lambda* (%j. if  $i = a$  then  $q * A \$ a \$ j$  else  $A \$ i \$ j$ )

```

lemma mult-row-code [code abstract]:
  vec-nth (mult-row-row A a q i) = (%j. if i = a then q * A $ a $ j else A $ i $ j)
  ⟨proof⟩

lemma mult-row-code-nth [code abstract]: vec-nth (mult-row A a q) = mult-row-row
A a q
⟨proof⟩

definition mult-column-row
  where mult-column-row A n q i = vec-lambda (%j. if j = n then A $ i $ j * q
else A $ i $ j)

lemma mult-column-code [code abstract]:
  vec-nth (mult-column-row A n q i) = (%j. if j = n then A $ i $ j * q else A $ i
$ j)
  ⟨proof⟩

lemma mult-column-code-nth [code abstract]: vec-nth (mult-column A a q) = mult-column-row
A a q
⟨proof⟩

end

```

## 5 Rank of a matrix

```

theory Rank
imports
  Rank-Nullity-Theorem.Dim-Formula
begin

```

### 5.1 Row rank, column rank and rank

Definitions of row rank, column rank and rank

```

definition row-rank :: 'a::{field} ^n ^m=>nat
  where row-rank A = vec.dim (row-space A)

definition col-rank :: 'a::{field} ^n ^m=>nat
  where col-rank A = vec.dim (col-space A)

```

```

lemma rank-def: rank A = row-rank A
  ⟨proof⟩

```

### 5.2 Properties

```

lemma rrk-is-preserved:
fixes A::'a::{field} ^cols ^rows::{finite, wellorder}
and P::'a::{field} ^rows::{finite, wellorder} ^rows::{finite, wellorder}

```

```

assumes inv- $P$ : invertible  $P$ 
shows row-rank  $A$  = row-rank ( $P**A$ )
⟨proof⟩

lemma crk-is-preserved:
fixes  $A::'a::\{field\} \wedge cols::\{finite, wellorder\} \wedge rows$ 
and  $P::'a::\{field\} \wedge rows \wedge rows$ 
assumes inv- $P$ : invertible  $P$ 
shows col-rank  $A$  = col-rank ( $P**A$ )
⟨proof⟩

end

```

## 6 Gauss Jordan algorithm over abstract matrices

```

theory Gauss-Jordan
imports
  Rref
  Elementary-Operations
  Rank
begin

```

### 6.1 The Gauss-Jordan Algorithm

Now, a computable version of the Gauss-Jordan algorithm is presented. The output will be a matrix in reduced row echelon form. We present an algorithm in which the reduction is applied by columns

Using this definition, zeros are made in the column  $j$  of a matrix  $A$  placing the pivot entry (a nonzero element) in the position  $(i,j)$ . For that, a suitable row interchange is made to achieve a non-zero entry in position  $(i,j)$ . Then, this pivot entry is multiplied by its inverse to make the pivot entry equals to 1. After that, are other entries of the  $j$ -th column are eliminated by subtracting suitable multiples of the  $i$ -th row from the other rows.

```

definition Gauss-Jordan-in- $ij$  :: ' $a::\{\text{semiring-1, inverse, one, uminus}\} \wedge m \wedge n::\{finite, ord\} \Rightarrow 'n=>'m=>'a \wedge m \wedge n::\{finite, ord\}$ 
where Gauss-Jordan-in- $ij$   $A$   $i$   $j$  = (let  $n = (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)$ ;
  interchange- $A$  = (interchange-rows  $A$   $i$   $n$ );
   $A' = \text{mult-row interchange-}A\ i\ (1/\text{interchange-}A\$i\$j)\ \text{in}\ \text{vec-lambda}(\% s. \text{if } s=i \text{ then } A'\ \$ s \text{ else } (\text{row-add } A'\ s\ i\ (-(\text{interchange-}A\$s\$j))) \$ s))$ 

```

```

lemma Gauss-Jordan-in- $ij$ -unfold:
assumes  $\exists n. A \$ n \$ j \neq 0 \wedge i \leq n$ 
obtains  $n :: 'n::\{finite, wellorder\}$  and interchange- $A$  and  $A'$ 
where
   $(\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n) = n$ 

```

```

and  $A \$ n \$ j \neq 0$ 
and  $i \leq n$ 
and  $\text{interchange-}A = \text{interchange-rows } A i n$ 
and  $A' = \text{mult-row interchange-}A i (1 / \text{interchange-}A \$ i \$ j)$ 
and  $\text{Gauss-Jordan-in-}ij A i j = \text{vec-lambda } (\lambda s. \text{ if } s = i \text{ then } A' \$ s$ 
       $\text{else (row-add } A' s i (- (\text{interchange-}A \$ s \$ j))) \$ s)$ 

```

$\langle \text{proof} \rangle$

The following definition makes the step of Gauss-Jordan in a column. This function receives two input parameters: the column k where the step of Gauss-Jordan must be applied and a pair (which consists of the row where the pivot should be placed in the column k and the original matrix).

```

definition  $\text{Gauss-Jordan-column-}k :: (\text{nat} \times ('a :: \{\text{zero}, \text{inverse}, \text{uminus}, \text{semiring-}1\})^m :: \{\text{mod-type}\})^n :: \{\text{mod-type}\}$ 

 $=> \text{nat} => (\text{nat} \times ('a ^m :: \{\text{mod-type}\}) ^n :: \{\text{mod-type}\}))$ 
where  $\text{Gauss-Jordan-column-}k A' k = (\text{let } i = \text{fst } A'; A = (\text{snd } A'); \text{from-nat-}i = (\text{from-nat } i :: 'm); \text{from-nat-}k = (\text{from-nat } k :: 'm) \text{ in}$ 
       $\text{if } (\forall m \geq (\text{from-nat-}i). A \$ m \$ (\text{from-nat-}k) = 0) \vee (i = \text{nrows } A) \text{ then } (i, A)$ 
       $\text{else } (i + 1, (\text{Gauss-Jordan-in-}ij A (\text{from-nat-}i) (\text{from-nat-}k))) )$ 

```

The following definition applies the Gauss-Jordan step from the first column up to the k one (included).

```

definition  $\text{Gauss-Jordan-up-}k :: 'a :: \{\text{inverse}, \text{uminus}, \text{semiring-}1\}^{\text{columns} :: \{\text{mod-type}\}}^{\text{rows} :: \{\text{mod-type}\}}$ 
 $=> \text{nat}$ 
 $=> 'a ^{\text{columns} :: \{\text{mod-type}\}} ^{\text{rows} :: \{\text{mod-type}\}}$ 
where  $\text{Gauss-Jordan-up-}k A k = \text{snd } (\text{foldl } \text{Gauss-Jordan-column-}k (0, A) [0 .. < \text{Suc } k])$ 

```

Gauss-Jordan is to apply the *Gauss-Jordan-column-k* in all columns.

```

definition  $\text{Gauss-Jordan} :: 'a :: \{\text{inverse}, \text{uminus}, \text{semiring-}1\}^{\text{columns} :: \{\text{mod-type}\}}^{\text{rows} :: \{\text{mod-type}\}}$ 

 $=> 'a ^{\text{columns} :: \{\text{mod-type}\}} ^{\text{rows} :: \{\text{mod-type}\}}$ 
where  $\text{Gauss-Jordan } A = \text{Gauss-Jordan-up-}k A ((\text{ncols } A) - 1)$ 

```

## 6.2 Properties about rref and the greatest nonzero row.

```

lemma  $\text{greatest-plus-one-eq-}0:$ 
  fixes  $A :: 'a :: \{\text{field}\}^{\text{columns} :: \{\text{mod-type}\}}^{\text{rows} :: \{\text{mod-type}\}}$  and  $k :: \text{nat}$ 
  assumes  $\text{Suc } (\text{to-nat } (\text{GREATEST } n. \neg \text{is-zero-row-up-}k n k A)) = \text{nrows } A$ 
  shows  $(\text{GREATEST } n. \neg \text{is-zero-row-up-}k n k A) + 1 = 0$ 

```

$\langle \text{proof} \rangle$

```

lemma  $\text{from-nat-to-nat-greatest}:$ 
  fixes  $A :: 'a :: \{\text{zero}\}^{\text{columns} :: \{\text{mod-type}\}}^{\text{rows} :: \{\text{mod-type}\}}$ 
  shows  $\text{from-nat } (\text{Suc } (\text{to-nat } (\text{GREATEST } n. \neg \text{is-zero-row-up-}k n k A))) =$ 
 $(\text{GREATEST } n. \neg \text{is-zero-row-up-}k n k A) + 1$ 

```

$\langle \text{proof} \rangle$

```

lemma greatest-less-zero-row:
  fixes A::'a::{one, zero} ^'n::{mod-type} ^'m::{finite, one, plus, linorder}
  assumes r: reduced-row-echelon-form-up $\leq$ t-k A k
  and zero-i: is-zero-row-up $\leq$ t-k i k A
  and not-all-zero:  $\neg (\forall a. \text{is-zero-row-up $\leq$ t-k } a k A)$ 
  shows (GREATEST m.  $\neg \text{is-zero-row-up $\leq$ t-k } m k A) < i
  (proof)

lemma rref-suc-if-zero-below-greatest:
  fixes A::'a::{one, zero} ^'n::{mod-type} ^'m::{finite, one, plus, linorder}
  assumes r: reduced-row-echelon-form-up $\leq$ t-k A k
  and not-all-zero:  $\neg (\forall a. \text{is-zero-row-up $\leq$ t-k } a k A)$ 
  and all-zero-below-greatest:  $\forall a. a > (\text{GREATEST } m. \neg \text{is-zero-row-up $\leq$ t-k } m k A)$ 
   $\longrightarrow$  is-zero-row-up $\leq$ t-k a (Suc k) A
  shows reduced-row-echelon-form-up $\leq$ t-k A (Suc k)
  (proof)

lemma rref-suc-if-all-rows-not-zero:
  fixes A::'a::{one, zero} ^'n::{mod-type} ^'m::{finite, one, plus, linorder}
  assumes r: reduced-row-echelon-form-up $\leq$ t-k A k
  and all-not-zero:  $\forall n. \neg \text{is-zero-row-up $\leq$ t-k } n k A$ 
  shows reduced-row-echelon-form-up $\leq$ t-k A (Suc k)
  (proof)

lemma greatest-ge-nonzero-row:
  fixes A::'a::{zero} ^'n::{mod-type} ^'m::{finite, linorder}
  assumes  $\neg \text{is-zero-row-up $\leq$ t-k } i k A$ 
  shows i  $\leq$  (GREATEST m.  $\neg \text{is-zero-row-up $\leq$ t-k } m k A) (proof)

lemma greatest-ge-nonzero-row':
  fixes A::'a::{zero, one} ^'n::{mod-type} ^'m::{finite, linorder, one, plus}
  assumes r: reduced-row-echelon-form-up $\leq$ t-k A k
  and i: i  $\leq$  (GREATEST m.  $\neg \text{is-zero-row-up $\leq$ t-k } m k A)
  and not-all-zero:  $\neg (\forall a. \text{is-zero-row-up $\leq$ t-k } a k A)$ 
  shows  $\neg \text{is-zero-row-up $\leq$ t-k } i k A$ 
  (proof)

corollary row-greater-greatest-is-zero:
  fixes A::'a::{zero} ^'n::{mod-type} ^'m::{finite, linorder}
  assumes (GREATEST m.  $\neg \text{is-zero-row-up $\leq$ t-k } m k A) < i
  shows is-zero-row-up $\leq$ t-k i k A (proof)$$$$ 
```

### 6.3 The proof of its correctness

Properties of *Gauss-Jordan-in-ij*

```

lemma Gauss-Jordan-in-ij-1:
  fixes A::'a::{field} ^'m ^'n::{finite, ord, wellorder}
  assumes ex:  $\exists n. A \$ n \$ j \neq 0 \wedge i \leq n$ 

```

**shows** (*Gauss-Jordan-in-ij A i j*) \$ i \$ j = 1  
 $\langle proof \rangle$

**lemma** *Gauss-Jordan-in-ij-0*:

**fixes**  $A: a:\{\text{field}\} \wedge m \wedge n:\{\text{finite, ord, wellorder}\}$   
**assumes**  $\exists n. A \$ n \$ j \neq 0 \wedge i \leq n$  **and**  $a: a \neq i$   
**shows** (*Gauss-Jordan-in-ij A i j*) \$ a \$ j = 0  
 $\langle proof \rangle$

**corollary** *Gauss-Jordan-in-ij-0'*:

**fixes**  $A: a:\{\text{field}\} \wedge m \wedge n:\{\text{finite, ord, wellorder}\}$   
**assumes**  $\exists n. A \$ n \$ j \neq 0 \wedge i \leq n$   
**shows**  $\forall a. a \neq i \rightarrow (\text{Gauss-Jordan-in-ij } A \ i \ j) \$ a \$ j = 0$   $\langle proof \rangle$

**lemma** *Gauss-Jordan-in-ij-preserves-previous-elements*:

**fixes**  $A: a:\{\text{field}\} \wedge \text{columns}:\{\text{mod-type}\} \wedge \text{rows}:\{\text{mod-type}\}$   
**assumes**  $r: \text{reduced-row-echelon-form-upt-k } A \ k$   
**and**  $\text{not-zero-a}: \neg \text{is-zero-row-upt-k } a \ k \ A$   
**and**  $\text{exists-m}: \exists m. A \$ m \$ (\text{from-nat } k) \neq 0 \wedge (\text{GREATEST } m. \neg \text{is-zero-row-upt-k } m \ k \ A) + 1 \leq m$   
**and**  $\text{Greatest-plus-1}: (\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n \ k \ A) + 1 \neq 0$   
**and**  $j \leq k: \text{to-nat } j < k$   
**shows**  $\text{Gauss-Jordan-in-ij } A ((\text{GREATEST } m. \neg \text{is-zero-row-upt-k } m \ k \ A) + 1)$   
 $(\text{from-nat } k) \$ i \$ j = A \$ i \$ j$   
 $\langle proof \rangle$

**lemma** *Gauss-Jordan-in-ij-preserves-previous-elements'*:

**fixes**  $A: a:\{\text{field}\} \wedge \text{columns}:\{\text{mod-type}\} \wedge \text{rows}:\{\text{mod-type}\}$   
**assumes**  $\text{all-zero}: \forall n. \text{is-zero-row-upt-k } n \ k \ A$   
**and**  $j \leq k: \text{to-nat } j < k$   
**and**  $A \cdot nk \cdot \text{not-zero}: A \$ n \$ (\text{from-nat } k) \neq 0$   
**shows**  $\text{Gauss-Jordan-in-ij } A 0 (\text{from-nat } k) \$ i \$ j = A \$ i \$ j$   
 $\langle proof \rangle$

**lemma** *is-zero-after-Gauss*:

**fixes**  $A: a:\{\text{field}\} \wedge n:\{\text{mod-type}\} \wedge m:\{\text{mod-type}\}$   
**assumes**  $\text{zero-a}: \text{is-zero-row-upt-k } a \ k \ A$   
**and**  $\text{not-zero-m}: \neg \text{is-zero-row-upt-k } m \ k \ A$   
**and**  $r: \text{reduced-row-echelon-form-upt-k } A \ k$   
**and**  $\text{greatest-less-ma}: (\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n \ k \ A) + 1 \leq ma$   
**and**  $A \cdot ma \cdot \text{not-zero}: A \$ ma \$ (\text{from-nat } k) \neq 0$   
**shows**  $\text{is-zero-row-upt-k } a \ k (\text{Gauss-Jordan-in-ij } A ((\text{GREATEST } m. \neg \text{is-zero-row-upt-k } m \ k \ A) + 1)) (\text{from-nat } k)$   
 $\langle proof \rangle$

**lemma** *all-zero-imp-Gauss-Jordan-column-not-zero-in-row-0*:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes all-zero:  $\forall n.$  is-zero-row-up-k n k A
and not-zero-i:  $\neg$  is-zero-row-up-k i (Suc k) B
and Amk-zero: A $ m $ from-nat k  $\neq$  0
shows i=0
⟨proof⟩

```

Here we start to prove that the output of *Gauss Jordan* A is a matrix in reduced row echelon form.

**lemma** condition-1-part-1:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
assumes zero-column-k:  $\forall m \geq$  from-nat 0. A $ m $ from-nat k = 0
and all-zero:  $\forall m.$  is-zero-row-up-k m k A
shows is-zero-row-up-k j (Suc k) A
⟨proof⟩

```

**lemma** condition-1-part-2:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
assumes j-not-zero: j  $\neq$  0
and all-zero:  $\forall m.$  is-zero-row-up-k m k A
and Amk-not-zero: A $ m $ from-nat k  $\neq$  0
shows is-zero-row-up-k j (Suc k) (Gauss-Jordan-in-ij A (from-nat 0) (from-nat
k))
⟨proof⟩

```

**lemma** condition-1-part-3:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes rref: reduced-row-echelon-form-up-k A k
and i-less-j: i < j
and not-zero-m:  $\neg$  is-zero-row-up-k m k A
and zero-below-greatest:  $\forall m \geq$  (GREATEST n.  $\neg$  is-zero-row-up-k n k A) + 1.
A $ m $ from-nat k = 0
and zero-i-suc-k: is-zero-row-up-k i (Suc k) B
shows is-zero-row-up-k j (Suc k) A
⟨proof⟩

```

**lemma** condition-1-part-4:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes rref: reduced-row-echelon-form-up-k A k
and zero-i-suc-k: is-zero-row-up-k i (Suc k) B

```

```

and i-less-j:  $i < j$ 
and not-zero-m:  $\neg \text{is-zero-row-upk } m k A$ 
and greatest-eq-card:  $\text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A)) = \text{nrows } A$ 
shows is-zero-row-upk j (Suc k) A
⟨proof⟩

```

```

lemma condition-1-part-5:
fixes  $A: a:\{\text{field}\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k:\text{nat}$ 
defines  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else } \text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1)$ 
defines  $B:B \equiv (\text{snd}(\text{Gauss-Jordan-column-k } (ia, A) k))$ 
assumes  $rref: \text{reduced-row-echelon-form-upk } A k$ 
and zero-i-suc-k:  $\text{is-zero-row-upk } i (\text{Suc } k) B$ 
and i-less-j:  $i < j$ 
and not-zero-m:  $\neg \text{is-zero-row-upk } m k A$ 
and greatest-not-card:  $\text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A)) \neq \text{nrows } A$ 
and greatest-less-ma:  $(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1 \leq ma$ 
and A-ma-k-not-zero:  $A \$ ma \$ \text{from-nat } k \neq 0$ 
shows is-zero-row-upk j (Suc k) (Gauss-Jordan-in-ij A ((GREATEST n. \neg is-zero-row-upk n k A) + 1) (from-nat k))
⟨proof⟩

```

```

lemma condition-1:
fixes  $A: a:\{\text{field}\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k:\text{nat}$ 
defines  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else } \text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1)$ 
defines  $B:B \equiv (\text{snd}(\text{Gauss-Jordan-column-k } (ia, A) k))$ 
assumes  $rref: \text{reduced-row-echelon-form-upk } A k$ 
and zero-i-suc-k:  $\text{is-zero-row-upk } i (\text{Suc } k) B$  and i-less-j:  $i < j$ 
shows is-zero-row-upk j (Suc k) B
⟨proof⟩

```

```

lemma condition-2-part-1:
fixes  $A: a:\{\text{field}\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k:\text{nat}$ 
defines  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else } \text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1)$ 
defines  $B:B \equiv (\text{snd}(\text{Gauss-Jordan-column-k } (ia, A) k))$ 
assumes not-zero-i-suc-k:  $\neg \text{is-zero-row-upk } i (\text{Suc } k) B$ 
and all-zero:  $\forall m. \text{is-zero-row-upk } m k A$ 
and all-zero-k:  $\forall m. A \$ m \$ \text{from-nat } k = 0$ 
shows  $A \$ i \$ (\text{LEAST } k. A \$ i \$ k \neq 0) = 1$ 
⟨proof⟩

```

```

lemma condition-2-part-2:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
  defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up $t$ -k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up $t$ -k n k A) + 1)
  defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
  assumes not-zero-i-suc-k:  $\neg$  is-zero-row-up $t$ -k i (Suc k) B
  and all-zero:  $\forall m.$  is-zero-row-up $t$ -k m k A
  and Amk-not-zero: A $ m $ from-nat k  $\neq$  0
  shows Gauss-Jordan-in-ij A 0 (from-nat k) $ i $ (LEAST ka. Gauss-Jordan-in-ij
A 0 (from-nat k) $ i $ ka  $\neq$  0) = 1
  ⟨proof⟩

```

```

lemma condition-2-part-3:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
  defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up $t$ -k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up $t$ -k n k A) + 1)
  defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
  assumes rref: reduced-row-echelon-form-up $t$ -k A k
  and not-zero-i-suc-k:  $\neg$  is-zero-row-up $t$ -k i (Suc k) B
  and not-zero-m:  $\neg$  is-zero-row-up $t$ -k m k A
  and zero-below-greatest:  $\forall m \geq$  (GREATEST n.  $\neg$  is-zero-row-up $t$ -k n k A) + 1.
A $ m $ from-nat k = 0
  shows A $ i $ (LEAST k. A $ i $ k  $\neq$  0) = 1
  ⟨proof⟩

```

```

lemma condition-2-part-4:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
  assumes rref: reduced-row-echelon-form-up $t$ -k A k
  and not-zero-m:  $\neg$  is-zero-row-up $t$ -k m k A
  and greatest-eq-card: Suc (to-nat (GREATEST n.  $\neg$  is-zero-row-up $t$ -k n k A)) =
nrows A
  shows A $ i $ (LEAST k. A $ i $ k  $\neq$  0) = 1
  ⟨proof⟩

```

```

lemma condition-2-part-5:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
  defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-up $t$ -k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-up $t$ -k n k A) + 1)
  defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
  assumes rref: reduced-row-echelon-form-up $t$ -k A k
  and not-zero-i-suc-k:  $\neg$  is-zero-row-up $t$ -k i (Suc k) B
  and not-zero-m:  $\neg$  is-zero-row-up $t$ -k m k A
  and greatest-noteq-card: Suc (to-nat (GREATEST n.  $\neg$  is-zero-row-up $t$ -k n k A)) =
 $\neq$  nrows A

```

**and** greatest-less-ma: ( $\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1 \leq ma$   
**and** A-ma-k-not-zero:  $A \$ ma \$ \text{from-nat } k \neq 0$   
**shows** Gauss-Jordan-in-ij A ( $(\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1)$   
 $(\text{from-nat } k) \$ i \$$   
 $(\text{LEAST } ka. \text{Gauss-Jordan-in-ij } A ((\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1) (\text{from-nat } k) \$ i \$ ka \neq 0) = 1$   
 $\langle \text{proof} \rangle$

**lemma** condition-2:  
**fixes**  $A::'a::\{\text{field}\} \wedge' \text{columns}::\{\text{mod-type}\} \wedge' \text{rows}::\{\text{mod-type}\}$  **and**  $k::\text{nat}$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upt-k } m k A \text{ then } 0 \text{ else } \text{to-nat} (\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd} (\text{Gauss-Jordan-column-k } (ia, A) k))$   
**assumes** rref: reduced-row-echelon-form-upt-k  $A k$   
**and** not-zero-i-suc-k:  $\neg \text{is-zero-row-upt-k } i (\text{Suc } k) B$   
**shows**  $B \$ i \$ (\text{LEAST } k. B \$ i \$ k \neq 0) = 1$   
 $\langle \text{proof} \rangle$

**lemma** condition-3-part-1:  
**fixes**  $A::'a::\{\text{field}\} \wedge' \text{columns}::\{\text{mod-type}\} \wedge' \text{rows}::\{\text{mod-type}\}$  **and**  $k::\text{nat}$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upt-k } m k A \text{ then } 0 \text{ else } \text{to-nat} (\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd} (\text{Gauss-Jordan-column-k } (ia, A) k))$   
**assumes** not-zero-i-suc-k:  $\neg \text{is-zero-row-upt-k } i (\text{Suc } k) B$   
**and** all-zero:  $\forall m. \text{is-zero-row-upt-k } m k A$   
**and** all-zero-k:  $\forall m. A \$ m \$ \text{from-nat } k = 0$   
**shows**  $(\text{LEAST } n. A \$ i \$ n \neq 0) < (\text{LEAST } n. A \$ (i + 1) \$ n \neq 0)$   
 $\langle \text{proof} \rangle$

**lemma** condition-3-part-2:  
**fixes**  $A::'a::\{\text{field}\} \wedge' \text{columns}::\{\text{mod-type}\} \wedge' \text{rows}::\{\text{mod-type}\}$  **and**  $k::\text{nat}$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upt-k } m k A \text{ then } 0 \text{ else } \text{to-nat} (\text{GREATEST } n. \neg \text{is-zero-row-upt-k } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd} (\text{Gauss-Jordan-column-k } (ia, A) k))$   
**assumes** i-le:  $i < i + 1$   
**and** not-zero-i-suc-k:  $\neg \text{is-zero-row-upt-k } i (\text{Suc } k) B$   
**and** not-zero-suc-i-suc-k:  $\neg \text{is-zero-row-upt-k } (i + 1) (\text{Suc } k) B$   
**and** all-zero:  $\forall m. \text{is-zero-row-upt-k } m k A$   
**and** Amk-notzero:  $A \$ m \$ \text{from-nat } k \neq 0$   
**shows**  $(\text{LEAST } n. \text{Gauss-Jordan-in-ij } A 0 (\text{from-nat } k) \$ i \$ n \neq 0) < (\text{LEAST } n. \text{Gauss-Jordan-in-ij } A 0 (\text{from-nat } k) \$ (i + 1) \$ n \neq 0)$   
 $\langle \text{proof} \rangle$

**lemma** *condition-3-part-3*:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-upt-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-upt-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes rref: reduced-row-echelon-form-upt-k A k
and i-le:  $i < i + 1$ 
and not-zero-i-suc-k:  $\neg$  is-zero-row-upt-k i (Suc k) B
and not-zero-suc-i-suc-k:  $\neg$  is-zero-row-upt-k (i + 1) (Suc k) B
and not-zero-m:  $\neg$  is-zero-row-upt-k m k A
and zero-below-greatest:  $\forall m \geq$  (GREATEST n.  $\neg$  is-zero-row-upt-k n k A) + 1.
A $ m $ from-nat k = 0
shows (LEAST n. A $ i $ n  $\neq$  0)  $<$  (LEAST n. A $ (i + 1) $ n  $\neq$  0)
⟨proof⟩

```

**lemma** *condition-3-part-4*:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-upt-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-upt-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes rref: reduced-row-echelon-form-upt-k A k and i-le:  $i < i + 1$ 
and not-zero-i-suc-k:  $\neg$  is-zero-row-upt-k i (Suc k) B
and not-zero-suc-i-suc-k:  $\neg$  is-zero-row-upt-k (i + 1) (Suc k) B
and not-zero-m:  $\neg$  is-zero-row-upt-k m k A
and greatest-eq-card: Suc (to-nat (GREATEST n.  $\neg$  is-zero-row-upt-k n k A)) =
nrows A
shows (LEAST n. A $ i $ n  $\neq$  0)  $<$  (LEAST n. A $ (i + 1) $ n  $\neq$  0)
⟨proof⟩

```

**lemma** *condition-3-part-5*:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat
defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-upt-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-upt-k n k A) + 1)
defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
assumes rref: reduced-row-echelon-form-upt-k A k
and i-le:  $i < i + 1$ 
and not-zero-i-suc-k:  $\neg$  is-zero-row-upt-k i (Suc k) B
and not-zero-suc-i-suc-k:  $\neg$  is-zero-row-upt-k (i + 1) (Suc k) B
and not-zero-m:  $\neg$  is-zero-row-upt-k m k A
and greatest-not-card: Suc (to-nat (GREATEST n.  $\neg$  is-zero-row-upt-k n k A)) ≠
nrows A
and greatest-less-ma: (GREATEST n.  $\neg$  is-zero-row-upt-k n k A) + 1  $\leq$  ma
and A-ma-k-not-zero: A $ ma $ from-nat k  $\neq$  0
shows (LEAST n. Gauss-Jordan-in-ij A ((GREATEST n.  $\neg$  is-zero-row-upt-k n
k A) + 1) (from-nat k) $ i $ n  $\neq$  0)
 $<$  (LEAST n. Gauss-Jordan-in-ij A ((GREATEST n.  $\neg$  is-zero-row-upt-k n k A)
+ 1) (from-nat k) $ (i + 1) $ n  $\neq$  0)

```

$\langle proof \rangle$

**lemma** *condition-3*:

fixes  $A::'a::\{field\} \wedge'columns::\{mod-type\} \wedge'rows::\{mod-type\}$  **and**  $k::nat$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else to-nat (GREATEST}$   
 $n. \neg \text{is-zero-row-upk } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd (Gauss-Jordan-column-k (ia,A) k)})$   
**assumes**  $rref: \text{reduced-row-echelon-form-upk } A k$   
**and**  $i-le: i < i + 1$   
**and**  $\text{not-zero-i-suc-k: } \neg \text{is-zero-row-upk } i (\text{Suc } k) B$   
**and**  $\text{not-zero-suc-i-suc-k: } \neg \text{is-zero-row-upk } (i + 1) (\text{Suc } k) B$   
**shows**  $(\text{LEAST } n. B \$ i \$ n \neq 0) < (\text{LEAST } n. B \$ (i + 1) \$ n \neq 0)$   
 $\langle proof \rangle$

**lemma** *condition-4-part-1*:

fixes  $A::'a::\{field\} \wedge'columns::\{mod-type\} \wedge'rows::\{mod-type\}$  **and**  $k::nat$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else to-nat (GREATEST}$   
 $n. \neg \text{is-zero-row-upk } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd (Gauss-Jordan-column-k (ia,A) k)})$   
**assumes**  $\text{not-zero-i-suc-k: } \neg \text{is-zero-row-upk } i (\text{Suc } k) B$   
**and**  $\text{all-zero: } \forall m. \text{is-zero-row-upk } m k A$   
**and**  $\text{all-zero-k: } \forall m. A \$ m \$ \text{from-nat } k = 0$   
**shows**  $A \$ j \$ (\text{LEAST } n. A \$ i \$ n \neq 0) = 0$   
 $\langle proof \rangle$

**lemma** *condition-4-part-2*:

fixes  $A::'a::\{field\} \wedge'columns::\{mod-type\} \wedge'rows::\{mod-type\}$  **and**  $k::nat$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else to-nat (GREATEST}$   
 $n. \neg \text{is-zero-row-upk } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd (Gauss-Jordan-column-k (ia,A) k)})$   
**assumes**  $\text{not-zero-i-suc-k: } \neg \text{is-zero-row-upk } i (\text{Suc } k) B$   
**and**  $i-not-j: i \neq j$   
**and**  $\text{all-zero: } \forall m. \text{is-zero-row-upk } m k A$   
**and**  $\text{Amk-not-zero: } A \$ m \$ \text{from-nat } k \neq 0$   
**shows**  $\text{Gauss-Jordan-in-ij } A 0 (\text{from-nat } k) \$ j \$ (\text{LEAST } n. \text{Gauss-Jordan-in-ij}$   
 $A 0 (\text{from-nat } k) \$ i \$ n \neq 0) = 0$   
 $\langle proof \rangle$

**lemma** *condition-4-part-3*:

fixes  $A::'a::\{field\} \wedge'columns::\{mod-type\} \wedge'rows::\{mod-type\}$  **and**  $k::nat$   
**defines**  $ia:ia \equiv (\text{if } \forall m. \text{is-zero-row-upk } m k A \text{ then } 0 \text{ else to-nat (GREATEST}$   
 $n. \neg \text{is-zero-row-upk } n k A) + 1)$   
**defines**  $B:B \equiv (\text{snd (Gauss-Jordan-column-k (ia,A) k)})$   
**assumes**  $rref: \text{reduced-row-echelon-form-upk } A k$   
**and**  $\text{not-zero-i-suc-k: } \neg \text{is-zero-row-upk } i (\text{Suc } k) B$   
**and**  $i-not-j: i \neq j$

**and** *not-zero-m*:  $\neg \text{is-zero-row-upk } m k A$   
**and** *zero-below-greatest*:  $\forall m \geq (\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1.$

*A \$ m \$ from-nat k = 0*

**shows** *A \$ j \$ (LEAST n. A \$ i \$ n ≠ 0) = 0*

*{proof}*

**lemma** *condition-4-part-4*:

**fixes** *A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat*

**defines** *ia:ia*≡(*if*  $\forall m. \text{is-zero-row-upk } m k A$  *then* 0 *else* *to-nat* (*GREATEST* *n. ¬ is-zero-row-upk n k A*) + 1)

**defines** *B:B*≡(*snd* (*Gauss-Jordan-column-k* (*ia,A*) *k*))

**assumes** *rref*: *reduced-row-echelon-form-upk A k*

**and** *not-zero-i-suc-k*:  $\neg \text{is-zero-row-upk } i (\text{Suc } k) B$

**and** *i-not-j*: *i ≠ j*

**and** *not-zero-m*:  $\neg \text{is-zero-row-upk } m k A$

**and** *greatest-eq-card*: *Suc (to-nat (GREATEST n. ¬ is-zero-row-upk n k A)) = nrows A*

**shows** *A \$ j \$ (LEAST n. A \$ i \$ n ≠ 0) = 0*

*{proof}*

**lemma** *condition-4-part-5*:

**fixes** *A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat*

**defines** *ia:ia*≡(*if*  $\forall m. \text{is-zero-row-upk } m k A$  *then* 0 *else* *to-nat* (*GREATEST* *n. ¬ is-zero-row-upk n k A*) + 1)

**defines** *B:B*≡(*snd* (*Gauss-Jordan-column-k* (*ia,A*) *k*))

**assumes** *rref*: *reduced-row-echelon-form-upk A k*

**and** *not-zero-i-suc-k*:  $\neg \text{is-zero-row-upk } i (\text{Suc } k) B$

**and** *i-not-j*: *i ≠ j*

**and** *not-zero-m*:  $\neg \text{is-zero-row-upk } m k A$

**and** *greatest-not-card*: *Suc (to-nat (GREATEST n. ¬ is-zero-row-upk n k A)) ≠ nrows A*

**and** *greatest-less-ma*: (*GREATEST n. ¬ is-zero-row-upk n k A*) + 1 ≤ *ma*

**and** *A-ma-k-not-zero*: *A \$ ma \$ from-nat k ≠ 0*

**shows** *Gauss-Jordan-in-ij A ((GREATEST n. ¬ is-zero-row-upk n k A) + 1) (from-nat k) \$ j \$ (LEAST n. Gauss-Jordan-in-ij A ((GREATEST n. ¬ is-zero-row-upk n k A) + 1) (from-nat k) \$ i \$ n ≠ 0) = 0*

*{proof}*

**lemma** *condition-4*:

**fixes** *A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type} and k::nat*

**defines** *ia:ia*≡(*if*  $\forall m. \text{is-zero-row-upk } m k A$  *then* 0 *else* *to-nat* (*GREATEST* *n. ¬ is-zero-row-upk n k A*) + 1)

**defines** *B:B*≡(*snd* (*Gauss-Jordan-column-k* (*ia,A*) *k*))

**assumes** *rref*: *reduced-row-echelon-form-upk A k*

**and** *not-zero-i-suc-k*:  $\neg \text{is-zero-row-upk } i (\text{Suc } k) B$

**and** *i-not-j*: *i ≠ j*

**shows** *B \$ j \$ (LEAST n. B \$ i \$ n ≠ 0) = 0*

$\langle proof \rangle$

```

lemma reduced-row-echelon-form-upt-k-Gauss-Jordan-column-k:
  fixes A::'a::{field}  $\wedge$ 'columns::{mod-type}  $\wedge$ 'rows::{mod-type} and k::nat
  defines ia:ia $\equiv$ (if  $\forall m.$  is-zero-row-upt-k m k A then 0 else to-nat (GREATEST
n.  $\neg$  is-zero-row-upt-k n k A) + 1)
  defines B:B $\equiv$ (snd (Gauss-Jordan-column-k (ia,A) k))
  assumes rref: reduced-row-echelon-form-upt-k A k
  shows reduced-row-echelon-form-upt-k B (Suc k)
   $\langle proof \rangle$ 

```

```

lemma foldl-Gauss-condition-1:
  fixes A::'a::{field}  $\wedge$ 'columns::{mod-type}  $\wedge$ 'rows::{mod-type} and k::nat
  assumes  $\forall m.$  is-zero-row-upt-k m k A
  and  $\forall m \geq 0.$  A $ m $ from-nat k = 0
  shows is-zero-row-upt-k m (Suc k) A
   $\langle proof \rangle$ 

```

```

lemma foldl-Gauss-condition-2:
  fixes A::'a::{field}  $\wedge$ 'columns::{mod-type}  $\wedge$ 'rows::{mod-type} and k::nat
  assumes k: k < ncols A
  and all-zero:  $\forall m.$  is-zero-row-upt-k m k A
  and Amk-not-zero: A $ m $ from-nat k  $\neq$  0
  shows  $\exists m.$   $\neg$  is-zero-row-upt-k m (Suc k) (Gauss-Jordan-in-ij A 0 (from-nat k))
   $\langle proof \rangle$ 

```

```

lemma foldl-Gauss-condition-3:
  fixes A::'a::{field}  $\wedge$ 'columns::{mod-type}  $\wedge$ 'rows::{mod-type} and k::nat
  assumes k: k < ncols A
  and all-zero:  $\forall m.$  is-zero-row-upt-k m k A
  and Amk-not-zero: A $ m $ from-nat k  $\neq$  0
  and  $\neg$  is-zero-row-upt-k ma (Suc k) (Gauss-Jordan-in-ij A 0 (from-nat k))
  shows to-nat (GREATEST n.  $\neg$  is-zero-row-upt-k n (Suc k) (Gauss-Jordan-in-ij
A 0 (from-nat k))) = 0
   $\langle proof \rangle$ 

```

```

lemma foldl-Gauss-condition-5:
  fixes A::'a::{field}  $\wedge$ 'columns::{mod-type}  $\wedge$ 'rows::{mod-type} and k::nat
  assumes rref-A: reduced-row-echelon-form-upt-k A k
  and not-zero-a: $\neg$  is-zero-row-upt-k a k A
  and all-zero-below-greatest:  $\forall m \geq$ (GREATEST n.  $\neg$  is-zero-row-upt-k n k A) +
1. A $ m $ from-nat k = 0
  shows (GREATEST n.  $\neg$  is-zero-row-upt-k n k A) = (GREATEST n.  $\neg$  is-zero-row-upt-k
n (Suc k) A)

```

$\langle proof \rangle$

**lemma** foldl-Gauss-condition-6:

fixes  $A: 'a::\{field\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k::\text{nat}$   
**assumes** not-zero-m:  $\neg \text{is-zero-row-upk } m k A$   
**and** eq-card:  $\text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A)) = \text{nrows } A$   
**shows**  $\text{nrows } A = \text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n (\text{Suc } k) A))$

$\langle proof \rangle$

**lemma** foldl-Gauss-condition-8:

fixes  $A: 'a::\{field\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k::\text{nat}$   
**assumes**  $k: k < \text{ncols } A$   
**and** not-zero-m:  $\neg \text{is-zero-row-upk } m k A$   
**and** A-ma-k:  $A \$ ma \$ \text{from-nat } k \neq 0$   
**and** ma:  $(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1 \leq ma$   
**shows**  $\exists m. \neg \text{is-zero-row-upk } m (\text{Suc } k) (\text{Gauss-Jordan-in-ij } A ((\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1) (\text{from-nat } k))$

$\langle proof \rangle$

**lemma** foldl-Gauss-condition-9:

fixes  $A: 'a::\{field\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k::\text{nat}$   
**assumes**  $k: k < \text{ncols } A$   
**and** rref-A: reduced-row-echelon-form-upk  $A k$   
**assumes** not-zero-m:  $\neg \text{is-zero-row-upk } m k A$   
**and** suc-greatest-not-card:  $\text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A)) \neq \text{nrows } A$   
**and** greatest-less-ma:  $(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1 \leq ma$   
**and** A-ma-k:  $A \$ ma \$ \text{from-nat } k \neq 0$   
**shows**  $\text{Suc}(\text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A)) = \text{to-nat}(\text{GREATEST } n. \neg \text{is-zero-row-upk } n (\text{Suc } k) (\text{Gauss-Jordan-in-ij } A ((\text{GREATEST } n. \neg \text{is-zero-row-upk } n k A) + 1) (\text{from-nat } k)))$

$\langle proof \rangle$

The following lemma is one of most important ones in the verification of the Gauss-Jordan algorithm. The aim is to prove two statements about  $\text{Gauss-Jordan-upk } ?A ?k = \text{snd}(\text{foldl Gauss-Jordan-column-k } (0, ?A) [0..<\text{Suc } ?k])$  (one about the result is on rref and another about the index). The reason of doing that way is because both statements need them mutually to be proved. As the proof is made using induction, two base cases and two induction steps appear.

**lemma** rref-and-index-Gauss-Jordan-upk:

fixes  $A: 'a::\{field\} \rightsquigarrow \text{columns}:\{\text{mod-type}\} \rightsquigarrow \text{rows}:\{\text{mod-type}\}$  and  $k::\text{nat}$   
**assumes**  $k < \text{ncols } A$   
**shows** rref-Gauss-Jordan-upk: reduced-row-echelon-form-upk ( $\text{Gauss-Jordan-upk }$

```

 $A k) (Suc k)$ 
and snd-Gauss-Jordan-up-k:
 $\text{foldl Gauss-Jordan-column-k } (0, A) [0..<Suc k] =$ 
 $(\text{if } \forall m. \text{is-zero-row-up-k } m (\text{Suc } k) (\text{snd} (\text{foldl Gauss-Jordan-column-k } (0, A)$ 
 $[0..<Suc k])) \text{ then } 0$ 
 $\text{else to-nat} (\text{GREATEST } n. \neg \text{is-zero-row-up-k } n (\text{Suc } k) (\text{snd} (\text{foldl Gauss-Jordan-column-k}$ 
 $(0, A) [0..<Suc k]))) + 1,$ 
 $\text{snd} (\text{foldl Gauss-Jordan-column-k } (0, A) [0..<Suc k]))$ 
 $\langle \text{proof} \rangle$ 

```

```

corollary rref-Gauss-Jordan:
fixes  $A: 'a::\{\text{field}\}^n \times 'm::\{\text{mod-type}\}^n$ 
shows reduced-row-echelon-form (Gauss-Jordan A)
 $\langle \text{proof} \rangle$ 

```

```

lemma independent-not-zero-rows-rref:
fixes  $A: 'a::\{\text{field}\}^n \times 'm::\{\text{mod-type}\}^n$ 
assumes rref-A: reduced-row-echelon-form A
shows vec.independent { $\text{row } i \text{ } A \mid i. \text{row } i \text{ } A \neq 0$ }
 $\langle \text{proof} \rangle$ 

```

Here we start to prove that the transformation from the original matrix to its reduced row echelon form has been carried out by means of elementary operations.

The following function eliminates all entries of the  $j$ -th column using the non-zero element situated in the position  $(i,j)$ . It is introduced to make easier the proof that each Gauss-Jordan step consists in applying suitable elementary operations.

```

primrec row-add-iterate ::  $'a::\{\text{semiring-1}, \text{uminus}\}^n \times 'm::\{\text{mod-type}\} = > \text{nat}$ 
 $= > 'm = > 'n = > 'a^n \times 'm::\{\text{mod-type}\}$ 
where row-add-iterate  $A \ 0 \ i \ j =$  (if  $i=0$  then  $A$  else row-add  $A \ 0 \ i \ (-A \$ 0 \$ j)$ )
 $| \text{row-add-iterate } A (\text{Suc } n) i j =$  (if ( $\text{Suc } n = \text{to-nat } i$ ) then row-add-iterate  $A \ n \ i \ j$ 
 $\text{else} \text{row-add-iterate} (\text{row-add } A (\text{from-nat} (\text{Suc } n)) i (-A \$ (\text{from-nat} (\text{Suc } n)) \$ j)) \ n \ i \ j)$ 

```

```

lemma invertible-row-add-iterate:
fixes  $A: 'a::\{\text{ring-1}\}^n \times 'm::\{\text{mod-type}\}$ 
assumes  $n: n < \text{nrows } A$ 
shows  $\exists P. \text{invertible } P \wedge \text{row-add-iterate } A \ n \ i \ j = P ** A$ 
 $\langle \text{proof} \rangle$ 

```

```

lemma row-add-iterate-preserves-greater-than-n:
fixes  $A: 'a::\{\text{ring-1}\}^n \times 'm::\{\text{mod-type}\}$ 
assumes  $n: n < \text{nrows } A$ 

```

**and**  $a: \text{to-nat } a > n$   
**shows**  $(\text{row-add-iterate } A \ n \ i \ j) \$ a \$ b = A \$ a \$ b$   
 $\langle \text{proof} \rangle$

**lemma** *row-add-iterate-preserves-pivot-row*:  
**fixes**  $A: 'a::\{\text{ring-1}\} \wedge 'n \wedge m::\{\text{mod-type}\}$   
**assumes**  $n: n < \text{nrows } A$   
**and**  $a: \text{to-nat } i \leq n$   
**shows**  $(\text{row-add-iterate } A \ n \ i \ j) \$ i \$ b = A \$ i \$ b$   
 $\langle \text{proof} \rangle$

**lemma** *row-add-iterate-eq-row-add*:  
**fixes**  $A: 'a::\{\text{ring-1}\} \wedge 'n \wedge m::\{\text{mod-type}\}$   
**assumes**  $a \neq i$   
**and**  $n: n < \text{nrows } A$   
**and**  $\text{to-nat } a \leq n$   
**shows**  $(\text{row-add-iterate } A \ n \ i \ j) \$ a \$ b = (\text{row-add } A \ a \ i \ (-A \$ a \$ j)) \$ a \$ b$   
 $\langle \text{proof} \rangle$

**lemma** *row-add-iterate-eq-Gauss-Jordan-in-ij*:  
**fixes**  $A: 'a::\{\text{field}\} \wedge 'n \wedge m::\{\text{mod-type}\}$  **and**  $i::'m$  **and**  $j::'n$   
**defines**  $A': A' == \text{mult-row}(\text{interchange-rows } A \ i \ (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)) \ i \ (1 / (\text{interchange-rows } A \ i \ (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)) \$ i \$ j)$   
**shows**  $\text{row-add-iterate } A'(\text{nrows } A - 1) \ i \ j = \text{Gauss-Jordan-in-ij } A \ i \ j$   
 $\langle \text{proof} \rangle$

**lemma** *invertible-Gauss-Jordan-column-k*:  
**fixes**  $A: 'a::\{\text{field}\} \wedge 'n::\{\text{mod-type}\} \wedge m::\{\text{mod-type}\}$  **and**  $k::\text{nat}$   
**shows**  $\exists P. \text{invertible } P \wedge (\text{snd } (\text{Gauss-Jordan-column-}k(i, A) \ k)) = P ** A$   
 $\langle \text{proof} \rangle$

**lemma** *invertible-Gauss-Jordan-up-to-k*:  
**fixes**  $A: 'a::\{\text{field}\} \wedge 'n::\{\text{mod-type}\} \wedge m::\{\text{mod-type}\}$   
**shows**  $\exists P. \text{invertible } P \wedge (\text{Gauss-Jordan-up-to-}k A \ k) = P ** A$   
 $\langle \text{proof} \rangle$

**lemma** *inj-index-independent-rows*:  
**fixes**  $A: 'a::\{\text{field}\} \wedge m::\{\text{mod-type}\} \wedge n::\{\text{finite, one, plus, ord}\}$   
**assumes**  $\text{rref-}A: \text{reduced-row-echelon-form } A$   
**and**  $x: \text{row } x \in \{\text{row } i \ A \mid i. \text{row } i \ A \neq 0\}$   
**and**  $\text{eq}: A \$ x = A \$ y$   
**shows**  $x = y$   
 $\langle \text{proof} \rangle$

The final results:

**lemma invertible-Gauss-Jordan:**

**fixes**  $A::'a::\{field\} \wedge n::\{mod-type\} \wedge m::\{mod-type\}$   
**shows**  $\exists P. \text{invertible } P \wedge (\text{Gauss-Jordan } A) = P**A \langle proof \rangle$

**lemma Gauss-Jordan:**

**fixes**  $A::'a::\{field\} \wedge n::\{mod-type\} \wedge m::\{mod-type\}$   
**shows**  $\exists P. \text{invertible } P \wedge (\text{Gauss-Jordan } A) = P**A \wedge \text{reduced-row-echelon-form } (\text{Gauss-Jordan } A)$   
 $\langle proof \rangle$

Some properties about the rank of a matrix, obtained thanks to the Gauss-Jordan algorithm and the reduced row echelon form.

**lemma rref-rank:**

**fixes**  $A::'a::\{field\} \wedge m::\{mod-type\} \wedge n::\{finite,one,plus,ord\}$   
**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**shows**  $\text{rank } A = \text{card } \{\text{row } i \text{ } A \mid i. \text{row } i \text{ } A \neq 0\}$   
 $\langle proof \rangle$

**lemma column-leading-coefficient-component-eq:**

**fixes**  $A::'a::\{field\} \wedge m::\{mod-type\} \wedge n::\{finite,one,plus,ord\}$   
**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $v: v \in \{\text{column } (\text{LEAST } n. A \$ i \$ n \neq 0) A \mid i. \text{row } i \text{ } A \neq 0\}$   
**and**  $vx: v \$ x \neq 0$   
**and**  $vy: v \$ y \neq 0$   
**shows**  $x = y$   
 $\langle proof \rangle$

**lemma column-leading-coefficient-component-1:**

**fixes**  $A::'a::\{field\} \wedge m::\{mod-type\} \wedge n::\{finite,one,plus,ord\}$   
**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $v: v \in \{\text{column } (\text{LEAST } n. A \$ i \$ n \neq 0) A \mid i. \text{row } i \text{ } A \neq 0\}$   
**and**  $vx: v \$ x \neq 0$   
**shows**  $v \$ x = 1$   
 $\langle proof \rangle$

**lemma column-leading-coefficient-component-0:**

**fixes**  $A::'a::\{field\} \wedge m::\{mod-type\} \wedge n::\{finite,one,plus,ord\}$   
**assumes**  $rref-A: \text{reduced-row-echelon-form } A$   
**and**  $v: v \in \{\text{column } (\text{LEAST } n. A \$ i \$ n \neq 0) A \mid i. \text{row } i \text{ } A \neq 0\}$   
**and**  $vx: v \$ x \neq 0$   
**and**  $x-not-y: x \neq y$   
**shows**  $v \$ y = 0 \langle proof \rangle$

**lemma rref-col-rank:**

**fixes**  $A::'a::\{field\} \wedge m::\{mod-type\} \wedge n::\{mod-type\}$   
**assumes**  $rref-A: \text{reduced-row-echelon-form } A$

**shows**  $\text{col-rank } A = \text{card} \{ \text{column } (\text{LEAST } n. A \$ i \$ n \neq 0) A \mid i. \text{row } i A \neq 0 \}$   
 $\langle \text{proof} \rangle$

**lemma** *rref-row-rank*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow m::\{\text{mod-type}\} \rightsquigarrow n::\{\text{finite,one,plus,ord}\}$   
**assumes**  $\text{rref-}A: \text{reduced-row-echelon-form } A$   
**shows**  $\text{row-rank } A = \text{card} \{ \text{column } (\text{LEAST } n. A \$ i \$ n \neq 0) A \mid i. \text{row } i A \neq 0 \}$   
 $\langle \text{proof} \rangle$

**lemma** *row-rank-eq-col-rank-rref*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow m::\{\text{mod-type}\} \rightsquigarrow n::\{\text{mod-type}\}$   
**assumes**  $r: \text{reduced-row-echelon-form } A$   
**shows**  $\text{row-rank } A = \text{col-rank } A$   
 $\langle \text{proof} \rangle$

**lemma** *row-rank-eq-col-rank*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{row-rank } A = \text{col-rank } A$   
 $\langle \text{proof} \rangle$

**theorem** *rank-col-rank*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{rank } A = \text{col-rank } A \langle \text{proof} \rangle$

**theorem** *rank-eq-dim-image*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{rank } A = \text{vec.dim} (\text{range } (\lambda x. A * v x))$   
 $\langle \text{proof} \rangle$

**theorem** *rank-eq-dim-col-space*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{rank } A = \text{vec.dim} (\text{col-space } A) \langle \text{proof} \rangle$

**lemma** *rank-transpose*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{rank} (\text{transpose } A) = \text{rank } A$   
 $\langle \text{proof} \rangle$

**lemma** *rank-le-nrows*:  
**fixes**  $A: 'a::\{\text{field}\} \rightsquigarrow n::\{\text{mod-type}\} \rightsquigarrow m::\{\text{mod-type}\}$   
**shows**  $\text{rank } A \leq \text{nrows } A$   
 $\langle \text{proof} \rangle$

```

lemma rank-le-ncols:
  fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
  shows rank A ≤ ncols A
  ⟨proof⟩

lemma rank-Gauss-Jordan:
  fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
  shows rank A = rank (Gauss-Jordan A)
  ⟨proof⟩

```

Other interesting properties:

```

lemma A-0-imp-Gauss-Jordan-0:
  fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
  assumes A=0
  shows Gauss-Jordan A = 0
  ⟨proof⟩

lemma rank-0: rank 0 = 0
  ⟨proof⟩

```

```

lemma rank-greater-zero:
  assumes A ≠ 0
  shows rank A > 0
  ⟨proof⟩

lemma Gauss-Jordan-not-0:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes A ≠ 0
  shows Gauss-Jordan A ≠ 0
  ⟨proof⟩

```

```

lemma rank-eq-suc-to-nat-greatest:
  assumes A-not-0: A ≠ 0
  shows rank A = to-nat (GREATEST a. ¬ is-zero-row a (Gauss-Jordan A)) + 1
  ⟨proof⟩

```

```

lemma rank-less-row-i-imp-i-is-zero:
  assumes rank-less-i: to-nat i ≥ rank A
  shows Gauss-Jordan A $ i = 0
  ⟨proof⟩

```

```

lemma rank-Gauss-Jordan-eq:
  fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
  shows rank A = (let A'=(Gauss-Jordan A) in card {row i A' | i. row i A' ≠ 0})
  ⟨proof⟩

```

## 6.4 Lemmas for code generation and rank computation

```

lemma [code abstract]:
shows vec-nth (Gauss-Jordan-in-ij A i j) = (let n = (LEAST n. A $ n $ j ≠ 0 ∧
i ≤ n);
interchange-A = (interchange-rows A i n);
A' = mult-row interchange-A i (1/interchange-A$i$j) in
(% s. if s=i then A' $ s else (row-add A' s i (-(interchange-A$s$j))) $ s))
⟨proof⟩

lemma rank-Gauss-Jordan-code[code]:
fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
shows rank A = (if A = 0 then 0 else (let A'=(Gauss-Jordan A) in to-nat
(GREATEST a. row a A' ≠ 0) + 1))
⟨proof⟩

lemma dim-null-space[code-unfold]:
fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows vec.dim (null-space A) = (vec.dimension TYPE('a) TYPE('cols)) - rank
(A)
⟨proof⟩

lemma rank-eq-dim-col-space'[code-unfold]:
fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows vec.dim (col-space A) = rank A ⟨proof⟩

lemma dim-left-null-space[code-unfold]:
fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows vec.dim (left-null-space A) = (vec.dimension TYPE('a) TYPE('rows)) - rank
(A)
⟨proof⟩

lemmas rank-col-rank[symmetric, code-unfold]
lemmas rank-def[symmetric, code-unfold]
lemmas row-rank-def[symmetric, code-unfold]
lemmas col-rank-def[symmetric, code-unfold]
lemmas DIM-cart[code-unfold]
lemmas DIM-real[code-unfold]

end

```

## 7 Linear Maps

```

theory Linear-Maps
imports
    Gauss-Jordan
begin

lemma ((λ(x, y). (x::real , − y::real)) has-derivative (λh. (fst h, − snd h))) (at x)

```

$\langle proof \rangle$

## 7.1 Properties about ranks and linear maps

```
lemma rank-matrix-dim-range:
assumes lf: linear ((*)*) f
shows rank (matrix f::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}) = vec.dim
(range f)
⟨proof⟩
```

The following two lemmas are the demonstration of theorem 2.11 that appears the book "Advanced Linear Algebra" by Steven Roman.

```
lemma linear-injective-rank-eq-ncols:
assumes lf: linear ((*)*) f
shows inj f  $\longleftrightarrow$  rank (matrix f::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type})
= ncols (matrix f)
⟨proof⟩
```

```
lemma linear-surjective-rank-eq-ncols:
assumes lf: linear ((*)*) f
shows surj f  $\longleftrightarrow$  rank (matrix f::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type})
= nrows (matrix f)
⟨proof⟩
```

```
lemma linear-bij-rank-eq-ncols:
fixes f::('a::{field} ^'n::{mod-type}) => ('a::{field} ^'n::{mod-type})
assumes lf: linear ((*)*) f
shows bij f  $\longleftrightarrow$  rank (matrix f) = ncols (matrix f)
⟨proof⟩
```

## 7.2 Invertible linear maps

```
locale invertible-lf = Vector-Spaces.linear +
assumes invertible: ( $\exists g. g \circ f = id \wedge f \circ g = id$ )
begin
```

```
lemma invertible-lf: ( $\exists g. linear ((*)*) g \wedge (g \circ f = id) \wedge (f \circ g = id)$ )
⟨proof⟩
```

end

```
lemma (in Vector-Spaces.linear) invertible-lf-intro[intro]:
assumes (g ∘ f = id) and (f ∘ g = id)
shows invertible-lf ((*)*) f
⟨proof⟩
```

```
lemma invertible-imp-bijective:
assumes invertible-lf scaleB scaleC f
shows bij f
```

$\langle proof \rangle$

```
lemma invertible-matrix-imp-invertible-lf:  
  fixes A::'a::{field} ^n ^n  
  assumes invertible-A: invertible A  
  shows invertible-lf ((*s)) ((*s)) (λx. A *v x)  
 $\langle proof \rangle$ 
```

```
lemma invertible-lf-imp-invertible-matrix:  
  fixes f::'a::{field} ^n ⇒ 'a ^n  
  assumes invertible-f: invertible-lf ((*s)) ((*s)) f  
  shows invertible (matrix f)  
 $\langle proof \rangle$ 
```

```
lemma invertible-matrix-iff-invertible-lf:  
  fixes A::'a::{field} ^n ^n  
  shows invertible A ↔ invertible-lf ((*s)) ((*s)) (λx. A *v x)  
 $\langle proof \rangle$ 
```

```
lemma invertible-matrix-iff-invertible-lf':  
  fixes f::'a::{field} ^n ⇒ 'a ^n  
  assumes linear-f: linear ((*s)) ((*s)) f  
  shows invertible (matrix f) ↔ invertible-lf ((*s)) ((*s)) f  
 $\langle proof \rangle$ 
```

```
lemma invertible-matrix-mult-right-rank:  
  fixes A::'a::{field} ^n :: {mod-type} ^m :: {mod-type}  
  and Q::'a::{field} ^n :: {mod-type} ^n :: {mod-type}  
  assumes invertible-Q: invertible Q  
  shows rank (A**Q) = rank A  
 $\langle proof \rangle$ 
```

```
lemma subspace-image-invertible-mat:  
  fixes P::'a::{field} ^m ^m  
  assumes inv-P: invertible P  
  and sub-W: vec.subspace W  
  shows vec.subspace ((λx. P *v x) ` W)  
 $\langle proof \rangle$ 
```

```
lemma dim-image-invertible-mat:  
  fixes P::'a::{field} ^m ^m  
  assumes inv-P: invertible P  
  and sub-W: vec.subspace W  
  shows vec.dim ((λx. P *v x) ` W) = vec.dim W  
 $\langle proof \rangle$ 
```

```
lemma invertible-matrix-mult-left-rank:
```

```

fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
and P::'a::{field} ^'m::{mod-type} ^'m::{mod-type}
assumes invertible-P: invertible P
shows rank (P**A) = rank A
⟨proof⟩

corollary invertible-matrices-mult-rank:
fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
and P::'a ^'m::{mod-type} ^'m::{mod-type} and Q::'a ^'n::{mod-type} ^'n::{mod-type}
assumes invertible-P: invertible P
and invertible-Q: invertible Q
shows rank (P**A**Q) = rank A
⟨proof⟩

lemma invertible-matrix-mult-left-rank':
fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type} and P::'a ^'m::{mod-type} ^'m::{mod-type}
assumes invertible-P: invertible P and B-eq-PA: B=P**A
shows rank B = rank A
⟨proof⟩

lemma invertible-matrix-mult-right-rank':
fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
and Q::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
assumes invertible-Q: invertible Q and B-eq-PA: B=A**Q
shows rank B = rank A ⟨proof⟩

lemma invertible-matrices-rank':
fixes A::'a::{field} ^'n::{mod-type} ^'m::{mod-type}
and P::'a ^'m::{mod-type} ^'m::{mod-type} and Q::'a ^'n::{mod-type} ^'n::{mod-type}
assumes invertible-P: invertible P and invertible-Q: invertible Q and B-eq-PA:
B = P**A**Q
shows rank B = rank A ⟨proof⟩

```

### 7.3 Definition and properties of the set of a vector

Some definitions:

In the file *Generalizations.thy* there exists the following definition: *cart-basis* = {axis i 1 |i. i ∈ UNIV}.

*cart-basis* returns a set which is a basis and it works properly in my development. But in this file, I need to know the order of the elements of the basis, because is very important for the coordinates of a vector and the matrices of change of bases. So, I have defined a new *cart-basis'*, which will be a matrix. The columns of this matrix are the elements of the basis.

```

definition set-of-vector :: 'a ^'n ⇒ 'a set
where set-of-vector A = {A $ i |i. i ∈ UNIV}

```

```

definition cart-basis' :: 'a::{field} ^n ^n
where cart-basis' = ( $\chi i. \text{axis } i 1$ )

lemma cart-basis-eq-set-of-vector-cart-basis':
  cart-basis = set-of-vector (cart-basis')
   $\langle \text{proof} \rangle$ 

lemma basis-image-linear:
  fixes f::'b::{field} ^n => 'b ^n
  assumes invertible-lf: invertible-lf ((s)) ((s)) f
  and basis-X: is-basis (set-of-vector X)
  shows is-basis (f` (set-of-vector X))
   $\langle \text{proof} \rangle$ 

```

Properties about  $\text{cart-basis}' = (\chi i. \text{axis } i 1)$

```

lemma set-of-vector-cart-basis':
  shows (set-of-vector cart-basis') = {axis i 1 :: 'a::{field} ^n | i. i ∈ (UNIV :: 'n
  set)}
   $\langle \text{proof} \rangle$ 

```

```
lemma cart-basis'-i: cart-basis' $ i = axis i 1  $\langle \text{proof} \rangle$ 
```

```
lemma finite-set-of-vector[intro,simp]: finite (set-of-vector X)
   $\langle \text{proof} \rangle$ 
```

```
lemma is-basis-cart-basis': is-basis (set-of-vector cart-basis')
   $\langle \text{proof} \rangle$ 
```

```
lemma basis-expansion-cart-basis':sum (λi. x$i *s cart-basis' $ i) UNIV = x
   $\langle \text{proof} \rangle$ 
```

```
lemma basis-expansion-unique:
  sum (λi. f i *s axis (i::'n::finite) 1) UNIV = (x::('a::comm-ring-1) ^n)  $\longleftrightarrow$ 
  ( $\forall i. f i = x\$i$ )
   $\langle \text{proof} \rangle$ 
```

```
lemma basis-expansion-cart-basis'-unique: sum (λi. f (cart-basis' $ i) *s cart-basis'
  $ i) UNIV = x  $\longleftrightarrow$  ( $\forall i. f (cart-basis' $ i) = x\$i$ )
   $\langle \text{proof} \rangle$ 
```

```
lemma basis-expansion-cart-basis'-unique': sum (λi. f i *s cart-basis' $ i) UNIV
= x  $\longleftrightarrow$  ( $\forall i. f i = x\$i$ )
   $\langle \text{proof} \rangle$ 
```

Properties of  $\text{is-basis } ?S \equiv \text{vec.independent } ?S \wedge \text{vec.span } ?S = \text{UNIV}$ .

```
lemma sum-basis-eq:
  fixes X::'a::{field} ^n ^n
  assumes is-basis:is-basis (set-of-vector X)
```

**shows**  $\text{sum}(\lambda x. f x * s x)$  (*set-of-vector*  $X$ ) =  $\text{sum}(\lambda i. f(X\$i) * s(X\$i))$   $\text{UNIV}$   
 $\langle \text{proof} \rangle$

**corollary** *sum-basis-eq2*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *is-basis*: *is-basis* (*set-of-vector*  $X$ )

**shows**  $\text{sum}(\lambda x. f x * s x)$  (*set-of-vector*  $X$ ) =  $\text{sum}(\lambda i. (f \circ (\$) X) i * s(X\$i))$

$\text{UNIV}$

$\langle \text{proof} \rangle$

**lemma** *inj-op-nth*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *is-basis*: *is-basis* (*set-of-vector*  $X$ )

**shows**  $\text{inj}((\$) X)$

$\langle \text{proof} \rangle$

**lemma** *basis-UNIV*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *is-basis*: *is-basis* (*set-of-vector*  $X$ )

**shows**  $\text{UNIV} = \{x. \exists g. (\sum_{i \in \text{UNIV}} g i * s X\$i) = x\}$

$\langle \text{proof} \rangle$

**lemma** *scalars-zero-if-basis*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *is-basis*: *is-basis* (*set-of-vector*  $X$ ) **and** *sum*:  $(\sum_{i \in (\text{UNIV}::'n \text{ set})} f i * s X\$i) = 0$

**shows**  $\forall i \in (\text{UNIV}::'n \text{ set}). f i = 0$

$\langle \text{proof} \rangle$

**lemma** *basis-combination-unique*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *basis-X*: *is-basis* (*set-of-vector*  $X$ ) **and** *sum-eq*:  $(\sum_{i \in \text{UNIV}} g i * s X\$i) = (\sum_{i \in \text{UNIV}} f i * s X\$i)$

**shows**  $f = g$

$\langle \text{proof} \rangle$

## 7.4 Coordinates of a vector

Definition and properties of the coordinates of a vector (in terms of a particular ordered basis).

**definition** *coord* ::  $'a::\{\text{field}\}^n^n \Rightarrow 'a::\{\text{field}\}^n \Rightarrow 'a::\{\text{field}\}^n$

**where**  $\text{coord } X v = (\chi i. (\text{THE } f. v = \text{sum}(\lambda x. f x * s X\$x) \text{ UNIV}) i)$

$\text{coord } X v$  are the coordinates of vector  $v$  with respect to the basis  $X$

**lemma** *bij-coord*:

**fixes**  $X::'a::\{\text{field}\}^n^n$

**assumes** *basis-X*: *is-basis* (*set-of-vector*  $X$ )

**shows**  $\text{bij}(\text{coord } X)$

$\langle proof \rangle$

```
lemma linear-coord:
  fixes X::'a::{field} ^n ^n
  assumes basis-X: is-basis (set-of-vector X)
  shows linear ((*s)) ((*s)) (coord X)
⟨proof⟩
```

```
lemma coord-eq:
  assumes basis-X:is-basis (set-of-vector X)
  and coord-eq: coord X v = coord X w
  shows v = w
⟨proof⟩
```

## 7.5 Matrix of change of basis and coordinate matrix of a linear map

Definitions of matrix of change of basis and matrix of a linear transformation with respect to two bases:

```
definition matrix-change-of-basis :: 'a::{field} ^n ^n ⇒ 'a ^n ^n ⇒ 'a ^n ^n
  where matrix-change-of-basis X Y = (χ i j. (coord Y (X\$j)) \$ i)
```

There exists in the library the definition  $matrix ?f = (\chi i j. ?f (axis j 1) \$ i)$ , which is the coordinate matrix of a linear map with respect to the standard bases. Now we generalise that concept to the coordinate matrix of a linear map with respect to any two bases.

```
definition matrix' :: 'a::{field} ^n ^n ⇒ 'a ^m ^m ⇒ ('a ^n => 'a ^m) ⇒ 'a ^n ^m
  where matrix' X Y f = (χ i j. (coord Y (f(X\$j))) \$ i)
```

Properties of  $matrix' ?X ?Y ?f = (\chi i j. coord ?Y (?f (?X \$ j)) \$ i)$

```
lemma matrix'-eq-matrix:
  defines cart-basis-Rn: cart-basis-Rn == (cart-basis')::'a::{field} ^n ^n
  and cart-basis-Rm:cart-basis-Rm == (cart-basis')::'a ^m ^m
  shows matrix' (cart-basis-Rn) (cart-basis-Rm) f = matrix f
⟨proof⟩
```

```
lemma matrix':
  assumes basis-X: is-basis (set-of-vector X) and basis-Y: is-basis (set-of-vector Y)
  shows f (X\$i) = sum (λj. (matrix' X Y f) \$ j \$ i *s (Y\$j)) UNIV
⟨proof⟩
```

```
corollary matrix'2:
  assumes basis-X: is-basis (set-of-vector X) and basis-Y: is-basis (set-of-vector Y)
  and eq-f: ∀ i. f (X\$i) = sum (λj. A \$ j \$ i *s (Y\$j)) UNIV
```

**shows**  $\text{matrix}' X Y f = A$   
 $\langle \text{proof} \rangle$

This is the theorem 2.14 in the book "Advanced Linear Algebra" by Steven Roman.

**lemma**  $\text{coord-matrix}'$ :  
**fixes**  $X::'a::\{\text{field}\}^n^n$  **and**  $Y::'a^m^m$   
**assumes**  $\text{basis-}X$ : *is-basis* (*set-of-vector*  $X$ ) **and**  $\text{basis-}Y$ : *is-basis* (*set-of-vector*  $Y$ )  
**and**  $\text{linear-}f$ : *linear*  $((*)s) ((*)s) f$   
**shows**  $\text{coord } Y (f v) = (\text{matrix}' X Y f) *v (\text{coord } X v)$   
 $\langle \text{proof} \rangle$

This is the second part of the theorem 2.15 in the book "Advanced Linear Algebra" by Steven Roman.

**lemma**  $\text{matrix}'\text{-compose}$ :  
**fixes**  $X::'a::\{\text{field}\}^n^n$  **and**  $Y::'a^m^m$  **and**  $Z::'a^p^p$   
**assumes**  $\text{basis-}X$ : *is-basis* (*set-of-vector*  $X$ ) **and**  $\text{basis-}Y$ : *is-basis* (*set-of-vector*  $Y$ ) **and**  $\text{basis-}Z$ : *is-basis* (*set-of-vector*  $Z$ )  
**and**  $\text{linear-}f$ : *linear*  $((*)s) ((*)s) f$  **and**  $\text{linear-}g$ : *linear*  $((*)s) ((*)s) g$   
**shows**  $\text{matrix}' X Z (g \circ f) = (\text{matrix}' Y Z g) ** (\text{matrix}' X Y f)$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{exists-linear-eq-matrix}'$ :  
**fixes**  $A::'a::\{\text{field}\}^m^n$  **and**  $X::'a^m^m$  **and**  $Y::'a^n^n$   
**assumes**  $\text{basis-}X$ : *is-basis* (*set-of-vector*  $X$ ) **and**  $\text{basis-}Y$ : *is-basis* (*set-of-vector*  $Y$ )  
**shows**  $\exists f. \text{matrix}' X Y f = A \wedge \text{linear } ((*)s) ((*)s) f$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{matrix}'\text{-surj}$ :  
**assumes**  $\text{basis-}X$ : *is-basis* (*set-of-vector*  $X$ ) **and**  $\text{basis-}Y$ : *is-basis* (*set-of-vector*  $Y$ )  
**shows**  $\text{surj } (\text{matrix}' X Y)$   
 $\langle \text{proof} \rangle$

Properties of  $\text{matrix-change-of-basis } ?X ?Y = (\chi i j. \text{coord } ?Y (?X \$ j) \$ i)$ .

This is the first part of the theorem 2.12 in the book "Advanced Linear Algebra" by Steven Roman.

**lemma**  $\text{matrix-change-of-basis-works}$ :  
**fixes**  $X::'a::\{\text{field}\}^n^n$  **and**  $Y::'a^n^n$   
**assumes**  $\text{basis-}X$ : *is-basis* (*set-of-vector*  $X$ )  
**and**  $\text{basis-}Y$ : *is-basis* (*set-of-vector*  $Y$ )  
**shows**  $(\text{matrix-change-of-basis } X Y) *v (\text{coord } X v) = (\text{coord } Y v)$

$\langle proof \rangle$

```

lemma matrix-change-of-basis-mat-1:
  fixes X::'a::{field} ^n ^n
  assumes basis-X: is-basis (set-of-vector X)
  shows matrix-change-of-basis X X = mat 1
  ⟨proof⟩

```

Relationships between  $matrix' ?X ?Y ?f = (\chi i j. coord ?Y (?f (?X \$ j)) \$ i)$  and  $matrix-change-of-basis ?X ?Y = (\chi i j. coord ?Y (?X \$ j) \$ i)$ . This is the theorem 2.16 in the book "Advanced Linear Algebra" by Steven Roman.

```

lemma matrix'-matrix-change-of-basis:
  fixes B::'a::{field} ^n ^n and B'::'a ^n ^n and C::'a ^m ^m and C'::'a ^m ^m
  assumes basis-B: is-basis (set-of-vector B) and basis-B': is-basis (set-of-vector B')
    and basis-C: is-basis (set-of-vector C) and basis-C': is-basis (set-of-vector C')
    and linear-f: linear ((*)s) ((*)s) f
  shows matrix' B' C' f = matrix-change-of-basis C C' ** matrix' B C f ** matrix-change-of-basis B' B
  ⟨proof⟩

```

```

lemma matrix'-id-eq-matrix-change-of-basis:
  fixes X::'a::{field} ^n ^n and Y::'a ^n ^n
  assumes basis-X: is-basis (set-of-vector X) and basis-Y: is-basis (set-of-vector Y)
  shows matrix' X Y (id) = matrix-change-of-basis X Y
  ⟨proof⟩

```

Relationships among  $invertible-lf ?s1.0 ?s2.0 ?f \equiv linear ?s1.0 ?s2.0 ?f \wedge invertible-lf-axioms ?f$ ,  $matrix-change-of-basis ?X ?Y = (\chi i j. coord ?Y (?X \$ j) \$ i)$ ,  $matrix' ?X ?Y ?f = (\chi i j. coord ?Y (?f (?X \$ j)) \$ i)$  and  $invertible ?A = (\exists A'. ?A ** A' = mat 1 \wedge A' ** ?A = mat 1)$ .

This is the second part of the theorem 2.12 in the book "Advanced Linear Algebra" by Steven Roman.

```

lemma matrix-inv-matrix-change-of-basis:
  fixes X::'a::{field} ^n ^n and Y::'a ^n ^n
  assumes basis-X: is-basis (set-of-vector X) and basis-Y: is-basis (set-of-vector Y)
  shows matrix-change-of-basis Y X = matrix-inv (matrix-change-of-basis X Y)
  ⟨proof⟩

```

The following four lemmas are the proof of the theorem 2.13 in the book "Advanced Linear Algebra" by Steven Roman.

**corollary** invertible-matrix-change-of-basis:

```

fixes  $X::'a::\{field\}^n \times^n n$  and  $Y::'a \times^n n$ 
assumes basis- $X$ : is-basis (set-of-vector  $X$ ) and basis- $Y$ : is-basis (set-of-vector  $Y$ )
shows invertible (matrix-change-of-basis  $X Y$ )
⟨proof⟩

lemma invertible-lf-imp-invertible-matrix':
fixes  $f::'a::\{field\}^n \times^n b \Rightarrow 'a \times^n b$ 
assumes invertible-lf ((*) $s$ ) ((*) $s$ )  $f$  and basis- $X$ : is-basis (set-of-vector  $X$ ) and basis- $Y$ : is-basis (set-of-vector  $Y$ )
shows invertible (matrix'  $X Y f$ )
⟨proof⟩

lemma invertible-matrix'-imp-invertible-lf:
fixes  $f::'a::\{field\}^n \times^n b \Rightarrow 'a \times^n b$ 
assumes invertible (matrix'  $X Y f$ ) and basis- $X$ : is-basis (set-of-vector  $X$ )
and linear-f: linear ((*) $s$ ) ((*) $s$ )  $f$  and basis- $Y$ : is-basis (set-of-vector  $Y$ )
shows invertible-lf ((*) $s$ ) ((*) $s$ )  $f$ 
⟨proof⟩

lemma invertible-matrix-is-change-of-basis:
assumes invertible- $P$ : invertible  $P$  and basis- $X$ : is-basis (set-of-vector  $X$ )
shows  $\exists! Y$ . matrix-change-of-basis  $Y X = P \wedge$  is-basis (set-of-vector  $Y$ )
⟨proof⟩

```

## 7.6 Equivalent Matrices

Next definition follows the one presented in Modern Algebra by Seth Warner.

**definition** equivalent-matrices  $A B = (\exists P Q. \text{invertible } P \wedge \text{invertible } Q \wedge B = (\text{matrix-inv } P) * A * Q)$

```

lemma exists-basis:  $\exists X::'a::\{field\}^n \times^n n$ . is-basis (set-of-vector  $X$ )
⟨proof⟩

lemma equivalent-implies-exist-matrix':
assumes equivalent: equivalent-matrices  $A B$ 
shows  $\exists X Y X' Y' f::'a::\{field\}^n \times^n m$ .
linear ((*) $s$ ) ((*) $s$ )  $f \wedge$  matrix'  $X Y f = A \wedge$  matrix'  $X' Y' f = B \wedge$  is-basis (set-of-vector  $X$ )
 $\wedge$  is-basis (set-of-vector  $Y$ )  $\wedge$  is-basis (set-of-vector  $X'$ )  $\wedge$  is-basis (set-of-vector  $Y'$ )
⟨proof⟩

```

```

lemma exist-matrix'-implies-equivalent:
assumes  $A: \text{matrix}' X Y f = A$ 
and  $B: \text{matrix}' X' Y' f = B$ 
and  $X: \text{is-basis}(\text{set-of-vector } X)$ 
and  $Y: \text{is-basis}(\text{set-of-vector } Y)$ 

```

```

and  $X'$ : is-basis (set-of-vector  $X'$ )
and  $Y'$ : is-basis (set-of-vector  $Y'$ )
and linear-f: linear ((*) $s$ ) ((*) $s$ )  $f$ 
shows equivalent-matrices  $A$   $B$ 
⟨proof⟩

```

This is the proof of the theorem 2.18 in the book "Advanced Linear Algebra" by Steven Roman.

```

corollary equivalent-iff-exist-matrix':
shows equivalent-matrices  $A$   $B$   $\longleftrightarrow$  ( $\exists X Y X' Y' f::'a::\{field\} \wedge n \Rightarrow 'a \wedge m$ .
linear ((*) $s$ ) ((*) $s$ )  $f \wedge \text{matrix}' X Y f = A \wedge \text{matrix}' X' Y' f = B$ 
 $\wedge \text{is-basis}(\text{set-of-vector } X) \wedge \text{is-basis}(\text{set-of-vector } Y)$ 
 $\wedge \text{is-basis}(\text{set-of-vector } X') \wedge \text{is-basis}(\text{set-of-vector } Y')$ )
⟨proof⟩

```

## 7.7 Similar matrices

```

definition similar-matrices ::  $'a::\{\text{semiring-1}\} \wedge n \Rightarrow 'a::\{\text{semiring-1}\} \wedge n \Rightarrow \text{bool}$ 
where similar-matrices  $A$   $B$  = ( $\exists P$ . invertible  $P \wedge B = (\text{matrix-inv } P) * * A * * P$ )

```

```

lemma similar-implies-exist-matrix':
fixes  $A B::'a::\{\text{field}\} \wedge n \wedge n$ 
assumes similar: similar-matrices  $A$   $B$ 
shows  $\exists X Y f$ . linear ((*) $s$ ) ((*) $s$ )  $f \wedge \text{matrix}' X X f = A \wedge \text{matrix}' Y Y f = B$ 
 $\wedge \text{is-basis}(\text{set-of-vector } X) \wedge \text{is-basis}(\text{set-of-vector } Y)$ 
⟨proof⟩

```

```

lemma exist-matrix'-implies-similar:
fixes  $A B::'a::\{\text{field}\} \wedge n \wedge n$ 
assumes linear-f: linear ((*) $s$ ) ((*) $s$ )  $f$  and  $A$ : matrix'  $X X f = A$  and  $B$ : matrix'  $Y Y f = B$ 
and  $X$ : is-basis (set-of-vector  $X$ ) and  $Y$ : is-basis (set-of-vector  $Y$ )
shows similar-matrices  $A$   $B$ 
⟨proof⟩

```

This is the proof of the theorem 2.19 in the book "Advanced Linear Algebra" by Steven Roman.

```

corollary similar-iff-exist-matrix':
fixes  $A B::'a::\{\text{field}\} \wedge n \wedge n$ 
shows similar-matrices  $A$   $B$   $\longleftrightarrow$  ( $\exists X Y f$ . linear ((*) $s$ ) ((*) $s$ )  $f \wedge \text{matrix}' X X f = A$ 
 $\wedge \text{matrix}' Y Y f = B \wedge \text{is-basis}(\text{set-of-vector } X) \wedge \text{is-basis}(\text{set-of-vector } Y))$ 
⟨proof⟩

```

**end**

## 8 Obtaining explicitly the invertible matrix which transforms a matrix to its reduced row echelon form

```
theory Gauss-Jordan-PA
imports
  Gauss-Jordan
  Rank-Nullity-Theorem.Miscellaneous
  Linear-Maps
begin
```

### 8.1 Definitions

The following algorithm is similar to *Gauss-Jordan*, but in this case we will also return the P matrix which makes *Gauss-Jordan*  $A = P \star\star A$ . If A is invertible, this matrix P will be the inverse of it.

```
definition Gauss-Jordan-in-ij-PA :: (('a::semiring-1, inverse, one, uminus} ^'rows::{finite,
ord} ^'rows::{finite, ord}) × ('a ^'cols ^'rows::{finite, ord})) => 'rows=>'cols
  =>((('a ^'rows::{finite, ord} ^'rows::{finite, ord}) × ('a ^'cols ^'rows::{finite, ord})))
```

**where** Gauss-Jordan-in-ij-PA  $A' i j = (\text{let } P = \text{fst } A'; A = \text{snd } A';$

$n = (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n);$

$\text{interchange-}A = (\text{interchange-rows } A i n);$

$\text{interchange-}P = (\text{interchange-rows } P i n);$

$P' = \text{mult-row interchange-}P i (1 / \text{interchange-}A \$ i \$ j)$   
in

$(\text{vec-lambda}(\% s. \text{if } s = i \text{ then } P' \$ s \text{ else } (\text{row-add}$   
 $P' s i (-(\text{interchange-}A \$ s \$ j)) \$ s), \text{Gauss-Jordan-in-ij } A i j))$

**definition** Gauss-Jordan-column-k-PA

**where** Gauss-Jordan-column-k-PA  $A' k =$

$(\text{let } P = \text{fst } A';$

$i = \text{fst } (\text{snd } A');$

$A = \text{snd } (\text{snd } A');$

$\text{from-nat-}i = \text{from-nat } i;$

$\text{from-nat-}k = \text{from-nat } k$

$\text{in}$

$\text{if } (\forall m \geq \text{from-nat-}i. A \$ m \$ \text{from-nat-}k = 0) \vee i = \text{nrows } A \text{ then } (P, i, A)$

$\text{else } (\text{let } \text{Gauss} = \text{Gauss-Jordan-in-ij-PA } (P, A) (\text{from-nat-}i) (\text{from-nat-}k)$

$\text{in } (\text{fst } \text{Gauss}, i + 1, \text{snd } \text{Gauss}))$

**definition** Gauss-Jordan-upt-k-PA  $A k = (\text{let } \text{foldl} = (\text{foldl } \text{Gauss-Jordan-column-k-PA}$   
 $(\text{mat } 1, 0, A) [0..<\text{Suc } k]) \text{ in } (\text{fst } \text{foldl}, \text{snd } (\text{snd } \text{foldl})))$

**definition** Gauss-Jordan-PA  $A = \text{Gauss-Jordan-upt-k-PA } A (\text{ncols } A - 1)$

## 8.2 Proofs

### 8.2.1 Properties about Gauss-Jordan-in-ij-PA

The following lemmas are very important in order to improve the efficiency of the code

We define the following function to obtain an efficient code for *Gauss-Jordan-in-ij-PA*

**definition** *Gauss-Jordan-wrapper i j A B = vec-lambda(%s. if s=i then A \$ s else (row-add A s i (-(B\$s\$j))) \$ s)*

**lemma** *Gauss-Jordan-wrapper-code[code abstract]:*

*vec-nth (Gauss-Jordan-wrapper i j A B) = (%s. if s=i then A \$ s else (row-add A s i (-(B\$s\$j))) \$ s)*

*{proof}*

**lemma** *Gauss-Jordan-in-ij-PA-def'[code]:*

*Gauss-Jordan-in-ij-PA A' i j = (let P=fst A'; A=snd A';*

*n = (LEAST n. A \$ n \$ j ≠ 0 ∧ i ≤ n);*

*interchange-A = (interchange-rows A i n);*

*A' = mult-row interchange-A i (1 / interchange-A\$i\$j);*

*interchange-P = (interchange-rows P i n);*

*P' = mult-row interchange-P i (1 / interchange-A\$i\$j)  
in*

*(Gauss-Jordan-wrapper i j P' interchange-A,*

*Gauss-Jordan-wrapper i j A' interchange-A))*

*{proof}*

The second component is equal to *Gauss-Jordan-in-ij*

**lemma** *snd-Gauss-Jordan-in-ij-PA-eq[code-unfold]: snd (Gauss-Jordan-in-ij-PA (P,A)  
i j) = Gauss-Jordan-in-ij A i j*

*{proof}*

**lemma** *fst-Gauss-Jordan-in-ij-PA:*

**fixes** *A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}*

**assumes** *PB-A: P \*\* B = A*

**shows** *fst (Gauss-Jordan-in-ij-PA (P,A) i j) \*\* B = snd (Gauss-Jordan-in-ij-PA  
(P,A) i j)*

*{proof}*

### 8.2.2 Properties about Gauss-Jordan-column-k-PA

**lemma** *fst-Gauss-Jordan-column-k:*

**assumes** *i ≤ nrows A*

**shows** *fst (Gauss-Jordan-column-k (i, A) k) ≤ nrows A*

*{proof}*

**lemma** *fst-Gauss-Jordan-column-k-PA:*

```

fixes A::'a::{field}  $\wedge$  cols::{mod-type}  $\wedge$  rows::{mod-type}
assumes PB-A:  $P \star\star B = A$ 
shows fst (Gauss-Jordan-column-k-PA (P,i,A) k)  $\star\star B = snd (snd (Gauss-Jordan-column-k-PA (P,i,A) k))$ 
 $\langle proof \rangle$ 

lemma snd-snd-Gauss-Jordan-column-k-PA-eq:
shows snd (snd (Gauss-Jordan-column-k-PA (P,i,A) k)) = snd (Gauss-Jordan-column-k (i,A) k)
 $\langle proof \rangle$ 

lemma fst-snd-Gauss-Jordan-column-k-PA-eq:
shows fst (snd (Gauss-Jordan-column-k-PA (P,i,A) k)) = fst (Gauss-Jordan-column-k (i,A) k)
 $\langle proof \rangle$ 

```

### 8.2.3 Properties about Gauss-Jordan-upt-k-PA

```

lemma fst-Gauss-Jordan-upt-k-PA:
fixes A::'a::{field}  $\wedge$  cols::{mod-type}  $\wedge$  rows::{mod-type}
shows fst (Gauss-Jordan-upt-k-PA A k)  $\star\star A = snd (Gauss-Jordan-upt-k-PA A k)$ 
 $\langle proof \rangle$ 

lemma snd-foldl-Gauss-Jordan-column-k-eq:
shows snd (foldl Gauss-Jordan-column-k-PA (mat 1, 0, A) [0..<k]) = foldl Gauss-Jordan-column-k (0, A) [0..<k]
 $\langle proof \rangle$ 

lemma snd-Gauss-Jordan-upt-k-PA:
shows snd (Gauss-Jordan-upt-k-PA A k) = (Gauss-Jordan-upt-k A k)
 $\langle proof \rangle$ 

```

### 8.2.4 Properties about Gauss-Jordan-PA

```

lemma fst-Gauss-Jordan-PA:
fixes A::'a::{field}  $\wedge$  cols::{mod-type}  $\wedge$  rows::{mod-type}
shows fst (Gauss-Jordan-PA A)  $\star\star A = snd (Gauss-Jordan-PA A)$ 
 $\langle proof \rangle$ 

lemma Gauss-Jordan-PA-eq:
shows snd (Gauss-Jordan-PA A) = (Gauss-Jordan A)
 $\langle proof \rangle$ 

```

### 8.2.5 Proving that the transformation has been carried out by means of elementary operations

This function is very similar to *row-add-iterate* one. It allows us to prove that  $fst (Gauss-Jordan-PA A)$  is an invertible matrix. Concretely, it has been

defined to demonstrate that  $\text{fst}$  (*Gauss-Jordan-PA*  $A$ ) has been obtained by means of elementary operations applied to the identity matrix

```
fun row-add-iterate-PA :: (('a:{semiring-1, uminus} ^'m:{mod-type} ^'m:{mod-type})
  × ('a ^'n ^'m:{mod-type})) => nat => 'm => 'n =>
  (((('a ^'m:{mod-type} ^'m:{mod-type}) × ('a ^'n ^'m:{mod-type})))
where row-add-iterate-PA (P,A) 0 i j = (if i=0 then (P,A) else (row-add P 0
  i (-A $ 0 $ j), row-add A 0 i (-A $ 0 $ j)))
  | row-add-iterate-PA (P,A) (Suc n) i j = (if (Suc n = to-nat i) then
  row-add-iterate-PA (P,A) n i j
  else row-add-iterate-PA ((row-add P (from-nat (Suc n)) i (- A $ (from-nat (Suc
  n)) $ j)), (row-add A (from-nat (Suc n)) i (- A $ (from-nat (Suc
  n)) $ j))) n i j)
```

**lemma** fst-row-add-iterate-PA-preserves-greater-than-n:

```
assumes n: n < nrows A
and a: to-nat a > n
shows fst (row-add-iterate-PA (P,A) n i j) $ a $ b = P $ a $ b
⟨proof⟩
```

**lemma** snd-row-add-iterate-PA-eq-row-add-iterate:

```
shows snd (row-add-iterate-PA (P,A) n i j) = row-add-iterate A n i j
⟨proof⟩
```

**lemma** row-add-iterate-PA-preserves-pivot-row:

```
assumes n: n < nrows A
and a: to-nat i ≤ n
shows fst (row-add-iterate-PA (P,A) n i j) $ i $ b = P $ i $ b
⟨proof⟩
```

**lemma** fst-row-add-iterate-PA-eq-row-add:

```
fixes A::'a:{ring-1} ^'n ^'m:{mod-type}
assumes a-not-i: a ≠ i
and n: n < nrows A
and to-nat a ≤ n
shows fst (row-add-iterate-PA (P,A) n i j) $ a $ b = (row-add P a i (- A $ a
$ j)) $ a $ b
⟨proof⟩
```

**lemma** fst-row-add-iterate-PA-eq-fst-Gauss-Jordan-in-ij-PA:

```
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
and i::'rows and j::'cols
and P::'a:{field} ^'rows:{mod-type} ^'rows:{mod-type}
defines A': A' == mult-row (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i
```

```

 $\leq n)) i (1 / (\text{interchange-rows } A i (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)) \$ i \$ j)$ 
defines  $P': P' == \text{mult-row} (\text{interchange-rows } P i (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)) i (1 / (\text{interchange-rows } A i (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)) \$ i \$ j)$ 
shows  $\text{fst} (\text{row-add-iterate-PA} (P', A') (\text{nrows } A - 1) i j) = \text{fst} (\text{Gauss-Jordan-in-ij-PA} (P, A) i j)$ 
(proof)

```

```

lemma invertible-fst-row-add-iterate-PA:
  fixes  $A :: 'a :: \{\text{ring-1}\} \wedge 'n \wedge m :: \{\text{mod-type}\}$ 
  assumes  $n : n < \text{nrows } A$ 
  and  $\text{inv-}P : \text{invertible } P$ 
  shows  $\text{invertible} (\text{fst} (\text{row-add-iterate-PA} (P, A) n i j))$ 
(proof)

```

```

lemma invertible-fst-Gauss-Jordan-in-ij-PA:
  fixes  $A :: 'a :: \{\text{field}\} \wedge 'n :: \{\text{mod-type}\} \wedge m :: \{\text{mod-type}\}$ 
  assumes  $\text{inv-}P : \text{invertible } P$ 
  and  $\text{not-all-zero} : \neg (\forall m \geq i. A \$ m \$ j = 0)$ 
  shows  $\text{invertible} (\text{fst} (\text{Gauss-Jordan-in-ij-PA} (P, A) i j))$ 
(proof)

```

```

lemma invertible-fst-Gauss-Jordan-column-k-PA:
  fixes  $A :: 'a :: \{\text{field}\} \wedge 'n :: \{\text{mod-type}\} \wedge m :: \{\text{mod-type}\}$ 
  assumes  $\text{inv-}P : \text{invertible } P$ 
  shows  $\text{invertible} (\text{fst} (\text{Gauss-Jordan-column-k-PA} (P, i, A) k))$ 
(proof)

```

```

lemma invertible-fst-Gauss-Jordan-upk-PA:
  fixes  $A :: 'a :: \{\text{field}\} \wedge 'n :: \{\text{mod-type}\} \wedge m :: \{\text{mod-type}\}$ 
  shows  $\text{invertible} (\text{fst} (\text{Gauss-Jordan-upk-PA} A k))$ 
(proof)

```

```

lemma invertible-fst-Gauss-Jordan-PA:
  fixes  $A :: 'a :: \{\text{field}\} \wedge 'n :: \{\text{mod-type}\} \wedge m :: \{\text{mod-type}\}$ 
  shows  $\text{invertible} (\text{fst} (\text{Gauss-Jordan-PA} A))$ 
(proof)

```

**definition**  $P\text{-Gauss-Jordan } A = \text{fst} (\text{Gauss-Jordan-PA} A)$

**end**

## 9 Computing determinants of matrices using the Gauss Jordan algorithm

**theory** Determinants2

```

imports
  Gauss-Jordan-PA
begin

```

## 9.1 Some previous properties

### 9.1.1 Relationships between determinants and elementary row operations

**lemma** *det-interchange-rows*:  
**shows**  $\det(\text{interchange-rows } A \ i \ j) = \text{of-int}(\text{if } i = j \text{ then } 1 \text{ else } -1) * \det A$   
*(proof)*

**corollary** *det-interchange-different-rows*:  
**assumes** *i-not-j*:  $i \neq j$   
**shows**  $\det(\text{interchange-rows } A \ i \ j) = - \det A$  *(proof)*

**corollary** *det-interchange-same-rows*:  
**assumes** *i-eq-j*:  $i = j$   
**shows**  $\det(\text{interchange-rows } A \ i \ j) = \det A$  *(proof)*

**lemma** *det-mult-row*:  
**shows**  $\det(\text{mult-row } A \ a \ k) = k * \det A$   
*(proof)*

**lemma** *det-row-add'*:  
**assumes** *i-not-j*:  $i \neq j$   
**shows**  $\det(\text{row-add } A \ i \ j \ q) = \det A$   
*(proof)*

### 9.1.2 Relationships between determinants and elementary column operations

**lemma** *det-interchange-columns*:  
**shows**  $\det(\text{interchange-columns } A \ i \ j) = \text{of-int}(\text{if } i = j \text{ then } 1 \text{ else } -1) * \det A$   
*(proof)*

**corollary** *det-interchange-different-columns*:  
**assumes** *i-not-j*:  $i \neq j$   
**shows**  $\det(\text{interchange-columns } A \ i \ j) = - \det A$  *(proof)*

**corollary** *det-interchange-same-columns*:  
**assumes** *i-eq-j*:  $i = j$   
**shows**  $\det(\text{interchange-columns } A \ i \ j) = \det A$  *(proof)*

**lemma** *det-mult-columns*:  
**shows**  $\det(\text{mult-column } A \ a \ k) = k * \det A$   
*(proof)*

```

lemma det-column-add:
assumes i-not-j:  $i \neq j$ 
shows  $\det(\text{column-add } A \ i \ j \ q) = \det A$ 
⟨proof⟩

```

## 9.2 Proving that the determinant can be computed by means of the Gauss Jordan algorithm

### 9.2.1 Previous properties

```

lemma det-row-add-iterate-upt-n:
fixes A::'a::{comm-ring-1} ^'n::{mod-type} ^'n::{mod-type}
assumes n:  $n < \text{nrows } A$ 
shows  $\det(\text{row-add-iterate } A \ n \ i \ j) = \det A$ 
⟨proof⟩

```

```

corollary det-row-add-iterate:
fixes A::'a::{comm-ring-1} ^'n::{mod-type} ^'n::{mod-type}
shows  $\det(\text{row-add-iterate } A \ (\text{nrows } A - 1) \ i \ j) = \det A$ 
⟨proof⟩

```

```

lemma det-Gauss-Jordan-in-ij:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type} and i j::'n
defines A': A' == mult-row (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) i (1 / (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) $ i $ j)
shows  $\det(\text{Gauss-Jordan-in-ij } A \ i \ j) = \det A'$ 
⟨proof⟩

```

```

lemma det-Gauss-Jordan-in-ij-1:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type} and i j::'n
defines A': A' == mult-row (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) i (1 / (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) $ i $ j)
assumes i: (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n) = i
shows  $\det(\text{Gauss-Jordan-in-ij } A \ i \ j) = 1/(A \$ i \$ j) * \det A$ 
⟨proof⟩

```

```

lemma det-Gauss-Jordan-in-ij-2:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type} and i j::'n
defines A': A' == mult-row (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) i (1 / (interchange-rows A i (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n)) $ i $ j)
assumes i: (LEAST n. A $ n $ j ≠ 0 ∧ i ≤ n) ≠ i
shows  $\det(\text{Gauss-Jordan-in-ij } A \ i \ j) = -1/(A \$ (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n) \$ j) * \det A$ 
⟨proof⟩

```

### 9.2.2 Definitions

The following definitions allow the computation of the determinant of a matrix using the Gauss-Jordan algorithm. In the first component the determinant of each transformation is accumulated and the second component contains the matrix transformed into a reduced row echelon form matrix

**definition** *Gauss-Jordan-in-ij-det-P* :: 'a::{semiring-1, inverse, one, uminus}  $\wedge$ 'm  $\wedge$ 'n::{finite, ord}  $\Rightarrow$  'n  $\Rightarrow$  'm  $\Rightarrow$  ('a  $\times$  ('a  $\wedge$ 'm  $\wedge$ 'n::{finite, ord}))

**where** *Gauss-Jordan-in-ij-det-P A i j* = (let  $n = (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)$  in (if  $i = n$  then  $1/(A \$ i \$ j)$  else  $-1/(A \$ n \$ j)$ , *Gauss-Jordan-in-ij A i j*))

**definition** *Gauss-Jordan-column-k-det-P* **where** *Gauss-Jordan-column-k-det-P A' k* =

(let *det-P* = *fst A'*;  $i = \text{fst}(\text{snd } A')$ ;  $A = \text{snd}(\text{snd } A')$ ; *from-nat-i* = *from-nat i*; *from-nat-k* = *from-nat k*

in if  $(\forall m \geq \text{from-nat-i}. A \$ m \$ \text{from-nat-k} = 0) \vee i = \text{nrows } A$  then (*det-P*,  $i, A$ )

else let *gauss* = *Gauss-Jordan-in-ij-det-P A (from-nat-i) (from-nat-k)* in (*fst gauss \* det-P, i + 1, snd gauss*))

**definition** *Gauss-Jordan-upk-det-P*

**where** *Gauss-Jordan-upk-det-P A k* = (let *foldl* = *foldl Gauss-Jordan-column-k-det-P (1, 0, A) [0..<Suc k]* in (*fst foldl, snd (snd foldl)*))

**definition** *Gauss-Jordan-det-P*

**where** *Gauss-Jordan-det-P A* = *Gauss-Jordan-upk-det-P A (ncols A - 1)*

### 9.2.3 Proofs

This is an equivalent definition created to achieve a more efficient computation.

**lemma** *Gauss-Jordan-in-ij-det-P-code[code]*:

**shows** *Gauss-Jordan-in-ij-det-P A i j* =

(let  $n = (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)$ ;

*interchange-A* = *interchange-rows A i n*;

$A' = \text{mult-row } \text{interchange-A } i (1 / \text{interchange-A } \$ i \$ j)$  in (if  $i = n$  then  $1/(A \$ i \$ j)$  else  $-1/(A \$ n \$ j)$ , *Gauss-Jordan-wrapper i j A' interchange-A*)  
*{proof}*

**lemma** *det-Gauss-Jordan-in-ij-det-P*:

**fixes** *A::'a::{field}  $\wedge$ 'n::{mod-type}  $\wedge$ 'n::{mod-type}* **and** *i j::'n*

**shows** (*fst (Gauss-Jordan-in-ij-det-P A i j)*) \* *det A* = *det (snd (Gauss-Jordan-in-ij-det-P A i j))*  
*{proof}*

**lemma** *det-Gauss-Jordan-column-k-det-P*:

```

fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes det: det-P * det B = det A
shows (fst (Gauss-Jordan-column-k-det-P (det-P,i,A) k)) * det B = det (snd (snd
(Gauss-Jordan-column-k-det-P (det-P,i,A) k)))
⟨proof⟩

lemma det-Gauss-Jordan-upt-k-det-P:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows (fst (Gauss-Jordan-upt-k-det-P A k)) * det A = det (snd (Gauss-Jordan-upt-k-det-P
A k))
⟨proof⟩

lemma det-Gauss-Jordan-det-P:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows (fst (Gauss-Jordan-det-P A)) * det A = det (snd (Gauss-Jordan-det-P A))
⟨proof⟩

definition upper-triangular-upt-k where upper-triangular-upt-k A k = (forall i j. j < i
& to-nat j < k --> A $ i $ j = 0)
definition upper-triangular where upper-triangular A = (forall i j. j < i --> A $ i $ j
= 0)

lemma upper-triangular-upt-imp-upper-triangular:
assumes upper-triangular-upt-k A (nrows A)
shows upper-triangular A
⟨proof⟩

lemma rref-imp-upper-triangular-upt:
fixes A::'a::{one, zero} ^n::{mod-type} ^n::{mod-type}
assumes reduced-row-echelon-form A
shows upper-triangular-upt-k A k
⟨proof⟩

lemma rref-imp-upper-triangular:
assumes reduced-row-echelon-form A
shows upper-triangular A
⟨proof⟩

lemma det-Gauss-Jordan[code-unfold]:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows det (Gauss-Jordan A) = prod (lambda i. (Gauss-Jordan A)$i$i) (UNIV: 'n set)
⟨proof⟩

lemma snd-Gauss-Jordan-in-ij-det-P-is-snd-Gauss-Jordan-in-ij-PA:

```

**shows**  $\text{snd}(\text{Gauss-Jordan-in-ij-det-P } A \ i \ j) = \text{snd}(\text{Gauss-Jordan-in-ij-PA } (P, A) \ i \ j)$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{snd-Gauss-Jordan-column-k-det-P-is-snd-Gauss-Jordan-column-k-PA}$ :  
**shows**  $\text{snd}(\text{Gauss-Jordan-column-k-det-P } (n, i, A) \ k) = \text{snd}(\text{Gauss-Jordan-column-k-PA } (P, i, A) \ k)$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{det-fst-row-add-iterate-PA}$ :  
**fixes**  $A :: 'a :: \{\text{comm-ring-1}\} \rightsquigarrow n :: \{\text{mod-type}\} \rightsquigarrow n :: \{\text{mod-type}\}$   
**assumes**  $n :: n < \text{nrows } A$   
**shows**  $\text{det}(\text{fst}(\text{row-add-iterate-PA } (P, A) \ n \ i \ j)) = \text{det } P$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{det-fst-Gauss-Jordan-in-ij-PA-eq-fst-Gauss-Jordan-in-ij-det-P}$ :  
**fixes**  $A :: 'a :: \{\text{field}\} \rightsquigarrow n :: \{\text{mod-type}\} \rightsquigarrow n :: \{\text{mod-type}\}$   
**shows**  $\text{fst}(\text{Gauss-Jordan-in-ij-det-P } A \ i \ j) * \text{det } P = \text{det}(\text{fst}(\text{Gauss-Jordan-in-ij-PA } (P, A) \ i \ j))$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{det-fst-Gauss-Jordan-column-k-PA-eq-fst-Gauss-Jordan-column-k-det-P}$ :  
**fixes**  $A :: 'a :: \{\text{field}\} \rightsquigarrow n :: \{\text{mod-type}\} \rightsquigarrow n :: \{\text{mod-type}\}$   
**shows**  $\text{fst}(\text{Gauss-Jordan-column-k-det-P } (\text{det } P, i, A) \ k) = \text{det}(\text{fst}(\text{Gauss-Jordan-column-k-PA } (P, i, A) \ k))$   
 $\langle \text{proof} \rangle$

**lemma**  $\text{fst-snd-Gauss-Jordan-column-k-det-P-eq-fst-snd-Gauss-Jordan-column-k-PA}$ :  
**shows**  $\text{fst}(\text{snd}(\text{Gauss-Jordan-column-k-det-P } (n, i, A) \ k)) = \text{fst}(\text{snd}(\text{Gauss-Jordan-column-k-PA } (P, i, A) \ k))$   
 $\langle \text{proof} \rangle$

The way of proving the following lemma is very similar to the demonstration of  $?k < \text{ncols } ?A \implies \text{reduced-row-echelon-form-upt-k } (\text{Gauss-Jordan-upk } ?A \ ?k) \ (\text{Suc } ?k)$

$?k < \text{ncols } ?A \implies \text{foldl Gauss-Jordan-column-k } (0, ?A) [0..<\text{Suc } ?k] =$   
 $(\text{if } \forall m. \text{is-zero-row-upk } m \ (\text{Suc } ?k) \ (\text{snd}(\text{foldl Gauss-Jordan-column-k } (0, ?A) [0..<\text{Suc } ?k])) \text{ then } 0 \text{ else } \text{mod-type-class.to-nat } (\text{GREATEST } n.$   
 $\neg \text{is-zero-row-upk } n \ (\text{Suc } ?k) \ (\text{snd}(\text{foldl Gauss-Jordan-column-k } (0, ?A) [0..<\text{Suc } ?k]))) + 1,$   
 $\text{snd}(\text{foldl Gauss-Jordan-column-k } (0, ?A) [0..<\text{Suc } ?k])).$

**lemma**  $\text{foldl-Gauss-Jordan-column-k-det-P}$ :

```

fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows det-fst-Gauss-Jordan-upt-k-PA-eq-fst-Gauss-Jordan-upt-k-det-P: fst (Gauss-Jordan-upt-k-det-P
A k) = det (fst (Gauss-Jordan-upt-k-PA A k))
and snd-Gauss-Jordan-upt-k-det-P-is-snd-Gauss-Jordan-upt-k-PA: snd (Gauss-Jordan-upt-k-det-P
A k) = snd (Gauss-Jordan-upt-k-PA A k)
and fst-snd-foldl-Gauss-det-P-PA: fst (snd (foldl Gauss-Jordan-column-k-det-P (1,
0, A) [0..<Suc k])) = fst (snd (foldl Gauss-Jordan-column-k-PA (mat 1, 0, A)
[0..<Suc k]))

⟨proof⟩

lemma snd-Gauss-Jordan-det-P-is-Gauss-Jordan:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows snd (Gauss-Jordan-det-P A) = (Gauss-Jordan A)
⟨proof⟩

lemma det-snd-Gauss-Jordan-det-P[code-unfold]:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows det (snd (Gauss-Jordan-det-P A)) = prod (λi. (snd (Gauss-Jordan-det-P
A))$i$i) (UNIV:: 'n set)
⟨proof⟩

lemma det-fst-Gauss-Jordan-PA-eq-fst-Gauss-Jordan-det-P:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows fst (Gauss-Jordan-det-P A) = det (fst (Gauss-Jordan-PA A))
⟨proof⟩

lemma fst-Gauss-Jordan-det-P-not-0:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows fst (Gauss-Jordan-det-P A) ≠ 0
⟨proof⟩

lemma det-code-equation[code-unfold]:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows det A = (let A' = Gauss-Jordan-det-P A in prod (λi. (snd (A'))$i$i)
(UNIV::'n set)/(fst (A')))
⟨proof⟩

end

```

## 10 Inverse of a matrix using the Gauss Jordan algorithm

```
theory Inverse
imports
  Gauss-Jordan-PA
begin
```

### 10.1 Several properties

Properties about Gauss Jordan algorithm, reduced row echelon form, rank, identity matrix and invertibility

```
lemma rref-id-implies-invertible:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
assumes Gauss-mat-1: Gauss-Jordan A = mat 1
shows invertible A
⟨proof⟩
```

In the following case, nrows is equivalent to ncols due to we are working with a square matrix

```
lemma full-rank-implies-invertible:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
assumes rank-n: rank A = nrows A
shows invertible A
⟨proof⟩
```

```
lemma invertible-implies-full-rank:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
assumes inv-A: invertible A
shows rank A = nrows A
⟨proof⟩
```

```
definition id-upr-k :: 'a::{zero, one} ^'n::{mod-type} ^'n::{mod-type} ⇒ nat =>
bool
where id-upr-k A k = (forall i j. to-nat i < k and to-nat j < k → ((i = j → A $ i $ j = 1) and (i ≠ j → A $ i $ j = 0)))
```

```
lemma id-upr-nrows-mat-1:
assumes id-upr-k A (nrows A)
shows A = mat 1
⟨proof⟩
```

## 10.2 Computing the inverse of a matrix using the Gauss Jordan algorithm

This lemma is essential to demonstrate that the Gauss Jordan form of an invertible matrix is the identity. The proof is made by induction and it is explained in [http://www.unirioja.es/cu/jodivaso/Isabelle/Gauss-Jordan-2013-2-Generalized/Demonstration\\_invertible.pdf](http://www.unirioja.es/cu/jodivaso/Isabelle/Gauss-Jordan-2013-2-Generalized/Demonstration_invertible.pdf)

```
lemma id-upk-Gauss-Jordan:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes inv-A: invertible A
shows id-upk (Gauss-Jordan A) k
⟨proof⟩
```

```
lemma invertible-implies-rref-id:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes inv-A: invertible A
shows Gauss-Jordan A = mat 1
⟨proof⟩
```

```
lemma matrix-inv-Gauss:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes inv-A: invertible A and Gauss-eq: Gauss-Jordan A = P ** A
shows matrix-inv A = P
⟨proof⟩
```

```
lemma matrix-inv-Gauss-Jordan-PA:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes inv-A: invertible A
shows matrix-inv A = fst (Gauss-Jordan-PA A)
⟨proof⟩
```

```
lemma invertible-eq-full-rank[code-unfold]:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
shows invertible A = (rank A = nrows A)
⟨proof⟩
```

**definition** inverse-matrix A = (if invertible A then Some (matrix-inv A) else None)

```
lemma the-inverse-matrix:
fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
assumes invertible A
shows the (inverse-matrix A) = P-Gauss-Jordan A
⟨proof⟩
```

```

lemma inverse-matrix:
  fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
  shows inverse-matrix A = (if invertible A then Some (P-Gauss-Jordan A) else
    None)
    ⟨proof⟩

lemma inverse-matrix-code[code-unfold]:
  fixes A::'a::{field} ^n::{mod-type} ^n::{mod-type}
  shows inverse-matrix A = (let GJ = Gauss-Jordan-PA A;
    rank-A = (if A = 0 then 0 else to-nat (GREATEST a.
      row a (snd GJ) ≠ 0) + 1) in
      if nrows A = rank-A then Some (fst(GJ)) else None)
    ⟨proof⟩

end

```

## 11 Bases of the four fundamental subspaces

```

theory Bases-Of-Fundamental-Subspaces
imports
  Gauss-Jordan-PA
begin

```

```

11.1 Computation of the bases of the fundamental subspaces

definition basis-null-space A = {row i (P-Gauss-Jordan (transpose A)) | i. to-nat
  i ≥ rank A}
definition basis-row-space A = {row i (Gauss-Jordan A) | i. row i (Gauss-Jordan
  A) ≠ 0}
definition basis-col-space A = {row i (Gauss-Jordan (transpose A)) | i. row i
  (Gauss-Jordan (transpose A)) ≠ 0}
definition basis-left-null-space A = {row i (P-Gauss-Jordan A) | i. to-nat i ≥ rank
  A}

```

### 11.2 Relationships amongst the bases

```

lemma basis-null-space-eq-basis-left-null-space-transpose:
  basis-null-space A = basis-left-null-space (transpose A)
  ⟨proof⟩

lemma basis-null-space-transpose-eq-basis-left-null-space:
  shows basis-null-space (transpose A) = basis-left-null-space A
  ⟨proof⟩

lemma basis-col-space-eq-basis-row-space-transpose:
  basis-col-space A = basis-row-space (transpose A)
  ⟨proof⟩

```

### 11.3 Code equations

Code equations to make more efficient the computations.

**lemma** *basis-null-space-code[code]*: *basis-null-space A = (let GJ = Gauss-Jordan-PA (transpose A);*

*rank-A = (if A = 0 then 0 else to-nat (GREATEST a. row a (snd GJ) ≠ 0) + 1)*  
*in {row i (fst GJ) | i. to-nat i ≥ rank-A})*

**lemma** *basis-row-space-code[code]*: *basis-row-space A = (let A' = Gauss-Jordan A in {row i A' | i. row i A' ≠ 0})*

**lemma** *basis-col-space-code[code]*: *basis-col-space A = (let A' = Gauss-Jordan (transpose A) in {row i A' | i. row i A' ≠ 0})*

**lemma** *basis-left-null-space-code[code]*: *basis-left-null-space A = (let GJ = Gauss-Jordan-PA A;*

*rank-A = (if A = 0 then 0 else to-nat (GREATEST a. row a (snd GJ) ≠ 0) + 1)*  
*in {row i (fst GJ) | i. to-nat i ≥ rank-A})*

### 11.4 Demonstrations that they are bases

We prove that we have obtained a basis for each subspace

**lemma** *independent-basis-left-null-space*:  
**fixes** *A::'a::{field} ↗ cols::{mod-type} ↗ rows::{mod-type}*  
**shows** *vec.independent (basis-left-null-space A)*

*{proof}*

**lemma** *card-basis-left-null-space-eq-dim*:  
**fixes** *A::'a::{field} ↗ cols::{mod-type} ↗ rows::{mod-type}*  
**shows** *card (basis-left-null-space A) = vec.dim (left-null-space A)*

*{proof}*

**lemma** *basis-left-null-space-in-left-null-space*:  
**fixes** *A::'a::{field} ↗ cols::{mod-type} ↗ rows::{mod-type}*  
**shows** *basis-left-null-space A ⊆ left-null-space A*

*{proof}*

**lemma** *left-null-space-subset-span-basis*:

**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{left-null-space } A \subseteq \text{vec.span}(\text{basis-left-null-space } A)$   
 $\langle proof \rangle$

**corollary**  $\text{basis-left-null-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{vec.independent}(\text{basis-left-null-space } A) \wedge$   
 $\text{left-null-space } A = \text{vec.span}(\text{basis-left-null-space } A)$   
 $\langle proof \rangle$

**corollary**  $\text{basis-null-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{vec.independent}(\text{basis-null-space } A) \wedge$   
 $\text{null-space } A = \text{vec.span}(\text{basis-null-space } A)$   
 $\langle proof \rangle$

**lemma**  $\text{basis-row-space-subset-row-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{basis-row-space } A \subseteq \text{row-space } A$   
 $\langle proof \rangle$

**lemma**  $\text{row-space-subset-span-basis-row-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{row-space } A \subseteq \text{vec.span}(\text{basis-row-space } A)$   
 $\langle proof \rangle$

**lemma**  $\text{basis-row-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{vec.independent}(\text{basis-row-space } A)$   
 $\wedge \text{vec.span}(\text{basis-row-space } A) = \text{row-space } A$   
 $\langle proof \rangle$

**corollary**  $\text{basis-col-space}:$   
**fixes**  $A::'a::\{field\} \wedge cols::\{mod-type\} \wedge rows::\{mod-type\}$   
**shows**  $\text{vec.independent}(\text{basis-col-space } A)$   
 $\wedge \text{vec.span}(\text{basis-col-space } A) = \text{col-space } A$   
 $\langle proof \rangle$

**end**

## 12 Solving systems of equations using the Gauss Jordan algorithm

```
theory System-Of-Equations
imports
  Gauss-Jordan-PA
  Bases-Of-Fundamental-Subspaces
begin
```

### 12.1 Definitions

Given a system of equations  $A *v x = b$ , the following function returns the pair  $(P ** A, P *v b)$ , where  $P$  is the matrix which states *Gauss-Jordan A*  $= P ** A$ . That matrix is computed by means of *Gauss-Jordan-PA*.

```
definition solve-system :: ('a::{field} ^'cols::{mod-type} ^'rows::{mod-type}) ⇒ ('a ^'rows::{mod-type})
  ⇒ (('a ^'cols::{mod-type} ^'rows::{mod-type}) × ('a ^'rows::{mod-type}))
  where solve-system A b = (let A' = Gauss-Jordan-PA A in (snd A', (fst A') *v
b))

definition is-solution where is-solution x A b = (A *v x = b)
```

### 12.2 Relationship between *is-solution-def* and *solve-system-def*

```
lemma is-solution-imp-solve-system:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes xAb:is-solution x A b
  shows is-solution x (fst (solve-system A b)) (snd (solve-system A b))
  ⟨proof⟩
```

```
lemma solve-system-imp-is-solution:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes xAb: is-solution x (fst (solve-system A b)) (snd (solve-system A b))
  shows is-solution x A b
  ⟨proof⟩
```

```
lemma is-solution-solve-system:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  shows is-solution x A b = is-solution x (fst (solve-system A b)) (snd (solve-system
A b))
  ⟨proof⟩
```

### 12.3 Consistent and inconsistent systems of equations

```
definition consistent :: 'a::{field} ^'cols::{mod-type} ^'rows::{mod-type} ⇒ 'a::{field} ^'rows::{mod-type}
  ⇒ bool
  where consistent A b = (∃ x. is-solution x A b)
```

```
definition inconsistent where inconsistent A b = (¬ (consistent A b))
```

```
lemma inconsistent: inconsistent A b = (¬ (exists x. is-solution x A b))
  ⟨proof⟩
```

The following function will be used to solve consistent systems which are already in the reduced row echelon form.

```
definition solve-consistent-rref :: 'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  ⇒ 'a::{field} ^'rows::{mod-type} ⇒ 'a::{field} ^'cols::{mod-type}
where solve-consistent-rref A b = (χ j. if (exists i. A $ i $ j = 1 ∧ j=(LEAST n.
A $ i $ n ≠ 0)) then b $ (THE i. A $ i $ j = 1) else 0)
```

```
lemma solve-consistent-rref-code[code abstract]:
  shows vec-nth (solve-consistent-rref A b) = (% j. if (exists i. A $ i $ j = 1 ∧
j=(LEAST n. A $ i $ n ≠ 0)) then b $ (THE i. A $ i $ j = 1) else 0)
  ⟨proof⟩
```

```
lemma rank-ge-imp-is-solution:
  fixes A:'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes con: rank A ≥ (if (exists a. (P-Gauss-Jordan A *v b) $ a ≠ 0)
    then (to-nat (GREATEST a. (P-Gauss-Jordan
A *v b) $ a ≠ 0) + 1) else 0)
  shows is-solution (solve-consistent-rref (Gauss-Jordan A) (P-Gauss-Jordan A *v
b)) A b
  ⟨proof⟩
```

```
corollary rank-ge-imp-consistent:
  fixes A:'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes rank A ≥ (if (exists a. (P-Gauss-Jordan A *v b) $ a ≠ 0) then (to-nat
(GREATEST a. (P-Gauss-Jordan A *v b) $ a ≠ 0) + 1) else 0)
  shows consistent A b
  ⟨proof⟩
```

```
lemma inconsistent-imp-rank-less:
  fixes A:'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes inc: inconsistent A b
  shows rank A < (if (exists a. (P-Gauss-Jordan A *v b) $ a ≠ 0) then (to-nat
(GREATEST a. (P-Gauss-Jordan A *v b) $ a ≠ 0) + 1) else 0)
  ⟨proof⟩
```

```
lemma rank-less-imp-inconsistent:
  fixes A:'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes inc: rank A < (if (exists a. (P-Gauss-Jordan A *v b) $ a ≠ 0) then (to-nat
(GREATEST a. (P-Gauss-Jordan A *v b) $ a ≠ 0) + 1) else 0)
  shows inconsistent A b
```

$\langle proof \rangle$

**corollary** *consistent-imp-rank-ge*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**assumes** *consistent A b*  
**shows**  $\text{rank } A \geq (\text{if } (\exists a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0) \text{ then } (\text{to-nat } (\text{GREATEST } a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0) + 1) \text{ else } 0)$   
 $\langle proof \rangle$

**lemma** *inconsistent-eq-rank-less*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**shows** *inconsistent A b = (rank A < (if ( $\exists a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0$ ) then (to-nat ( $\text{GREATEST } a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0$ ) + 1) else 0))*  
 $\langle proof \rangle$

**lemma** *consistent-eq-rank-ge*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**shows** *consistent A b = (rank A  $\geq (\text{if } (\exists a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0) \text{ then } (\text{to-nat } (\text{GREATEST } a. (P\text{-Gauss-Jordan } A *v b) \$ a \neq 0) + 1) \text{ else } 0))$*   
 $\langle proof \rangle$

**corollary** *consistent-imp-is-solution*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**assumes** *consistent A b*  
**shows** *is-solution (solve-consistent-rref (Gauss-Jordan A) (P-Gauss-Jordan A \*v b)) A b*  
 $\langle proof \rangle$

**corollary** *consistent-imp-is-solution'*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**assumes** *consistent A b*  
**shows** *is-solution (solve-consistent-rref (fst (solve-system A b)) (snd (solve-system A b))) A b*  
 $\langle proof \rangle$

Code equations optimized using Lets

**lemma** *inconsistent-eq-rank-less-code[code]*:

**fixes**  $A::'a::\{field\} \rightsquigarrow cols::\{\text{mod-type}\} \rightsquigarrow rows::\{\text{mod-type}\}$   
**shows** *inconsistent A b = (let GJ-P=Gauss-Jordan-PA A;*  
 $P\text{-mult-}b = (\text{fst } (GJ-P) *v b);$   
 $\text{rank-}A = (\text{if } A = 0 \text{ then } 0 \text{ else } \text{to-nat } (\text{GREATEST } a.$   
 $\text{row } a (\text{snd } GJ-P) \neq 0) + 1) \text{ in } (\text{rank-}A < (\text{if } (\exists a. P\text{-mult-}b \$ a \neq 0) \text{ then } (\text{to-nat } (\text{GREATEST } a. P\text{-mult-}b \$ a \neq 0) + 1) \text{ else } 0)))$

$\langle proof \rangle$

```

lemma consistent-eq-rank-ge-code[code]:
fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows consistent A b = (let GJ-P=Gauss-Jordan-PA A;
    P-mult-b = (fst(GJ-P) *v b);
    rank-A = (if A = 0 then 0 else to-nat (GREATEST a. row
        a (snd GJ-P) ≠ 0) + 1) in (rank-A ≥ (if (exists a. P-mult-b $ a ≠ 0)
            then (to-nat (GREATEST a. P-mult-b $ a ≠ 0) + 1) else 0)))
  
```

$\langle proof \rangle$

#### 12.4 Solution set of a system of equations. Dependent and independent systems.

**definition** solution-set **where** solution-set A b = {x. is-solution x A b}

```

lemma null-space-eq-solution-set:
shows null-space A = solution-set A 0  $\langle proof \rangle$ 
  
```

```

corollary dim-solution-set-homogeneous-eq-dim-null-space[code-unfold]:
shows vec.dim (solution-set A 0) = vec.dim (null-space A)  $\langle proof \rangle$ 
  
```

```

lemma zero-is-solution-homogeneous-system:
shows 0 ∈ (solution-set A 0)
 $\langle proof \rangle$ 
  
```

```

lemma homogeneous-solution-set-subspace:
fixes A::'a::{field} ^'n ^'rows
shows vec.subspace (solution-set A 0)
 $\langle proof \rangle$ 
  
```

```

lemma solution-set-rel:
fixes A::'a::{field} ^'n ^'rows
assumes p: is-solution p A b
shows solution-set A b = {p} + (solution-set A 0)
 $\langle proof \rangle$ 
  
```

```

lemma independent-and-consistent-imp-uniqueness-solution:
fixes A::'a::{field} ^'n::{mod-type} ^'rows::{mod-type}
assumes dim-0: vec.dim (solution-set A 0) = 0
and con: consistent A b
shows ∃!x. is-solution x A b
 $\langle proof \rangle$ 
  
```

**lemma** *card-1-exists*:  $\text{card } s = 1 \longleftrightarrow (\exists !x. x \in s)$   
*(proof)*

**corollary** *independent-and-consistent-imp-card-1*:  
**fixes**  $A::'a::\{\text{field}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**assumes**  $\text{dim-0}: \text{vec.dim}(\text{solution-set } A 0) = 0$   
**and**  $\text{con}: \text{consistent } A b$   
**shows**  $\text{card}(\text{solution-set } A b) = 1$   
*(proof)*

**lemma** *uniqueness-solution-imp-independent*:  
**fixes**  $A::'a::\{\text{field}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**assumes**  $\text{ex1-sol}: \exists !x. \text{is-solution } x A b$   
**shows**  $\text{vec.dim}(\text{solution-set } A 0) = 0$   
*(proof)*

**corollary** *uniqueness-solution-eq-independent-and-consistent*:  
**fixes**  $A::'a::\{\text{field}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**shows**  $(\exists !x. \text{is-solution } x A b) = (\text{consistent } A b \wedge \text{vec.dim}(\text{solution-set } A 0) = 0)$   
*(proof)*

**lemma** *consistent-homogeneous*:  
**shows**  $\text{consistent } A 0$  *(proof)*

**lemma** *dim-solution-set-0*:  
**fixes**  $A::'a::\{\text{field}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**shows**  $(\text{vec.dim}(\text{solution-set } A 0) = 0) = (\text{solution-set } A 0 = \{0\})$   
*(proof)*

We have to impose the restriction *semiring-char-0* in the following lemma, because it may not hold over a general field (for instance, in Z2 there is a finite number of elements, so the solution set can't be infinite).

**lemma** *dim-solution-set-not-zero-imp-infinite-solutions-homogeneous*:  
**fixes**  $A::'a::\{\text{field, semiring-char-0}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**assumes**  $\text{dim-not-zero}: \text{vec.dim}(\text{solution-set } A 0) > 0$   
**shows**  $\text{infinite}(\text{solution-set } A 0)$   
*(proof)*

**lemma** *infinite-solutions-homogeneous-imp-dim-solution-set-not-zero*:  
**fixes**  $A::'a::\{\text{field}\}^n::\{\text{mod-type}\}^r::\{\text{mod-type}\}$   
**assumes**  $i: \text{infinite}(\text{solution-set } A 0)$   
**shows**  $\text{vec.dim}(\text{solution-set } A 0) > 0$   
*(proof)*

**corollary** *infinite-solution-set-homogeneous-eq*:

```

fixes A::'a::{field,semiring-char-0} ^'n::{mod-type} ^'rows::{mod-type}
shows infinite (solution-set A 0) = (vec.dim (solution-set A 0) > 0)
⟨proof⟩

```

```

corollary infinite-solution-set-homogeneous-eq':
fixes A::'a::{field,semiring-char-0} ^'n::{mod-type} ^'rows::{mod-type}
shows (∃∞x. is-solution x A 0) = (vec.dim (solution-set A 0) > 0)
⟨proof⟩

```

```

lemma infinite-solution-set-imp-consistent:
infinite (solution-set A b)  $\implies$  consistent A b
⟨proof⟩

```

```

lemma dim-solution-set-not-zero-imp-infinite-solutions-no-homogeneous:
fixes A::'a::{field, semiring-char-0} ^'n::{mod-type} ^'rows::{mod-type}
assumes dim-not-0: vec.dim (solution-set A 0) > 0
and con: consistent A b
shows infinite (solution-set A b)
⟨proof⟩

```

```

lemma infinite-solutions-no-homogeneous-imp-dim-solution-set-not-zero-imp:
fixes A::'a::{field} ^'n::{mod-type} ^'rows::{mod-type}
assumes i: infinite (solution-set A b)
shows vec.dim (solution-set A 0) > 0
⟨proof⟩

```

```

corollary infinite-solution-set-no-homogeneous-eq:
fixes A::'a::{field, semiring-char-0} ^'n::{mod-type} ^'rows::{mod-type}
shows infinite (solution-set A b) = (consistent A b  $\wedge$  vec.dim (solution-set A 0) > 0)
⟨proof⟩

```

```

corollary infinite-solution-set-no-homogeneous-eq':
fixes A::'a::{field, semiring-char-0} ^'n::{mod-type} ^'rows::{mod-type}
shows (∃∞x. is-solution x A b) = (consistent A b  $\wedge$  vec.dim (solution-set A 0) > 0)
⟨proof⟩

```

```

definition independent-and-consistent A b = (consistent A b  $\wedge$  vec.dim (solution-set A 0) = 0)
definition dependent-and-consistent A b = (consistent A b  $\wedge$  vec.dim (solution-set A 0) > 0)

```

## 12.5 Solving systems of linear equations

The following function will solve any system of linear equations. Given a matrix  $A$  and a vector  $b$ , Firstly it makes use of the funcion *solve-system* to transform the original matrix  $A$  and the vector  $b$  into another ones in

reduced row echelon form. Then, that system will have the same solution than the original one but it is easier to be solved. So we make use of the function *solve-consistent-rref* to obtain one solution of the system.

We will prove that any solution of the system can be rewritten as a linear combination of elements of a basis of the null space plus a particular solution of the system. So the function *solve* will return an option type, depending on the consistency of the system:

- If the system is consistent (so there exists at least one solution), the function will return the *Some* of a pair. In the first component of that pair will be one solution of the system and the second one will be a basis of the null space of the matrix. Hence:
  1. If the system is consistent and independent (so there exists one and only one solution), the pair will consist of the solution and the empty set (this empty set is the basis of the null space).
  2. If the system is consistent and dependent (so there exists more than one solution, maybe an infinite number), the pair will consist of one particular solution and a basis of the null space (which will not be the empty set).
- If the system is inconsistent (so there exists no solution), the function will return *None*.

**definition** *solve A b = (if consistent A b then*

*Some (solve-consistent-rref (fst (solve-system A b)) (snd (solve-system A b)),*  
*basis-null-space A)*  
*else None)*

**lemma** *solve-code[code]:*

**shows** *solve A b = (let GJ-P=Gauss-Jordan-PA A;*  
*P-times-b=fst(GJ-P) \*v b;*  
*rank-A = (if A = 0 then 0 else to-nat (GREATEST a. row a*  
*(snd GJ-P) ≠ 0) + 1);*  
*consistent-Ab = (rank-A ≥ (if (exists a. (P-times-b) \$ a ≠ 0) then*  
*(to-nat (GREATEST a. (P-times-b) \$ a ≠ 0) + 1) else 0));*  
*GJ transpose = Gauss-Jordan-PA (transpose A);*  
*basis = {row i (fst GJ transpose) | i. to-nat i ≥ rank-A}*  
*in (if consistent-Ab then Some (solve-consistent-rref (snd GJ-P)*  
*P-times-b,basis) else None))*  
 *$\langle proof \rangle$*

**lemma** *consistent-imp-is-solution-solve:*

**fixes** *A::'a::{field} ^ cols::{mod-type} ^ rows::{mod-type}*  
**assumes** *con: consistent A b*  
**shows** *is-solution (fst (the (solve A b))) A b*  
 *$\langle proof \rangle$*

```

corollary consistent-eq-solution-solve:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  shows consistent A b = is-solution (fst (the (solve A b))) A b
  <proof>

lemma inconsistent-imp-solve-eq-none:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes con: inconsistent A b
  shows solve A b = None <proof>

corollary inconsistent-eq-solve-eq-none:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  shows inconsistent A b = (solve A b = None)
  <proof>

```

We demonstrate that all solutions of a system of linear equations can be expressed as a linear combination of the basis of the null space plus a particular solution obtained. The basis and the particular solution are obtained by means of the function *solve A b*

```

lemma solution-set-rel-solve:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes con: consistent A b
  shows solution-set A b = {fst (the (solve A b))} + vec.span (snd (the (solve A b)))
  <proof>

```

```

lemma is-solution-eq-in-span-solve:
  fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
  assumes con: consistent A b
  shows (is-solution x A b) = (x ∈ {fst (the (solve A b))} + vec.span (snd (the (solve A b))))
  <proof>

```

**end**

## 13 Code Generation for Z2

```

theory Code-Z2
imports HOL-Library.Z2
begin

```

Implementation for the field of integer numbers module 2. Experimentally we have checked that the implementation by means of booleans is the fastest one.

```

code-datatype 0::bit (1::bit)
code-printing
  type-constructor bit → (SML) Bool.bool

```

```

| constant 0::bit → (SML) false
| constant 1::bit → (SML) true

code-printing
type-constructor bit → (Haskell) Bool
| constant 0::bit → (Haskell) False
| constant 1::bit → (Haskell) True
| class-instance bit :: HOL.equal => (Haskell) −

end

```

## 14 Examples of computations over abstract matrices

```

theory Examples-Gauss-Jordan-Abstract
imports
  Determinants2
  Inverse
  System-Of-Equations
  Code-Z2
  HOL-Library.Code-Target-Numerical
begin

```

### 14.1 Transforming a list of lists to an abstract matrix

Definitions to transform a matrix to a list of list and vice versa

```

definition vec-to-list :: 'a ^ n::{finite, enum} => 'a list
  where vec-to-list A = map ((\$) A) (enum-class.enum::'n list)

definition matrix-to-list-of-list :: 'a ^ n::{finite, enum} ^ m::{finite, enum} => 'a
list list
  where matrix-to-list-of-list A = map (vec-to-list) (map ((\$) A) (enum-class.enum::'m
list))

```

This definition should be equivalent to *vector-def* (in suitable types)

```

definition list-to-vec :: 'a list => 'a ^ n::{finite, enum, mod-type}
  where list-to-vec xs = vec-lambda (% i. xs ! (to-nat i))

```

```

lemma [code abstract]: vec-nth (list-to-vec xs) = (%i. xs ! (to-nat i))

```

$\langle proof \rangle$

```
definition list-of-list-to-matrix :: 'a list list => 'a ^'n::{finite, enum, mod-type} ^'m::{finite,
enum, mod-type}
  where list-of-list-to-matrix xs = vec-lambda (%i. list-to-vec (xs ! (to-nat i)))

lemma [code abstract]: vec-nth (list-of-list-to-matrix xs) = (%i. list-to-vec (xs !
(to-nat i)))
  ⟨proof⟩
```

## 14.2 Examples

The following three lemmas are presented in both this file and in the *Examples-Gauss-Jordan-IArrays* one. They allow a more convenient printing of rational and real numbers after evaluation. They have already been added to the repository version of Isabelle, so after Isabelle2014 they should be removed from here.

```
lemma [code-post]:
  int-of-integer (- 1) = - 1
  ⟨proof⟩
```

```
lemma [code-abbrev]:
  (of-rat (- 1) :: real) = - 1
  ⟨proof⟩
```

```
lemma [code-post]:
  (of-rat (- (1 / numeral k)) :: real) = - 1 / numeral k
  (of-rat (- (numeral k / numeral l)) :: real) = - numeral k / numeral l
  ⟨proof⟩
```

### 14.2.1 Ranks and dimensions

Examples on computing ranks, dimensions of row space, null space and col space and the Gauss Jordan algorithm

```
value matrix-to-list-of-list (Gauss-Jordan (list-of-list-to-matrix ([[1,0,0,0,0,0],[0,1,0,0,0,0],[0,0,0,0,0,0],[0,0,0,0,0,0],[0,-1,0,0,0,0],[0,0,1,0,0,0]])))::rat^5^2)
value matrix-to-list-of-list (Gauss-Jordan (list-of-list-to-matrix ([[1,-2,1,-3,0],[3,-6,2,-7,0]]))::rat^5^2)
value matrix-to-list-of-list (Gauss-Jordan (list-of-list-to-matrix ([[1,0,0,1,1],[1,0,1,1,1]]))::bit^5^2)
value (reduced-row-echelon-form-upt-k (list-of-list-to-matrix ([[1,0,8],[0,1,9],[0,0,0]]))::real^3^3)
3
value matrix-to-list-of-list (Gauss-Jordan (list-of-list-to-matrix [[Complex 1 1,Complex 1 (- 1), Complex 0 0],[Complex 2 (- 1),Complex 1 3, Complex 7 3]]))::complex^3^2)
value DIM(real^5)
value vec.dimension (TYPE(bit)) (TYPE(5))
value vec.dimension (TYPE(real)) (TYPE(2))

value DIM(real^5^4)
```

```

value row-rank (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4)
value vec.dim (row-space (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4))
value col-rank (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4)
value vec.dim (col-space (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4))
value rank (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4)
value vec.dim (null-space (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4))
value rank (list-of-list-to-matrix [[Complex 1 1,Complex 1 (-1), Complex 0 0].[Complex 2 (-1),Complex 1 3, Complex 7 3]]::complex^3^2)

```

#### 14.2.2 Inverse of a matrix

Examples on computing the inverse of matrices

```

value let A=(list-of-list-to-matrix [[1,1,2,4,5,9,8],[3,0,8,4,5,0,8],[3,2,0,4,5,9,8],
[3,2,8,0,5,9,8],[3,2,8,4,0,9,8],[3,2,8,4,5,0,8],[3,2,8,4,5,9,0]]::real^7^7)
      in matrix-to-list-of-list (P-Gauss-Jordan A)
value let A=(list-of-list-to-matrix [[1,1,2,4,5,9,8],[3,0,8,4,5,0,8],[3,2,0,4,5,9,8],
[3,2,8,0,5,9,8],[3,2,8,4,0,9,8],[3,2,8,4,5,0,8],[3,2,8,4,5,9,0]]::real^7^7) in
      matrix-to-list-of-list (A ** (P-Gauss-Jordan A))
value let A=(list-of-list-to-matrix [[1,1,2,4,5,9,8],[3,0,8,4,5,0,8],[3,2,0,4,5,9,8],
[3,2,8,0,5,9,8],[3,2,8,4,0,9,8],[3,2,8,4,5,0,8],[3,2,8,4,5,9,0]]::real^7^7)
      in (inverse-matrix A)
value let A=(list-of-list-to-matrix [[1,1,2,4,5,9,8],[3,0,8,4,5,0,8],[3,2,0,4,5,9,8],
[3,2,8,0,5,9,8],[3,2,8,4,0,9,8],[3,2,8,4,5,0,8],[3,2,8,4,5,9,0]]::real^7^7)
      in matrix-to-list-of-list (the (inverse-matrix A))
value let A=(list-of-list-to-matrix [[1,1,1,1,1,1,1],[2,2,2,2,2,2,2],[3,2,0,4,5,9,8],
[3,2,8,0,5,9,8],[3,2,8,4,0,9,8],[3,2,8,4,5,0,8],[3,2,8,4,5,9,0]]::real^7^7)
      in (inverse-matrix A)
value let A=(list-of-list-to-matrix [[Complex 1 1,Complex 1 (-1), Complex 0 0],[Complex 1 1,Complex 1 (-1), Complex 8 0],[Complex 2 (-1),Complex 1 3, Complex 7 3]]::complex^3^3)
      in matrix-to-list-of-list (the (inverse-matrix A))

```

#### 14.2.3 Determinant of a matrix

Examples on computing determinants of matrices

```

value (let A = list-of-list-to-matrix [[1,2,7,8,9],[3,4,12,10,7],[-5,4,8,7,4],[0,1,2,4,8],[9,8,7,13,11]]::real^5^5
      in det A)
value det (list-of-list-to-matrix ([[1,0,0],[0,1,0],[0,0,1]])::real^3^3)
value det (list-of-list-to-matrix ([[1,8,9,1,47],[7,2,2,5,9],[3,2,7,7,4],[9,8,7,5,1],[1,2,6,4,5]])::rat^5^5)

```

#### 14.2.4 Bases of the fundamental subspaces

Examples on computing basis for null space, row space, column space and left null space

```

value let A = (list-of-list-to-matrix ([[1,3,-2,0,2,0],[2,6,-5,-2,4,-3],[0,0,5,10,0,15],[2,6,0,8,4,18]])::real^6^6
      in vec-to-list` (basis-null-space A)

```

```

value let A = (list-of-list-to-matrix ([[3,4,0,7],[1,-5,2,-2],[-1,4,0,3],[1,-1,2,2]])::real^4^4)
in vec-to-list` (basis-null-space A)

value let A = (list-of-list-to-matrix ([[1,3,-2,0,2,0],[2,6,-5,-2,4,-3],[0,0,5,10,0,15],[2,6,0,8,4,18]])::real
in vec-to-list` (basis-row-space A)
value let A = (list-of-list-to-matrix ([[3,4,0,7],[1,-5,2,-2],[-1,4,0,3],[1,-1,2,2]])::real^4^4)
in vec-to-list` (basis-row-space A)

value let A = (list-of-list-to-matrix ([[1,3,-2,0,2,0],[2,6,-5,-2,4,-3],[0,0,5,10,0,15],[2,6,0,8,4,18]])::real
in vec-to-list` (basis-col-space A)
value let A = (list-of-list-to-matrix ([[3,4,0,7],[1,-5,2,-2],[-1,4,0,3],[1,-1,2,2]])::real^4^4)
in vec-to-list` (basis-col-space A)

value let A = (list-of-list-to-matrix ([[1,3,-2,0,2,0],[2,6,-5,-2,4,-3],[0,0,5,10,0,15],[2,6,0,8,4,18]])::real
in vec-to-list` (basis-left-null-space A)
value let A = (list-of-list-to-matrix ([[3,4,0,7],[1,-5,2,-2],[-1,4,0,3],[1,-1,2,2]])::real^4^4)
in vec-to-list` (basis-left-null-space A)

```

#### 14.2.5 Consistency and inconsistency

Examples on checking the consistency/inconsistency of a system of equations

```

value independent-and-consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[0,0,1],[0,0,0],[0,0,0]])::real^3^5)
(list-to-vec([2,3,4,0,0])::real^5)
value consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[0,0,1],[0,0,0],[0,0,0]])::real^3^5)
(list-to-vec([2,3,4,0,0])::real^5)
value inconsistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[3,0,1],[0,7,0],[0,0,9]])::real^3^5)
(list-to-vec([2,0,4,0,0])::real^5)
value dependent-and-consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0]])::real^3^2)
(list-to-vec([3,4])::real^2)
value independent-and-consistent (mat 1::real^3^3) (list-to-vec([3,4,5])::real^3)

```

#### 14.2.6 Solving systems of linear equations

Examples on solving linear systems.

**definition** print-result-solve

**where** print-result-solve A = (if A = None then None else Some (vec-to-list (fst (the A)), vec-to-list` (snd (the A))))

```

value let A = (list-of-list-to-matrix [[4,5,8],[9,8,7],[4,6,1]]::real^3^3);
      b=(list-to-vec [4,5,8]::real^3)
      in (print-result-solve (solve A b))

```

```

value let A = (list-of-list-to-matrix [[0,0,0],[0,0,0],[0,0,1]]::real^3^3);
      b=(list-to-vec [4,5,0]::real^3)
      in (print-result-solve (solve A b))

value let A = (list-of-list-to-matrix [[3,2,5,2,7],[6,4,7,4,5],[3,2,-1,2,-11],[6,4,1,4,-13]]::real^5^4);
      b=(list-to-vec [0,0,0,0]::real^4)
      in (print-result-solve (solve A b))

value let A = (list-of-list-to-matrix [[1,2,1],[-2,-3,-1],[2,4,2]]::real^3^3);
      b=(list-to-vec [-2,1,-4]::real^3)
      in (print-result-solve (solve A b))

value let A = (list-of-list-to-matrix [[1,1,-4,10],[3,-2,-2,6]]::real^4^2);
      b=(list-to-vec [24,15]::real^2)
      in (print-result-solve (solve A b))

end

```

## 15 IArrays Addenda

```

theory IArray-Addenda
imports
  HOL-Library.IArray
begin

```

### 15.1 Some previous instances

```

instantiation iarray :: (plus) plus
begin
definition plus-iarray :: 'a iarray ⇒ 'a iarray ⇒ 'a iarray
  where plus-iarray A B = IArray.of-fun (λn. A!!n + B !! n) (IArray.length A)
instance ⟨proof⟩
end

instantiation iarray :: (minus) minus
begin
definition minus-iarray :: 'a iarray ⇒ 'a iarray ⇒ 'a iarray
  where minus-iarray A B = IArray.of-fun (λn. A!!n - B !! n) (IArray.length A)
instance ⟨proof⟩
end

```

### 15.2 Some previous definitions and properties for IArrays

### 15.3 Code generation

```
end
```

## 16 Matrices as nested IArrays

```
theory Matrix-To-IArray
imports
  Rank-Nullity-Theorem.Mod-Type
  Elementary-Operations
  IArray-Addenda
begin
```

### 16.1 Isomorphism between matrices implemented byvecs and matrices implemented by iarrays

#### 16.1.1 Isomorphism between vec and iarray

```
definition vec-to-iarray :: ' $a^{\sim}n::\{mod-type\}$  ⇒ ' $a$  iarray
  where vec-to-iarray  $A = IArray.of-fun (\lambda i. A \$ (from-nat i)) (CARD('n))$ 
```

```
definition iarray-to-vec :: ' $a$  iarray ⇒ ' $a^{\sim}n::\{mod-type\}$ 
  where iarray-to-vec  $A = (\chi i. A !! (to-nat i))$ 
```

```
lemma vec-to-iarray-nth:
  fixes  $A::'a^{\sim}n::\{finite, mod-type\}$ 
  assumes  $i: i < CARD('n)$ 
  shows  $(vec-to-iarray A) !! i = A \$ (from-nat i)$ 
  ⟨proof⟩
```

```
lemma vec-to-iarray-nth':
  fixes  $A::'a^{\sim}n::\{mod-type\}$ 
  shows  $(vec-to-iarray A) !! (to-nat i) = A \$ i$ 
  ⟨proof⟩
```

```
lemma iarray-to-vec-nth:
  shows  $(iarray-to-vec A) \$ i = A !! (to-nat i)$ 
  ⟨proof⟩
```

```
lemma vec-to-iarray-morph:
  fixes  $A::'a^{\sim}n::\{mod-type\}$ 
  shows  $(A = B) = (vec-to-iarray A = vec-to-iarray B)$ 
  ⟨proof⟩
```

```
lemma inj-vec-to-iarray:
  shows inj vec-to-iarray
  ⟨proof⟩
```

```
lemma iarray-to-vec-vec-to-iarray:
  fixes  $A::'a^{\sim}n::\{mod-type\}$ 
  shows iarray-to-vec (vec-to-iarray  $A) = A$ 
```

$\langle proof \rangle$

**lemma** *vec-to-iarray-iarray-to-vec*:  
  **assumes** *length-eq*:  $IArray.length A = CARD('n:\{mod-type\})$   
  **shows** *vec-to-iarray* (*iarray-to-vec*  $A::'a^{'n:\{mod-type\}}$ ) =  $A$   
 $\langle proof \rangle$

**lemma** *length-vec-to-iarray*:  
  **fixes**  $xa::'a^{'n:\{mod-type\}}$   
  **shows**  $IArray.length (\text{vec-to-iarray } xa) = CARD('n)$   
 $\langle proof \rangle$

### 16.1.2 Isomorphism between matrix and nested iarrays

**definition** *matrix-to-iarray* ::  $'a^{'n:\{mod-type\}}^{'m:\{mod-type\}} \Rightarrow 'a iarray iarray$   
  **where** *matrix-to-iarray*  $A = IArray (\text{map} (\text{vec-to-iarray} \circ ((\$) A) \circ (\text{from-nat}::nat \Rightarrow 'm)) [0.. < CARD('m)])$

**definition** *iarray-to-matrix* ::  $'a iarray iarray \Rightarrow 'a^{'n:\{mod-type\}}^{'m:\{mod-type\}}$   
  **where** *iarray-to-matrix*  $A = (\chi i j. A !! (\text{to-nat } i) !! (\text{to-nat } j))$

**lemma** *matrix-to-iarray-morph*:  
  **fixes**  $A::'a^{'n:\{mod-type\}}^{'m:\{mod-type\}}$   
  **shows**  $(A = B) = (\text{matrix-to-iarray } A = \text{matrix-to-iarray } B)$   
 $\langle proof \rangle$

**lemma** *matrix-to-iarray-eq-of-fun*:  
  **fixes**  $A::'a^{\text{columns}::\{mod-type\}}^{\text{rows}::\{mod-type\}}$   
  **assumes** *vec-eq-f*:  $\forall i. \text{vec-to-iarray} (A \$ i) = f (\text{to-nat } i)$   
  **and** *n-eq-length*:  $n = IArray.length (\text{matrix-to-iarray } A)$   
  **shows** *matrix-to-iarray*  $A = IArray.of-fun f n$   
 $\langle proof \rangle$

**lemma** *map-vec-to-iarray-rw*[simp]:  
  **fixes**  $A::'a^{\text{columns}::\{mod-type\}}^{\text{rows}::\{mod-type\}}$   
  **shows**  $\text{map} (\lambda x. \text{vec-to-iarray} (A \$ \text{from-nat } x)) [0.. < CARD('rows)] ! \text{to-nat } i = \text{vec-to-iarray} (A \$ i)$   
 $\langle proof \rangle$

**lemma** *matrix-to-iarray-nth*:  
  *matrix-to-iarray*  $A !! \text{to-nat } i !! \text{to-nat } j = A \$ i \$ j$   
 $\langle proof \rangle$

**lemma** *vec-matrix*:  $\text{vec-to-iarray} (A \$ i) = (\text{matrix-to-iarray } A) !! (\text{to-nat } i)$   
 $\langle proof \rangle$

**lemma** *iarray-to-matrix-matrix-to-iarray*:

**fixes**  $A::'a \sim columns :: \{mod-type\} \sim rows :: \{mod-type\}$   
**shows**  $iarray\text{-to-matrix} (\text{matrix-to-iarray } A) = A \langle proof \rangle$

## 16.2 Definition of operations over matrices implemented by iarrays

**definition**  $mult\text{-iarray} :: 'a :: \{times\} iarray \Rightarrow 'a \Rightarrow 'a iarray$   
**where**  $mult\text{-iarray } A q = IArray.of\text{-fun} (\lambda n. q * A!!n) (IArray.length A)$

**definition**  $row\text{-iarray} :: nat \Rightarrow 'a iarray iarray \Rightarrow 'a iarray$   
**where**  $row\text{-iarray } k A = A !! k$

**definition**  $column\text{-iarray} :: nat \Rightarrow 'a iarray iarray \Rightarrow 'a iarray$   
**where**  $column\text{-iarray } k A = IArray.of\text{-fun} (\lambda m. A !! m !! k) (IArray.length A)$

**definition**  $nrows\text{-iarray} :: 'a iarray iarray \Rightarrow nat$   
**where**  $nrows\text{-iarray } A = IArray.length A$

**definition**  $ncols\text{-iarray} :: 'a iarray iarray \Rightarrow nat$   
**where**  $ncols\text{-iarray } A = IArray.length (A!!0)$

**definition**  $rows\text{-iarray } A = \{row\text{-iarray } i A \mid i. i \in \{.. < nrows\text{-iarray } A\}\}$   
**definition**  $columns\text{-iarray } A = \{column\text{-iarray } i A \mid i. i \in \{.. < ncols\text{-iarray } A\}\}$

**definition**  $tabulate2 :: nat \Rightarrow nat \Rightarrow (nat \Rightarrow nat \Rightarrow 'a) \Rightarrow 'a iarray iarray$   
**where**  $tabulate2 m n f = IArray.of\text{-fun} (\lambda i. IArray.of\text{-fun} (f i) n) m$

**definition**  $transpose\text{-iarray} :: 'a iarray iarray \Rightarrow 'a iarray iarray$   
**where**  $transpose\text{-iarray } A = tabulate2 (ncols\text{-iarray } A) (nrows\text{-iarray } A) (\lambda a b. A!!b!!a)$

**definition**  $matrix\text{-matrix\text{-}mult\text{-}iarray} :: 'a :: \{times, comm\text{-}monoid\text{-}add\} iarray iarray \Rightarrow 'a iarray iarray \Rightarrow 'a iarray iarray$   
**where**  $A **i B = tabulate2 (nrows\text{-iarray } A) (ncols\text{-iarray } B) (\lambda i j. sum (\lambda k. ((A!!i)!!k) * ((B!!k)!!j)) \{0.. < ncols\text{-iarray } A\})$

**definition**  $matrix\text{-vector\text{-}mult\text{-}iarray} :: 'a :: \{semiring\text{-}1\} iarray iarray \Rightarrow 'a iarray$   
**where**  $A *iv x = IArray.of\text{-fun} (\lambda i. sum (\lambda j. ((A!!i)!!j) * (x!!j)) \{0.. < IArray.length x\}) (nrows\text{-iarray } A)$

**definition**  $vector\text{-matrix\text{-}mult\text{-}iarray} :: 'a :: \{semiring\text{-}1\} iarray iarray \Rightarrow 'a iarray iarray$   
**where**  $x v*i A = IArray.of\text{-fun} (\lambda j. sum (\lambda i. (x!!i) * ((A!!i)!!j)) \{0.. < IArray.length x\}) (ncols\text{-iarray } A)$

**definition**  $mat\text{-iarray} :: 'a :: \{zero\} \Rightarrow nat \Rightarrow 'a iarray iarray$   
**where**  $mat\text{-iarray } k n = tabulate2 n n (\lambda i j. if i = j then k else 0)$

```

definition is-zero-iarray :: 'a:{zero} iarray  $\Rightarrow$  bool
  where is-zero-iarray A = IArray.all ( $\lambda i. A !! i = 0$ ) (IArray[0..<IArray.length A])

```

### 16.2.1 Properties of previous definitions

**lemma** is-zero-iarray-eq-iff:

```

fixes A::'a:{zero}  $\rightsquigarrow$  n::{mod-type}
shows (A = 0) = (is-zero-iarray (vec-to-iarray A))
⟨proof⟩

```

**lemma** mult-iarray-works:

```

assumes a < IArray.length A shows mult-iarray A q !! a = q * A!!a
⟨proof⟩

```

**lemma** length-eq-card-rows:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows IArray.length (matrix-to-iarray A) = CARD('rows)
⟨proof⟩

```

**lemma** nrows-eq-card-rows:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows nrows-iarray (matrix-to-iarray A) = CARD('rows)
⟨proof⟩

```

**lemma** length-eq-card-columns:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows IArray.length (matrix-to-iarray A !! 0) = CARD ('columns)
⟨proof⟩

```

**lemma** ncols-eq-card-columns:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows ncols-iarray (matrix-to-iarray A) = CARD('columns)
⟨proof⟩

```

**lemma** matrix-to-iarray-nrows:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows nrows A = nrows-iarray (matrix-to-iarray A)
⟨proof⟩

```

**lemma** matrix-to-iarray-ncols:

```

fixes A::'a $\rightsquigarrow$ columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}
shows ncols A = ncols-iarray (matrix-to-iarray A)
⟨proof⟩

```

**lemma** vec-to-iarray-row[code-unfold]: vec-to-iarray (row i A) = row-iarray (to-nat i) (matrix-to-iarray A)
⟨proof⟩

```

lemma vec-to-iarray-row': vec-to-iarray (row i A) = (matrix-to-iarray A) !! (to-nat i)
  ⟨proof⟩

lemma vec-to-iarray-column[code-unfold]: vec-to-iarray (column i A) = column-iarray (to-nat i) (matrix-to-iarray A)
  ⟨proof⟩

lemma vec-to-iarray-column':
assumes k: k < ncols A
shows (vec-to-iarray (column (from-nat k) A)) = (column-iarray k (matrix-to-iarray A))
  ⟨proof⟩

lemma column-iarray-nth:
assumes i: i < nrows-iarray A
shows column-iarray j A !! i = A !! i !! j
  ⟨proof⟩

lemma vec-to-iarray-rows: vec-to-iarray` (rows A) = rows-iarray (matrix-to-iarray A)
  ⟨proof⟩

lemma vec-to-iarray-columns: vec-to-iarray` (columns A) = columns-iarray (matrix-to-iarray A)
  ⟨proof⟩

```

### 16.3 Definition of elementary operations

**definition** *interchange-rows-iarray* :: 'a iarray iarray => nat => nat => 'a iarray iarray

**where** *interchange-rows-iarray A a b* = *IArray.of-fun* ( $\lambda n. \text{if } n=a \text{ then } A!!b \text{ else if } n=b \text{ then } A!!a \text{ else } A!!n$ ) (*IArray.length A*)

**definition** *mult-row-iarray* :: 'a:{times} iarray iarray => nat => 'a => 'a iarray iarray

**where** *mult-row-iarray A a q* = *IArray.of-fun* ( $\lambda n. \text{if } n=a \text{ then mult-iarray (A!!a) q else A!!n}$ ) (*IArray.length A*)

**definition** *row-add-iarray* :: 'a:{plus, times} iarray iarray => nat => nat => 'a => 'a iarray iarray

**where** *row-add-iarray A a b q* = *IArray.of-fun* ( $\lambda n. \text{if } n=a \text{ then } A!!a + \text{mult-iarray (A!!b) q else A!!n}$ ) (*IArray.length A*)

**definition** *interchange-columns-iarray* :: 'a iarray iarray => nat => nat => 'a iarray iarray

**where** *interchange-columns-iarray A a b* = *tabulate2* (*nrows-iarray A*) (*ncols-iarray A*) ( $\lambda i j. \text{if } j=a \text{ then } A!!i !! b \text{ else if } j=b \text{ then } A!!i !! a \text{ else } A!!i !! j$ )

```

definition mult-column-iarray :: 'a:{times} iarray iarray => nat => 'a => 'a
iarray iarray
where mult-column-iarray A n q = tabulate2 (nrows-iarray A) (ncols-iarray A)
(λi j. if j = n then A !! i !! j * q else A !! i !! j)

definition column-add-iarray :: 'a:{plus, times} iarray iarray => nat => nat
=> 'a => 'a iarray iarray
where column-add-iarray A n m q = tabulate2 (nrows-iarray A) (ncols-iarray
A) (λi j. if j = n then A !! i !! n + A !! i !! m * q else A !! i !! j)

```

### 16.3.1 Code generator

```

lemma vec-to-iarray-plus[code-unfold]: vec-to-iarray (a + b) = (vec-to-iarray a)
+ (vec-to-iarray b)
⟨proof⟩

lemma matrix-to-iarray-plus[code-unfold]: matrix-to-iarray (A + B) = (matrix-to-iarray
A) + (matrix-to-iarray B)
⟨proof⟩

lemma matrix-to-iarray-mat[code-unfold]:
matrix-to-iarray (mat k ::'a:{zero} ^n:{mod-type} ^n:{mod-type}) = mat-iarray
k CARD('n:{mod-type})
⟨proof⟩

lemma matrix-to-iarray-transpose[code-unfold]:
shows matrix-to-iarray (transpose A) = transpose-iarray (matrix-to-iarray A)
⟨proof⟩

lemma matrix-to-iarray-matrix-matrix-mult[code-unfold]:
fixes A::'a:{semiring-1} ^m:{mod-type} ^n:{mod-type} and B::'a ^b:{mod-type} ^m:{mod-type}
shows matrix-to-iarray (A ** B) = (matrix-to-iarray A) **i (matrix-to-iarray
B)
⟨proof⟩

lemma vec-to-iarray-matrix-matrix-mult[code-unfold]:
fixes A::'a:{semiring-1} ^m:{mod-type} ^n:{mod-type} and x::'a ^m:{mod-type}
shows vec-to-iarray (A *v x) = (matrix-to-iarray A) *iv (vec-to-iarray x)
⟨proof⟩

lemma vec-to-iarray-vector-matrix-mult[code-unfold]:
fixes A::'a:{semiring-1} ^m:{mod-type} ^n:{mod-type} and x::'a ^n:{mod-type}
shows vec-to-iarray (x v* A) = (vec-to-iarray x) v*i (matrix-to-iarray A)
⟨proof⟩

lemma matrix-to-iarray-interchange-rows[code-unfold]:

```

```

fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (interchange-rows A i j) = interchange-rows-iarray (matrix-to-iarray
A) (to-nat i) (to-nat j)
⟨proof⟩

lemma matrix-to-iarray-mult-row[code-unfold]:
fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (mult-row A i q) = mult-row-iarray (matrix-to-iarray A)
(to-nat i) q
⟨proof⟩

lemma matrix-to-iarray-row-add[code-unfold]:
fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (row-add A i j q) = row-add-iarray (matrix-to-iarray A)
(to-nat i) (to-nat j) q
⟨proof⟩

lemma matrix-to-iarray-interchange-columns[code-unfold]:
fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (interchange-columns A i j) = interchange-columns-iarray
(matrix-to-iarray A) (to-nat i) (to-nat j)
⟨proof⟩

lemma matrix-to-iarray-mult-columns[code-unfold]:
fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (mult-column A i q) = mult-column-iarray (matrix-to-iarray
A) (to-nat i) q
⟨proof⟩

lemma matrix-to-iarray-column-add[code-unfold]:
fixes A::'a::{semiring-1} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (column-add A i j q) = column-add-iarray (matrix-to-iarray
A) (to-nat i) (to-nat j) q
⟨proof⟩

end

```

## 17 Gauss Jordan algorithm over nested IArrays

```

theory Gauss-Jordan-IArrays
imports
  Matrix-To-IArray
  Gauss-Jordan
begin

```

## 17.1 Definitions and functions to compute the Gauss-Jordan algorithm over matrices represented as nested iarrays

```

definition least-non-zero-position-of-vector-from-index A i = the (List.find ( $\lambda x. A$  !!  $x \neq 0$ ) [i..<IArr.length A])
definition least-non-zero-position-of-vector A = least-non-zero-position-of-vector-from-index A 0

definition vector-all-zero-from-index :: (nat  $\times$  'a::{zero} iarray) => bool
  where vector-all-zero-from-index A' = (let i=fst A'; A=(snd A') in IArr.all ( $\lambda x. A$ !! $x = 0$ ) (IArr [i..<(IArr.length A)]))

definition Gauss-Jordan-in-ij-iarrays :: 'a::{field} iarray iarray => nat => nat
=> 'a iarray iarray
  where Gauss-Jordan-in-ij-iarrays A i j = (let n = least-non-zero-position-of-vector-from-index (column-iarray j A) i;
    interchange-A = interchange-rows-iarray A i n;
    A' = mult-row-iarray interchange-A i (1 / interchange-A !! i !! j)
    in IArr.of-fun ( $\lambda s.$  if  $s = i$  then  $A'$  !!  $s$  else row-add-iarray A' s i (- interchange-A !!  $s$  !! j) !!  $s$ ) (nrows-iarray A))

definition Gauss-Jordan-column-k-iarrays :: (nat  $\times$  'a::{field} iarray iarray) =>
nat => (nat  $\times$  'a iarray iarray)
  where Gauss-Jordan-column-k-iarrays A' k = (let A=(snd A'); i=(fst A') in
if ((vector-all-zero-from-index (i, (column-iarray k A))))  $\vee$  i = (nrows-iarray A) then (i,A) else (Suc i, (Gauss-Jordan-in-ij-iarrays A i k)))

definition Gauss-Jordan-upk-iarrays :: 'a::{field} iarray iarray => nat => 'a::{field}
iarray iarray
  where Gauss-Jordan-upk-iarrays A k = snd (foldl Gauss-Jordan-column-k-iarrays
(0,A) [0..<Suc k])

definition Gauss-Jordan-iarrays :: 'a::{field} iarray iarray => 'a::{field} iarray
iarray
  where Gauss-Jordan-iarrays A = Gauss-Jordan-upk-iarrays A (ncols-iarray A - 1)

```

## 17.2 Proving the equivalence between Gauss-Jordan algorithm over nested iarrays and over nested vecs (abstract matrices).

```

lemma vector-all-zero-from-index-eq:
fixes A::'a::{zero}  $\rightsquigarrow$  n::{mod-type}
shows ( $\forall m \geq i. A \$ m = 0$ ) = (vector-all-zero-from-index (to-nat i, vec-to-iarray A))
  {proof}

lemma matrix-vector-all-zero-from-index:
fixes A::'a::{zero}  $\rightsquigarrow$  columns::{mod-type}  $\rightsquigarrow$  rows::{mod-type}

```

**shows**  $(\forall m \geq i. A \$ m \$ k = 0) = (\text{vector-all-zero-from-index}(\text{to-nat } i, \text{vec-to-iarray}(\text{column } k A)))$   
 $\langle \text{proof} \rangle$

**lemma** *vec-to-iarray-least-non-zero-position-of-vector-from-index*:  
**fixes**  $A :: 'a :: \{\text{zero}\} \rightsquigarrow n :: \{\text{mod-type}\}$   
**assumes** *not-all-zero*:  $\neg (\text{vector-all-zero-from-index}(\text{to-nat } i, \text{vec-to-iarray } A))$   
**shows** *least-non-zero-position-of-vector-from-index* ( $\text{vec-to-iarray } A$ ) ( $\text{to-nat } i$ ) =  
 $\text{to-nat} (\text{LEAST } n. A \$ n \neq 0 \wedge i \leq n)$   
 $\langle \text{proof} \rangle$

**corollary** *vec-to-iarray-least-non-zero-position-of-vector-from-index'*:  
**fixes**  $A :: 'a :: \{\text{zero}\} \rightsquigarrow \text{cols} :: \{\text{mod-type}\} \rightsquigarrow \text{rows} :: \{\text{mod-type}\}$   
**assumes** *not-all-zero*:  $\neg (\text{vector-all-zero-from-index}(\text{to-nat } i, \text{vec-to-iarray}(\text{column } j A)))$   
**shows** *least-non-zero-position-of-vector-from-index* ( $\text{vec-to-iarray}(\text{column } j A)$ ) ( $\text{to-nat } i$ ) =  
 $\text{to-nat} (\text{LEAST } n. A \$ n \$ j \neq 0 \wedge i \leq n)$   
 $\langle \text{proof} \rangle$

**corollary** *vec-to-iarray-least-non-zero-position-of-vector-from-index''*:  
**fixes**  $A :: 'a :: \{\text{zero}\} \rightsquigarrow \text{cols} :: \{\text{mod-type}\} \rightsquigarrow \text{rows} :: \{\text{mod-type}\}$   
**assumes** *not-all-zero*:  $\neg (\text{vector-all-zero-from-index}(\text{to-nat } j, \text{vec-to-iarray}(\text{row } i A)))$   
**shows** *least-non-zero-position-of-vector-from-index* ( $\text{vec-to-iarray}(\text{row } i A)$ ) ( $\text{to-nat } j$ ) =  
 $\text{to-nat} (\text{LEAST } n. A \$ i \$ n \neq 0 \wedge j \leq n)$   
 $\langle \text{proof} \rangle$

**lemma** *matrix-to-iarray-Gauss-Jordan-in-ij[code-unfold]*:  
**fixes**  $A :: 'a :: \{\text{field}\} \rightsquigarrow \text{columns} :: \{\text{mod-type}\} \rightsquigarrow \text{rows} :: \{\text{mod-type}\}$   
**assumes** *not-all-zero*:  $\neg (\text{vector-all-zero-from-index}(\text{to-nat } i, \text{vec-to-iarray}(\text{column } j A)))$   
**shows** *matrix-to-iarray* ( $\text{Gauss-Jordan-in-ij } A i j$ ) = *Gauss-Jordan-in-ij-arrays*  
 $(\text{matrix-to-iarray } A)$  ( $\text{to-nat } i$ ) ( $\text{to-nat } j$ )  
 $\langle \text{proof} \rangle$

**lemma** *matrix-to-iarray-Gauss-Jordan-column-k-1*:  
**fixes**  $A :: 'a :: \{\text{field}\} \rightsquigarrow \text{columns} :: \{\text{mod-type}\} \rightsquigarrow \text{rows} :: \{\text{mod-type}\}$   
**assumes**  $k : k < \text{ncols } A$   
**and**  $i : i \leq \text{nrows } A$   
**shows**  $(\text{fst } (\text{Gauss-Jordan-column-}k(i, A) k)) = \text{fst } (\text{Gauss-Jordan-column-}k\text{-iarrays}(i, \text{matrix-to-iarray } A) k)$   
 $\langle \text{proof} \rangle$

**lemma** *matrix-to-iarray-Gauss-Jordan-column-k-2*:

```

fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
assumes k: k < ncols A
and i: i ≤ nrows A
shows matrix-to-iarray (snd (Gauss-Jordan-column-k (i, A) k)) = snd (Gauss-Jordan-column-k-iarrays
(i, matrix-to-iarray A) k)
⟨proof⟩

```

Due to the assumptions presented in  $\llbracket ?k < \text{ncols } ?A; ?i \leq \text{nrows } ?A \rrbracket$   
 $\implies \text{matrix-to-iarray} (\text{snd} (\text{Gauss-Jordan-column-k} (?i, ?A) ?k)) = \text{snd} (\text{Gauss-Jordan-column-k-iarrays} (?i, \text{matrix-to-iarray} ?A) ?k)$ , the following lemma must have three shows. The proof style is similar to  $?k < \text{ncols } ?A \implies \text{reduced-row-echelon-form-upk} (\text{Gauss-Jordan-upk} ?A ?k) (\text{Suc } ?k)$

$?k < \text{ncols } ?A \implies \text{foldl Gauss-Jordan-column-k} (0, ?A) [0..<\text{Suc } ?k] =$   
 $(\text{if } \forall m. \text{is-zero-row-upk } m (\text{Suc } ?k) (\text{snd} (\text{foldl Gauss-Jordan-column-k} (0, ?A) [0..<\text{Suc } ?k])) \text{ then } 0 \text{ else } \text{mod-type-class.to-nat} (\text{GREATEST } n.$   
 $\neg \text{is-zero-row-upk } n (\text{Suc } ?k) (\text{snd} (\text{foldl Gauss-Jordan-column-k} (0, ?A) [0..<\text{Suc } ?k]))) + 1,$   
 $\text{snd} (\text{foldl Gauss-Jordan-column-k} (0, ?A) [0..<\text{Suc } ?k]))).$

```

lemma foldl-Gauss-Jordan-column-k-eq:
fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
assumes k: k < ncols A
shows matrix-to-iarray-Gauss-Jordan-upk[code-unfold]: matrix-to-iarray (Gauss-Jordan-upk
A k) = Gauss-Jordan-upk-iarrays (matrix-to-iarray A) k
and fst-foldl-Gauss-Jordan-column-k-eq: fst (foldl Gauss-Jordan-column-k-iarrays
(0, matrix-to-iarray A) [0..<\text{Suc } k]) = fst (foldl Gauss-Jordan-column-k (0, A)
[0..<\text{Suc } k])
and fst-foldl-Gauss-Jordan-column-k-less: fst (foldl Gauss-Jordan-column-k (0,
A) [0..<\text{Suc } k]) ≤ nrows A
⟨proof⟩

```

```

lemma matrix-to-iarray-Gauss-Jordan[code-unfold]:
fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
shows matrix-to-iarray (Gauss-Jordan A) = Gauss-Jordan-iarrays (matrix-to-iarray
A)
⟨proof⟩

```

### 17.3 Implementation over IArrays of the computation of the rank of a matrix

```

definition rank-iarray :: 'a::{field} iarray iarray => nat
where rank-iarray A = (let A' = (Gauss-Jordan-iarrays A); nrows = (IArray.length
A') in card {i. i < nrows ∧ ¬ is-zero-iarray (A' !! i)})

```

### 17.3.1 Proving the equivalence between rank and rank-iarray.

First of all, some code equations are removed to allow the execution of Gauss-Jordan algorithm using iarrays

```
lemmas card'-code(2)[code del]
lemmas rank-Gauss-Jordan-code[code del]
```

```
lemma rank-eq-card-iarrays:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows rank A = card {vec-to-iarray (row i (Gauss-Jordan A)) | i. ¬ is-zero-iarray (vec-to-iarray (row i (Gauss-Jordan A)))}
  ⟨proof⟩
```

```
lemma rank-eq-card-iarrays':
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows rank A = (let A' = (Gauss-Jordan-iarrays (matrix-to-iarray A)) in card {row-iarray (to-nat i) A' | i:'rows. ¬ is-zero-iarray (A' !! (to-nat i))})
  ⟨proof⟩
```

```
lemma rank-eq-card-iarrays-code:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows rank A = (let A' = (Gauss-Jordan-iarrays (matrix-to-iarray A)) in card {i:'rows. ¬ is-zero-iarray (A' !! (to-nat i))})
  ⟨proof⟩
```

### 17.3.2 Code equations for computing the rank over nested iarrays and the dimensions of the elementary subspaces

```
lemma rank-iarrays-code[code]:
  rank-iarray A = length (filter (λx. ¬ is-zero-iarray x) (IArray.list-of (Gauss-Jordan-iarrays A)))
  ⟨proof⟩
```

```
lemma matrix-to-iarray-rank[code-unfold]:
  shows rank A = rank-iarray (matrix-to-iarray A)
  ⟨proof⟩
```

```
lemma dim-null-space-iarray[code-unfold]:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows vec.dim (null-space A) = ncols-iarray (matrix-to-iarray A) - rank-iarray (matrix-to-iarray A)
  ⟨proof⟩
```

```
lemma dim-col-space-iarray[code-unfold]:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows vec.dim (col-space A) = rank-iarray (matrix-to-iarray A)
  ⟨proof⟩
```

```

lemma dim-row-space-iarray[code-unfold]:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows vec.dim (row-space A) = rank-iarray (matrix-to-iarray A)
  ⟨proof⟩

lemma dim-left-null-space-space-iarray[code-unfold]:
  fixes A::'a::{field} ^'columns::{mod-type} ^'rows::{mod-type}
  shows vec.dim (left-null-space A) = nrows-iarray (matrix-to-iarray A) - rank-iarray
  (matrix-to-iarray A)
  ⟨proof⟩

end

```

## 18 Obtaining explicitly the invertible matrix which transforms a matrix to its reduced row echelon form over nested iarrays

```

theory Gauss-Jordan-PA-IArrays
imports
  Gauss-Jordan-PA
  Gauss-Jordan-IArrays
begin

```

### 18.1 Definitions

```

definition Gauss-Jordan-in-ij-iarrays-PA A' i j =
(let P = fst A'; A = snd A'; n = least-non-zero-position-of-vector-from-index
(column-iarray j A) i; interchange-A = interchange-rows-iarray A i n;
interchange-P = interchange-rows-iarray P i n; P' = mult-row-iarray interchange-P
i (1 / interchange-A !! i !! j)
in (IArray.of-fun (λs. if s = i then P' !! s else row-add-iarray P' s i (- interchange-A !! s !! j) !! s) (nrows-iarray A), Gauss-Jordan-in-ij-iarrays A i j))

definition Gauss-Jordan-column-k-iarrays-PA :: ('a::{field} iarray iarray × nat ×
'a::{field} iarray iarray) => nat => ('a iarray iarray × nat × 'a iarray iarray)
where Gauss-Jordan-column-k-iarrays-PA A' k = (let P = fst A'; i = fst (snd A');
A = snd (snd A') in
if (vector-all-zero-from-index (i, (column-iarray k A))) ∨ i = (nrows-iarray A)
then (P, i, A) else let Gauss = Gauss-Jordan-in-ij-iarrays-PA (P, A) i k
in (fst Gauss, i + 1, snd Gauss))

definition Gauss-Jordan-upk-iarrays-PA :: 'a::{field} iarray iarray => nat =>
('a::{field} iarray iarray × 'a iarray iarray)
where Gauss-Jordan-upk-iarrays-PA A k = (let foldl = foldl Gauss-Jordan-column-k-iarrays-PA
(mat-iarray 1 (nrows-iarray A), 0, A) [0..<Suc k] in (fst foldl, snd (snd foldl)))

```

```

definition Gauss-Jordan-iarrays-PA :: 'a::{field} iarray iarray => ('a iarray iarray
ray × 'a iarray iarray)
where Gauss-Jordan-iarrays-PA A = Gauss-Jordan-upk-iarrays-PA A (ncols-iarray
A - 1)

```

## 18.2 Proofs

### 18.2.1 Properties of Gauss-Jordan-in-ij-iarrays-PA

```

lemma Gauss-Jordan-in-ij-iarrays-PA-def'[code]:
Gauss-Jordan-in-ij-iarrays-PA A' i j =
(let P = fst A'; A = snd A'; n = least-non-zero-position-of-vector-from-index
(column-iarray j A) i;
interchange-A = interchange-rows-iarray A i n; A' = mult-row-iarray inter-
change-A i (1 / interchange-A !! i !! j);
interchange-P = interchange-rows-iarray P i n; P' = mult-row-iarray inter-
change-P i (1 / interchange-A !! i !! j)
in (IArray.of-fun (λs. if s = i then P' !! s else row-add-iarray P' s i (- inter-
change-A !! s !! j) !! s) (nrows-iarray A),
(IArray.of-fun (λs. if s = i then A' !! s else row-add-iarray A' s i (- inter-
change-A !! s !! j) !! s) (nrows-iarray A)))
⟨proof⟩

```

```

lemma snd-Gauss-Jordan-in-ij-iarrays-PA:
shows snd (Gauss-Jordan-in-ij-iarrays-PA (P, A) i j) = Gauss-Jordan-in-ij-iarrays
A i j
⟨proof⟩

```

```

lemma matrix-to-iarray-snd-Gauss-Jordan-in-ij-iarrays-PA:
assumes ¬ vector-all-zero-from-index (to-nat i, vec-to-iarray (column j A))
shows matrix-to-iarray (snd (Gauss-Jordan-in-ij-PA (P, A) i j)) = snd (Gauss-Jordan-in-ij-iarrays-PA
(matrix-to-iarray P, matrix-to-iarray A) (to-nat i) (to-nat j))
⟨proof⟩

```

```

lemma matrix-to-iarray-fst-Gauss-Jordan-in-ij-iarrays-PA:
assumes not-all-zero: ¬ vector-all-zero-from-index (to-nat i, vec-to-iarray (column
j A))
shows matrix-to-iarray (fst (Gauss-Jordan-in-ij-PA (P, A) i j)) = fst (Gauss-Jordan-in-ij-iarrays-PA
(matrix-to-iarray P, matrix-to-iarray A) (to-nat i) (to-nat j))
⟨proof⟩

```

### 18.2.2 Properties about Gauss-Jordan-column-k-iarrays-PA

```

lemma matrix-to-iarray-fst-Gauss-Jordan-column-k-PA:
assumes i: i ≤ nrows A and k: k < ncols A
shows matrix-to-iarray (fst (Gauss-Jordan-column-k-PA (P, i, A) k)) = fst (Gauss-Jordan-column-k-iarrays-PA
(matrix-to-iarray P, i, matrix-to-iarray A) k)
⟨proof⟩

```

```

lemma matrix-to-iarray-snd-Gauss-Jordan-column-k-PA:
assumes i:  $i \leq \text{nrows } A$  and k:  $k < \text{ncols } A$ 
shows ( $\text{fst}(\text{snd}(\text{Gauss-Jordan-column-}k\text{-PA}(P, i, A) k))) = \text{fst}(\text{snd}(\text{Gauss-Jordan-column-}k\text{-iarrays-PA}($   

 $(\text{matrix-to-iarray } P, i, \text{matrix-to-iarray } A) k))$ 
⟨proof⟩

lemma matrix-to-iarray-third-Gauss-Jordan-column-k-PA:
assumes i:  $i \leq \text{nrows } A$  and k:  $k < \text{ncols } A$ 
shows matrix-to-iarray ( $\text{snd}(\text{snd}(\text{Gauss-Jordan-column-}k\text{-PA}(P, i, A) k))) = \text{snd}$   

 $(\text{snd}(\text{Gauss-Jordan-column-}k\text{-iarrays-PA}(\text{matrix-to-iarray } P, i, \text{matrix-to-iarray } A) k))$ 
⟨proof⟩

```

### 18.2.3 Properties about Gauss-Jordan-upt-k-iarrays-PA

```

lemma
assumes k:  $k < \text{ncols } A$ 
shows matrix-to-iarray-fst-Gauss-Jordan-upt-k-PA: matrix-to-iarray ( $\text{fst}(\text{Gauss-Jordan-upt-}k\text{-PA}$   

 $A k)) = \text{fst}(\text{Gauss-Jordan-upt-}k\text{-iarrays-PA}(\text{matrix-to-iarray } A) k)$ 
and matrix-to-iarray-snd-Gauss-Jordan-upt-k-PA: matrix-to-iarray ( $\text{snd}(\text{Gauss-Jordan-upt-}k\text{-PA}$   

 $A k)) = (\text{snd}(\text{Gauss-Jordan-upt-}k\text{-iarrays-PA}(\text{matrix-to-iarray } A) k))$ 
and fst ( $\text{snd}(\text{foldl Gauss-Jordan-column-}k\text{-PA}(\text{mat } 1, 0, A) [0..<\text{Suc } k])) =$   

 $\text{fst}(\text{snd}(\text{foldl Gauss-Jordan-column-}k\text{-iarrays-PA}(\text{mat-iarray } 1(\text{nrows-iarray}$   

 $(\text{matrix-to-iarray } A)), 0, \text{matrix-to-iarray } A) [0..<\text{Suc } k]))$ 
and fst ( $\text{snd}(\text{foldl Gauss-Jordan-column-}k\text{-PA}(\text{mat } 1, 0, A) [0..<\text{Suc } k])) \leq \text{nrows}$   

 $A$ 
⟨proof⟩

```

### 18.2.4 Properties about Gauss-Jordan-iarrays-PA

```

lemma matrix-to-iarray-fst-Gauss-Jordan-PA:
shows matrix-to-iarray ( $\text{fst}(\text{Gauss-Jordan-PA } A)) = \text{fst}(\text{Gauss-Jordan-iarrays-PA}$   

 $(\text{matrix-to-iarray } A))$ 
⟨proof⟩

```

```

lemma matrix-to-iarray-snd-Gauss-Jordan-PA:
shows matrix-to-iarray ( $\text{snd}(\text{Gauss-Jordan-PA } A)) = \text{snd}(\text{Gauss-Jordan-iarrays-PA}$   

 $(\text{matrix-to-iarray } A))$ 
⟨proof⟩

```

```

lemma Gauss-Jordan-iarrays-PA-mult:
fixes A::'a::{field}  $\wedge$  cols::{mod-type}  $\wedge$  rows::{mod-type}
shows  $\text{snd}(\text{Gauss-Jordan-iarrays-PA}(\text{matrix-to-iarray } A)) = \text{fst}(\text{Gauss-Jordan-iarrays-PA}$   

 $(\text{matrix-to-iarray } A)) ** i(\text{matrix-to-iarray } A)$ 
⟨proof⟩

```

```

lemma snd-snd-Gauss-Jordan-column-k-iarrays-PA-eq:
shows snd (snd (Gauss-Jordan-column-k-iarrays-PA (P,i,A) k)) = snd (Gauss-Jordan-column-k-iarrays (i,A) k)
<proof>

lemma fst-snd-Gauss-Jordan-column-k-iarrays-PA-eq:
shows fst (snd (Gauss-Jordan-column-k-iarrays-PA (P,i,A) k)) = fst (Gauss-Jordan-column-k-iarrays (i,A) k)
<proof>

lemma foldl-Gauss-Jordan-column-k-iarrays-eq:
shows snd (foldl Gauss-Jordan-column-k-iarrays-PA (B, 0, A) [0..<k]) = foldl Gauss-Jordan-column-k-iarrays (0, A) [0..<k]
<proof>

lemma snd-Gauss-Jordan-upk-iarrays-PA:
shows snd (Gauss-Jordan-upk-iarrays-PA A k) = (Gauss-Jordan-upk-iarrays A k)
<proof>

lemma snd-Gauss-Jordan-iarrays-PA-eq: snd (Gauss-Jordan-iarrays-PA A) = Gauss-Jordan-iarrays A
<proof>

end

```

## 19 Bases of the four fundamental subspaces over IArrays

```

theory Bases-Of-Fundamental-Subspaces-IArrays
imports
  Bases-Of-Fundamental-Subspaces
  Gauss-Jordan-PA-IArrays
begin

```

### 19.1 Computation of bases of the fundamental subspaces using IArrays

We have made the definitions as efficient as possible.

```

definition basis-left-null-space-iarrays A
  = (let GJ = Gauss-Jordan-iarrays-PA A;
    rank-A = length [x←IArray.list-of (snd GJ) . ⊢ is-zero-iarray x]
    in set (map (λi. row-iarray i (fst GJ)) [(rank-A)..<(nrows-iarray A)]))
definition basis-null-space-iarrays A

```

```

= (let GJ= Gauss-Jordan-iarrays-PA (transpose-iarray A);
   rank-A = length [x←IArray.list-of (snd GJ) . ¬ is-zero-iarray x]
   in set (map (λi. row-iarray i (fst GJ)) [(rank-A)..<(ncols-iarray A)]))

definition basis-row-space-iarrays A =
  (let GJ= Gauss-Jordan-iarrays A;
   rank-A = length [x←IArray.list-of (GJ) . ¬ is-zero-iarray x]
   in set (map (λi. row-iarray i (GJ)) [0..<rank-A]))

definition basis-col-space-iarrays A = basis-row-space-iarrays (transpose-iarray A)

```

The following lemmas make easier the proofs of equivalence between abstract versions and concrete versions. They are false if we remove *matrix-to-iarray*

```

lemma basis-null-space-iarrays-eq:
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
shows basis-null-space-iarrays (matrix-to-iarray A)
  = set (map (λi. row-iarray i (fst (Gauss-Jordan-iarrays-PA (transpose-iarray
  (matrix-to-iarray A)))))) [(rank-iarray (matrix-to-iarray A))..<(ncols-iarray (matrix-to-iarray
  A))])
  ⟨proof⟩

```

```

lemma basis-row-space-iarrays-eq:
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
shows basis-row-space-iarrays (matrix-to-iarray A) = set (map (λi. row-iarray i
(Gauss-Jordan-iarrays (matrix-to-iarray A))) [0..<(rank-iarray (matrix-to-iarray
A))])
  ⟨proof⟩

```

```

lemma basis-left-null-space-iarrays-eq:
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
shows basis-left-null-space-iarrays (matrix-to-iarray A) = basis-null-space-iarrays
(transpose-iarray (matrix-to-iarray A))
  ⟨proof⟩

```

## 19.2 Code equations

```

lemma vec-to-iarray-basis-null-space[code-unfold]:
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
shows vec-to-iarray‘(basis-null-space A) = basis-null-space-iarrays (matrix-to-iarray
A)
  ⟨proof⟩

```

```

corollary vec-to-iarray-basis-left-null-space[code-unfold]:
fixes A::'a:{field} ^'cols:{mod-type} ^'rows:{mod-type}
shows vec-to-iarray‘(basis-left-null-space A) = basis-left-null-space-iarrays (matrix-to-iarray
A)
  ⟨proof⟩

```

```

lemma vec-to-iarray-basis-row-space[code-unfold]:

```

```

fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows vec-to-iarray` (basis-row-space A) = basis-row-space-iarrays (matrix-to-iarray
A)
⟨proof⟩

```

```

corollary vec-to-iarray-basis-col-space[code-unfold]:
fixes A::'a::{field} ^'cols::{mod-type} ^'rows::{mod-type}
shows vec-to-iarray` (basis-col-space A) = basis-col-space-iarrays (matrix-to-iarray
A)
⟨proof⟩
end

```

## 20 Solving systems of equations using the Gauss Jordan algorithm over nested IArrays

```

theory System-Of-Equations-IArrays
imports
  System-Of-Equations
  Bases-Of-Fundamental-Subspaces-IArrays
begin

```

### 20.1 Previous definitions and properties

```

definition greatest-not-zero :: 'a::{zero} iarray => nat
  where greatest-not-zero A = the (List.find (λn. A !! n ≠ 0) (rev [0..<IArray.length A]))

```

```

lemma vec-to-iarray-exists:
shows (exists b. A $ b ≠ 0) = IArray.exists (λb. (vec-to-iarray A) !! b ≠ 0) (IArray[0..<IArray.length (vec-to-iarray A)])
⟨proof⟩

```

```

corollary vec-to-iarray-exists':
shows (exists b. A $ b ≠ 0) = IArray.exists (λb. (vec-to-iarray A) !! b ≠ 0) (IArray
(rev [0..<IArray.length (vec-to-iarray A)]))
⟨proof⟩

```

```

lemma not-is-zero-iarray-eq-iff: (exists b. A $ b ≠ 0) = (¬ is-zero-iarray (vec-to-iarray
A))
⟨proof⟩

```

```

lemma vec-to-iarray-greatest-not-zero:
assumes ex-b: (exists b. A $ b ≠ 0)
shows greatest-not-zero (vec-to-iarray A) = to-nat (GREATEST b. A $ b ≠ 0)
⟨proof⟩

```

## 20.2 Consistency and inconsistency

```

definition consistent-iarrays A b = (let GJ=Gauss-Jordan-iarrays-PA A;
                                         rank-A = length [x←IArray.list-of (snd GJ) . ¬
                                         is-zero-iarray x];
                                         P-mult-b = fst(GJ) *iv b
                                         in (rank-A ≥ (if (¬ is-zero-iarray P-mult-b)
                                         then (greatest-not-zero P-mult-b + 1) else 0)))
                                         )
                                         
```

**definition** inconsistent-iarrays A b = (¬ consistent-iarrays A b)

**lemma** matrix-to-iarray-consistent[code]: consistent A b = consistent-iarrays (matrix-to-iarray A) (vec-to-iarray b)  
 $\langle proof \rangle$

**lemma** matrix-to-iarray-inconsistent[code]: inconsistent A b = inconsistent-iarrays (matrix-to-iarray A) (vec-to-iarray b)  
 $\langle proof \rangle$

```

definition solve-consistent-rref-iarrays A b
= IArray.of-fun (λj. if (IArray.exists (λi. A !! i !! j = 1 ∧ j = least-non-zero-position-of-vector
                                         (row-iarray i A)) (IArray[0..<nrows-iarray A]))
                                         then b !! (least-non-zero-position-of-vector (column-iarray j A)) else 0) (ncols-iarray
                                         A)
                                         
```

**lemma** exists-solve-consistent-rref:  
**fixes** A::'a:{field} ^'cols::{mod-type} ^'rows::{mod-type}  
**assumes** rref: reduced-row-echelon-form A  
**shows** (exists i. A \$ i \$ j = 1 ∧ j = (LEAST n. A \$ i \$ n ≠ 0))
= (IArray.exists (λi. (matrix-to-iarray A) !! i !! (to-nat j) = 1
∧ (to-nat j) = least-non-zero-position-of-vector (row-iarray i (matrix-to-iarray A)))
(IArray[0..<nrows-iarray (matrix-to-iarray A)]))
 $\langle proof \rangle$

**lemma** to-nat-the-solve-consistent-rref:  
**fixes** A::'a:{field} ^'cols::{mod-type} ^'rows::{mod-type}  
**assumes** rref: reduced-row-echelon-form A  
**and exists:** (exists i. A \$ i \$ j = 1 ∧ j = (LEAST n. A \$ i \$ n ≠ 0))
**shows** to-nat (THE i. A \$ i \$ j = 1) = least-non-zero-position-of-vector (column-iarray
(to-nat j) (matrix-to-iarray A))
 $\langle proof \rangle$

**lemma** iarray-exhaust2:  
(xs = ys) = (IArray.list-of xs = IArray.list-of ys)
 $\langle proof \rangle$

```

lemma vec-to-iarray-solve-consistent-rref:
  fixes A::'a::{field} ^ cols::{mod-type} ^ rows::{mod-type}
  assumes rref: reduced-row-echelon-form A
  shows vec-to-iarray (solve-consistent-rref A b) = solve-consistent-rref-iarrays (matrix-to-iarray
A) (vec-to-iarray b)
  ⟨proof⟩

```

### 20.3 Independence and dependence

```

definition independent-and-consistent-iarrays A b =
  (let GJ = Gauss-Jordan-iarrays-PA A;
   rank-A = length [x←IArray.list-of (snd GJ) . ¬ is-zero-iarray x];
   P-mult-b = fst GJ *iv b;
   consistent-A = ((if ¬ is-zero-iarray P-mult-b then greatest-not-zero P-mult-b
+ 1 else 0) ≤ rank-A);
   dim-solution-set = ncols-iarray A - rank-A
   in consistent-A ∧ dim-solution-set = 0)

```

```

definition dependent-and-consistent-iarrays A b =
  (let GJ = Gauss-Jordan-iarrays-PA A;
   rank-A = length [x←IArray.list-of (snd GJ) . ¬ is-zero-iarray x];
   P-mult-b = fst GJ *iv b;
   consistent-A = ((if ¬ is-zero-iarray P-mult-b then greatest-not-zero P-mult-b
+ 1 else 0) ≤ rank-A);
   dim-solution-set = ncols-iarray A - rank-A
   in consistent-A ∧ dim-solution-set > 0)

```

```

lemma matrix-to-iarray-independent-and-consistent[code]:
  shows independent-and-consistent A b = independent-and-consistent-iarrays (matrix-to-iarray
A) (vec-to-iarray b)
  ⟨proof⟩

```

```

lemma matrix-to-iarray-dependent-and-consistent[code]:
  shows dependent-and-consistent A b = dependent-and-consistent-iarrays (matrix-to-iarray
A) (vec-to-iarray b)
  ⟨proof⟩

```

### 20.4 Solve a system of equations over nested IArrays

```

definition solve-system-iarrays A b = (let A' = Gauss-Jordan-iarrays-PA A in
(snd A', fst A' *iv b))

```

```

lemma matrix-to-iarray-fst-solve-system: matrix-to-iarray (fst (solve-system A b))
= fst (solve-system-iarrays (matrix-to-iarray A) (vec-to-iarray b))
  ⟨proof⟩

```

```

lemma vec-to-iarray-snd-solve-system: vec-to-iarray (snd (solve-system A b)) =
snd (solve-system-iarrays (matrix-to-iarray A) (vec-to-iarray b))
  ⟨proof⟩

```

```

definition solve-iarrays A b = (let GJ-P=Gauss-Jordan-iarrays-PA A;
                                P-mult-b = fst GJ-P *iv b;
                                rank-A = length [x←IArray.list-of (snd GJ-P) . ¬ is-zero-iarray
x];
                                consistent-Ab = (if ¬ is-zero-iarray P-mult-b then greatest-not-zero
P-mult-b + 1 else 0) ≤ rank-A;
                                GJ transpose = Gauss-Jordan-iarrays-PA (transpose-iarray A);
                                basis = set (map (λi. row-iarray i (fst GJ transpose))
[rank-A..<ncols-iarray A])
                                in (if consistent-Ab then Some (solve-consistent-rref-iarrays
(snd GJ-P) P-mult-b,basis) else None))

definition pair-vec-vecset A = (if Option.is-none A then None else Some (vec-to-iarray
(fst (the A)), vec-to-iarray‘ (snd (the A)))))

lemma pair-vec-vecset-solve[code-unfold]:
shows pair-vec-vecset (solve A b) = solve-iarrays (matrix-to-iarray A) (vec-to-iarray
b)
⟨proof⟩

end

```

## 21 Computing determinants of matrices using the Gauss Jordan algorithm over nested IArrays

```

theory Determinants-IArrays
imports
  Determinants2
  Gauss-Jordan-IArrays
begin

```

### 21.1 Definitions

```

definition Gauss-Jordan-in-ij-det-P-iarrays A i j = (let n = least-non-zero-position-of-vector-from-index
(column-iarray j A) i
  in (if i = n then 1 / A !! i !! j else - 1 / A !! n !! j, Gauss-Jordan-in-ij-iarrays
A i j))

definition Gauss-Jordan-column-k-det-P-iarrays A' k = (let det-P = fst A'; i =
fst (snd A'); A = snd (snd A')
  in if vector-all-zero-from-index (i, column-iarray k A) ∨ i = nrows-iarray A then
(det-P, i, A)
  else let gauss = Gauss-Jordan-in-ij-det-P-iarrays A i k in (fst gauss * det-P, i
+ 1, snd gauss))

definition Gauss-Jordan-upk-det-P-iarrays A k = (let foldl = foldl Gauss-Jordan-column-k-det-P-iarrays

```

$(1, 0, A) [0..<Suc k] in (fst foldl, snd (snd foldl))$   
**definition**  $Gauss-Jordan-det-P-iarrays A = Gauss-Jordan-upt-k-det-P-iarrays A$   
 $(nrows-iarray A - 1)$

## 21.2 Proofs

A more efficient equation for  $Gauss-Jordan-in-ij-det-P-iarrays A i j$ .

**lemma**  $Gauss-Jordan-in-ij-det-P-iarrays-code[code]: Gauss-Jordan-in-ij-det-P-iarrays A i j$   
 $= (let n = least-non-zero-position-of-vector-from-index (column-iarray j A) i;$   
 $interchange-A = interchange-rows-iarray A i n;$   
 $A' = mult-row-iarray interchange-A i (1 / interchange-A !! i !! j)$   
 $in (if i = n then 1 / A !! j else -1 / A !! n !! j, IArray.of-fun (\lambda s. if s = i$   
 $then A' !! s else row-add-iarray A' s i (- interchange-A !! s !! j) !! s) (nrows-iarray A))$   
 $\langle proof \rangle$

**lemma**  $matrix-to-iarray-fst-Gauss-Jordan-in-ij-det-P:$   
**assumes**  $ex-n: \exists n. A \$ n \$ j \neq 0 \wedge i \leq n$   
**shows**  $fst (Gauss-Jordan-in-ij-det-P A i j) = fst (Gauss-Jordan-in-ij-det-P-iarrays (matrix-to-iarray A) (to-nat i) (to-nat j))$   
 $\langle proof \rangle$

**corollary**  $matrix-to-iarray-fst-Gauss-Jordan-in-ij-det-P':$   
**assumes**  $\neg (vector-all-zero-from-index (to-nat i, vec-to-iarray (column j A)))$   
**shows**  $fst (Gauss-Jordan-in-ij-det-P A i j) = fst (Gauss-Jordan-in-ij-det-P-iarrays (matrix-to-iarray A) (to-nat i) (to-nat j))$   
 $\langle proof \rangle$

**lemma**  $matrix-to-iarray-snd-Gauss-Jordan-in-ij-det-P:$   
**assumes**  $ex-n: \exists n. A \$ n \$ j \neq 0 \wedge i \leq n$   
**shows**  $matrix-to-iarray (snd (Gauss-Jordan-in-ij-det-P A i j)) = snd (Gauss-Jordan-in-ij-det-P-iarrays (matrix-to-iarray A) (to-nat i) (to-nat j))$   
 $\langle proof \rangle$

**lemma**  $matrix-to-iarray-fst-Gauss-Jordan-column-k-det-P:$   
**assumes**  $i: i \leq nrows A \text{ and } k: k < ncols A$   
**shows**  $fst (Gauss-Jordan-column-k-det-P (n, i, A) k) = fst (Gauss-Jordan-column-k-det-P-iarrays (n, i, matrix-to-iarray A) k)$   
 $\langle proof \rangle$

**lemma**  $matrix-to-iarray-fst-snd-Gauss-Jordan-column-k-det-P:$   
**assumes**  $i: i \leq nrows A \text{ and } k: k < ncols A$   
**shows**  $fst (snd (Gauss-Jordan-column-k-det-P (n, i, A) k)) = fst (snd (Gauss-Jordan-column-k-det-P-iarrays (n, i, matrix-to-iarray A) k))$   
 $\langle proof \rangle$

```

lemma matrix-to-iarray-snd-snd-Gauss-Jordan-column-k-det-P:
assumes i:  $i \leq \text{nrows } A$  and k:  $k < \text{ncols } A$ 
shows matrix-to-iarray (snd (snd (Gauss-Jordan-column-k-det-P (n, i, A) k))) =
  snd (snd (Gauss-Jordan-column-k-det-P-iarrays (n, i, matrix-to-iarray A) k))
  ⟨proof⟩

```

```

lemma fst-snd-Gauss-Jordan-column-k-det-P-le-nrows:
assumes i:  $i \leq \text{nrows } A$ 
shows fst (snd (Gauss-Jordan-column-k-det-P (n, i, A) k))  $\leq \text{nrows } A$ 
  ⟨proof⟩

```

The proof of the following theorem is very similar to the ones of *foldl-Gauss-Jordan-column-k-eq*, *rref-and-index-Gauss-Jordan-upt-k* and *foldl-Gauss-Jordan-column-k-det-P*.

```

lemma
assumes k < ncols A
shows matrix-to-iarray-fst-Gauss-Jordan-upt-k-det-P: fst (Gauss-Jordan-upt-k-det-P
A k) = fst (Gauss-Jordan-upt-k-det-P-iarrays (matrix-to-iarray A) k)
and matrix-to-iarray-snd-Gauss-Jordan-upt-k-det-P: matrix-to-iarray (snd (Gauss-Jordan-upt-k-det-P
A k)) = snd (Gauss-Jordan-upt-k-det-P-iarrays (matrix-to-iarray A) k)
and fst (snd (foldl Gauss-Jordan-column-k-det-P (1, 0, A) [0..<Suc k]))  $\leq \text{nrows } A$ 
and fst (snd (foldl Gauss-Jordan-column-k-det-P-iarrays (1, 0, matrix-to-iarray A)
[0..<Suc k])) = fst (snd (foldl Gauss-Jordan-column-k-det-P (1, 0, A) [0..<Suc
k]))
  ⟨proof⟩

```

```

lemma matrix-to-iarray-fst-Gauss-Jordan-det-P:
shows fst (Gauss-Jordan-det-P A) = fst (Gauss-Jordan-det-P-iarrays (matrix-to-iarray
A))
  ⟨proof⟩

```

```

lemma matrix-to-iarray-snd-Gauss-Jordan-det-P:
shows matrix-to-iarray (snd (Gauss-Jordan-det-P A)) = snd (Gauss-Jordan-det-P-iarrays
(matrix-to-iarray A))
  ⟨proof⟩

```

### 21.3 Code equations

```

definition det-iarrays A = (let A' = Gauss-Jordan-det-P-iarrays A in prod-list
  (map (λi. (snd A') !! i !! i) [0..<nrows-iarray A]) / fst A')

```

```

lemma matrix-to-iarray-det[code-unfold]:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
shows det A = det-iarrays (matrix-to-iarray A)
  ⟨proof⟩

```

```
end
```

## 22 Inverse of a matrix using the Gauss Jordan algorithm over nested IArrays

```
theory Inverse-IArrays
imports
  Inverse
  Gauss-Jordan-PA-IArrays
begin
```

### 22.1 Definitions

```
definition invertible-iarray A = (rank-iarray A = nrows-iarray A)
definition inverse-matrix-iarray A = (if invertible-iarray A then Some(fst(Gauss-Jordan-iarrays-PA A)) else None)
definition matrix-to-iarray-option A = (if A ≠ None then Some (matrix-to-iarray (the A)) else None)
```

### 22.2 Some lemmas and code generation

```
lemma matrix-inv-Gauss-Jordan-iarrays-PA:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
assumes inv-A: invertible A
shows matrix-to-iarray (matrix-inv A) = fst (Gauss-Jordan-iarrays-PA (matrix-to-iarray A))
⟨proof⟩

lemma matrix-to-iarray-invertible[code-unfold]:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
shows invertible A = invertible-iarray (matrix-to-iarray A)
⟨proof⟩

lemma matrix-to-iarray-option-inverse-matrix:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
shows matrix-to-iarray-option (inverse-matrix A) = (inverse-matrix-iarray (matrix-to-iarray A))
⟨proof⟩

lemma matrix-to-iarray-option-inverse-matrix-code[code-unfold]:
fixes A::'a::{field} ^'n::{mod-type} ^'n::{mod-type}
shows matrix-to-iarray-option (inverse-matrix A) = (let matrix-to-iarray-A = matrix-to-iarray A; GJ = Gauss-Jordan-iarrays-PA matrix-to-iarray-A
in if nrows-iarray matrix-to-iarray-A = length [x←IArray.list-of (snd GJ) . ¬
is-zero-iarray x] then Some (fst GJ) else None)
⟨proof⟩

lemma[code-unfold]:
```

```

shows inverse-matrix-iarray A = (let A' = (Gauss-Jordan-iarrays-PA A); nrows
= IArray.length A in
  (if length [x←IArray.list-of (snd A') . ¬ is-zero-iarray x]
= nrows
    then Some (fst A') else None))
⟨proof⟩
end

```

## 23 Examples of computations over matrices represented as nested IArrays

```

theory Examples-Gauss-Jordan-IArrays
imports
  System-Of-Equations-IArrays
  Determinants-IArrays
  Inverse-IArrays
  Code-Z2
  HOL-Library.Code-Target-Numeral

```

```
begin
```

### 23.1 Transformations between nested lists nested IArrays

```

definition iarray-of-iarray-to-list-of-list :: 'a iarray iarray => 'a list list
  where iarray-of-iarray-to-list-of-list A = map IArray.list-of (map ((!!) A) [0..<IArray.length A])

```

The following definitions are also in the file *Examples-on-Gauss-Jordan-Abstract*.

Definitions to transform a matrix to a list of list and vice versa

```

definition vec-to-list :: 'a ^n::{finite, enum} => 'a list
  where vec-to-list A = map ((\$) A) (enum-class.enum::'n list)

```

```

definition matrix-to-list-of-list :: 'a ^n::{finite, enum} ^m::{finite, enum} => 'a
list list
  where matrix-to-list-of-list A = map (vec-to-list) (map ((\$) A) (enum-class.enum::'m
list))

```

This definition should be equivalent to *vector-def* (in suitable types)

```

definition list-to-vec :: 'a list => 'a ^n::{enum, mod-type}
  where list-to-vec xs = vec-lambda (% i. xs ! (to-nat i))

```

```

lemma [code abstract]: vec-nth (list-to-vec xs) = (%i. xs ! (to-nat i))
⟨proof⟩

```

```

definition list-of-list-to-matrix :: 'a list list => 'a ^n::{enum, mod-type} ^m::{enum,
mod-type}

```

```
where list-of-list-to-matrix xs = vec-lambda (%i. list-to-vec (xs ! (to-nat i)))
```

```
lemma [code abstract]: vec-nth (list-of-list-to-matrix xs) = (%i. list-to-vec (xs ! (to-nat i)))
  ⟨proof⟩
```

## 23.2 Examples

The following three lemmas are presented in both this file and in the *Examples-Gauss-Jordan-Abstract* one. They allow a more convenient printing of rational and real numbers after evaluation. They have already been added to the repository version of Isabelle, so after Isabelle2014 they should be removed from here.

```
lemma [code-post]:
  int-of-integer (- 1) = - 1
  ⟨proof⟩
```

```
lemma [code-abbrev]:
  (of-rat (- 1) :: real) = - 1
  ⟨proof⟩
```

```
lemma [code-post]:
  (of-rat (- (1 / numeral k)) :: real) = - 1 / numeral k
  (of-rat (- (numeral k / numeral l)) :: real) = - numeral k / numeral l
  ⟨proof⟩
```

From here on, we do the computations in two ways. The first one consists of executing the abstract functions (which internally will execute the ones over iarrays). The second one runs directly the functions over iarrays.

### 23.2.1 Ranks, dimensions and Gauss Jordan algorithm

In the following examples, the theorem *matrix-to-iarray-rank* (which is the file *Gauss-Jordan-IArrays* and it is a code unfold theorem) assures that the computation will be carried out using the iarrays representation.

```
value vec.dim (col-space (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4))
value rank (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::real^5^4)
```

```
value vec.dim (null-space (list-of-list-to-matrix [[1,0,0,7,5],[1,0,4,8,-1],[1,0,0,9,8],[1,2,3,6,5]]::rat^5^4))
```

```
value rank-iarray (IArray[IArray[1::rat,0,0,7,5],IArray[1,0,4,8,-1],IArray[1,0,0,9,8],IArray[1,2,3,6,5]])
```

```
value rank-iarray (IArray[IArray[1::real,0,1],IArray[1,1,0],IArray[0,1,1]])
value rank-iarray (IArray[IArray[1::bit,0,1],IArray[1,1,0],IArray[0,1,1]])
```

Examples on computing the Gauss Jordan algorithm.

```

value iarray-of-iarray-to-list-of-list (matrix-to-iarray (Gauss-Jordan (list-of-list-to-matrix
[[Complex 1 1,Complex 1 (- 1), Complex 0 0],[Complex 2 (- 1),Complex 1 3,
Complex 7 3]]::complex^3^2)))
value iarray-of-iarray-to-list-of-list (Gauss-Jordan-iarrays(IArray[IArray[Complex
1 1,Complex 1 (- 1),Complex 0 0],IArray[Complex 2 (- 1),Complex 1 3,Complex
7 3]]))

```

### 23.2.2 Inverse of a matrix

Examples on inverting matrices

```

definition print-result-some-iarrays A = (if A = None then None else Some (iarray-of-iarray-to-list-of-list
(the A)))

```

```

value let A=(list-of-list-to-matrix [[1,1,2,4,5,9,8],[3,0,8,4,5,0,8],[3,2,0,4,5,9,8],[3,2,8,0,5,9,8],[3,2,8,4,0
in print-result-some-iarrays (matrix-to-iarray-option (inverse-matrix
A)))
value let A=(IArray[IArray[1::real,1,2,4,5,9,8],IArray[3,0,8,4,5,0,8],IArray[3,2,0,4,5,9,8],IArray[3,2,8,0,5,9,8],IArray[3,2,8,4,0
in print-result-some-iarrays (inverse-matrix-iarray A))

```

### 23.2.3 Determinant of a matrix

Examples on computing determinants of matrices

```

value det (list-of-list-to-matrix ([[1,8,9,1,47],[7,2,2,5,9],[3,2,7,7,4],[9,8,7,5,1],[1,2,6,4,5]])::rat^5^5)
value det (list-of-list-to-matrix [[1,2,7,8,9],[3,4,12,10,7],[-5,4,8,7,4],[0,1,2,4,8],[9,8,7,13,11]]::rat^5^5)

value det-iarrays (IArray[IArray[1::real,2,7,8,9],IArray[3,4,12,10,7],IArray[-5,4,8,7,4],IArray[0,1,2,4,8],
value det-iarrays (IArray[IArray[286,662,263,246,642,656,351,454,339,848],
IArray[307,489,667,908,103,47,120,133,85,834],
IArray[69,732,285,147,527,655,732,661,846,202],
IArray[463,855,78,338,786,954,593,550,913,378],
IArray[90,926,201,362,985,341,540,912,494,427],
IArray[384,511,12,627,131,620,987,996,445,216],
IArray[385,538,362,643,567,804,499,914,332,512],
IArray[879,159,312,187,827,503,823,893,139,546],
IArray[800,376,331,363,840,737,911,886,456,848],
IArray[900,737,280,370,121,195,958,862,957,754::real]])

```

### 23.2.4 Bases of the fundamental subspaces

Examples on computing basis for null space, row space, column space and left null space.

```

value let A = (list-of-list-to-matrix ([[1,3,-2,0,2,0],[2,6,-5,-2,4,-3],[0,0,5,10,0,15],[2,6,0,8,4,18]])::real
in vec-to-list` (basis-null-space A)
value let A = (list-of-list-to-matrix ([[3,4,0,7],[1,-5,2,-2],[-1,4,0,3],[1,-1,2,2]])::real^4^4)
in vec-to-list` (basis-null-space A)

```

**value** let  $A = (IArray[IArray[1::real, 3, -2, 0, 2, 0], IArray[2, 6, -5, -2, 4, -3], IArray[0, 0, 5, 10, 0, 15], IArray[2, 6, -5, -2, 4, -3], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]]))$

*in IArray.list-of<sup>c</sup> (basis-null-space-iarrays A)*

**value** let  $A = (IArray[IArray[3::real, 4, 0, 7], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]])$

*in IArray.list-of<sup>c</sup> (basis-null-space-iarrays A)*

**value** let  $A = (list-of-list-to-matrix ([[1, 3, -2, 0, 2, 0], [2, 6, -5, -2, 4, -3], [0, 0, 5, 10, 0, 15], [2, 6, 0, 8, 4, 18]]))$

*in vec-to-list<sup>c</sup> (basis-row-space A)*

**value** let  $A = (list-of-list-to-matrix ([[3, 4, 0, 7], [1, -5, 2, -2], [-1, 4, 0, 3], [1, -1, 2, 2]]))$

*in vec-to-list<sup>c</sup> (basis-row-space A)*

**value** let  $A = (IArray[IArray[1::real, 3, -2, 0, 2, 0], IArray[2, 6, -5, -2, 4, -3], IArray[0, 0, 5, 10, 0, 15], IArray[2, 6, -5, -2, 4, -3], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]]))$

*in IArray.list-of<sup>c</sup> (basis-row-space-iarrays A)*

**value** let  $A = (IArray[IArray[3::real, 4, 0, 7], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]])$

*in IArray.list-of<sup>c</sup> (basis-row-space-iarrays A)*

**value** let  $A = (list-of-list-to-matrix ([[1, 3, -2, 0, 2, 0], [2, 6, -5, -2, 4, -3], [0, 0, 5, 10, 0, 15], [2, 6, 0, 8, 4, 18]]))$

*in vec-to-list<sup>c</sup> (basis-col-space A)*

**value** let  $A = (list-of-list-to-matrix ([[3, 4, 0, 7], [1, -5, 2, -2], [-1, 4, 0, 3], [1, -1, 2, 2]]))$

*in vec-to-list<sup>c</sup> (basis-col-space A)*

**value** let  $A = (IArray[IArray[1::real, 3, -2, 0, 2, 0], IArray[2, 6, -5, -2, 4, -3], IArray[0, 0, 5, 10, 0, 15], IArray[2, 6, -5, -2, 4, -3], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]]))$

*in IArray.list-of<sup>c</sup> (basis-col-space-iarrays A)*

**value** let  $A = (IArray[IArray[3::real, 4, 0, 7], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]])$

*in IArray.list-of<sup>c</sup> (basis-col-space-iarrays A)*

**value** let  $A = (list-of-list-to-matrix ([[1, 3, -2, 0, 2, 0], [2, 6, -5, -2, 4, -3], [0, 0, 5, 10, 0, 15], [2, 6, 0, 8, 4, 18]]))$

*in vec-to-list<sup>c</sup> (basis-left-null-space A)*

**value** let  $A = (list-of-list-to-matrix ([[3, 4, 0, 7], [1, -5, 2, -2], [-1, 4, 0, 3], [1, -1, 2, 2]]))$

*in vec-to-list<sup>c</sup> (basis-left-null-space A)*

**value** let  $A = (IArray[IArray[1::real, 3, -2, 0, 2, 0], IArray[2, 6, -5, -2, 4, -3], IArray[0, 0, 5, 10, 0, 15], IArray[2, 6, -5, -2, 4, -3], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]]))$

*in IArray.list-of<sup>c</sup> (basis-left-null-space-iarrays A)*

**value** let  $A = (IArray[IArray[3::real, 4, 0, 7], IArray[1, -5, 2, -2], IArray[-1, 4, 0, 3], IArray[1, -1, 2, 2]])$

*in IArray.list-of<sup>c</sup> (basis-left-null-space-iarrays A)*

### 23.2.5 Consistency and inconsistency

Examples on checking the consistency/inconsistency of a system of equations. The theorems *matrix-to-iarray-independent-and-consistent* and *matrix-to-iarray-dependent-and-consistent* which are code theorems and they are in the file *System-Of-Equations-IArrays* assure the execution using the iarrays representation.

```
value independent-and-consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[0,0,1],[0,0,0],[0,0,0]])::real^3^5)
(list-to-vec([2,3,4,0,0])::real^5)
value consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[0,0,1],[0,0,0],[0,0,0]])::real^3^5)
(list-to-vec([2,3,4,0,0])::real^5)
value inconsistent (list-of-list-to-matrix ([[1,0,0],[0,1,0],[3,0,1],[0,7,0],[0,0,9]])::real^3^5)
(list-to-vec([2,0,4,0,0])::real^5)
value dependent-and-consistent (list-of-list-to-matrix ([[1,0,0],[0,1,0]])::real^3^2)
(list-to-vec([3,4])::real^2)
value independent-and-consistent (mat 1::real^3^3) (list-to-vec([3,4,5])::real^3)
```

### 23.2.6 Solving systems of linear equations

Examples on solving linear systems.

```
definition print-result-system-iarrays A = (if A = None then None else Some
(IArray.list-of (fst (the A)), IArray.list-of` (snd (the A))))
```

```
value let A = (list-of-list-to-matrix [[0,0,0],[0,0,0],[0,0,1]]::real^3^3); b=(list-to-vec
[4,5,0]::real^3);
      result = pair-vec-vecset (solve A b)
      in print-result-system-iarrays (result)
value let A = (list-of-list-to-matrix [[3,2,5,2,7],[6,4,7,4,5],[3,2,-1,2,-11],[6,4,1,4,-13]]::real^5^4);
b=(list-to-vec [0,0,0,0]::real^4);
      result = pair-vec-vecset (solve A b)
      in print-result-system-iarrays (result)
value let A = (list-of-list-to-matrix [[4,5,8],[9,8,7],[4,6,1]]::real^3^3); b=(list-to-vec
[4,5,8]::real^3);
      result = pair-vec-vecset (solve A b)
      in print-result-system-iarrays (result)

value let A = (IArray[IArray[0::real,0,0],IArray[0,0,0],IArray[0,0,1]]); b=(IArray[4,5,0]);
      result = (solve-iarrays A b)
      in print-result-system-iarrays (result)
value let A = (IArray[IArray[3::real,2,5,2,7],IArray[6,4,7,4,5],IArray[3,2,-1,2,-11],IArray[6,4,1,4,-13]]);
b=(IArray[0,0,0,0]);
      result = (solve-iarrays A b)
      in print-result-system-iarrays (result)
value let A = (IArray[IArray[4,5,8],IArray[9::real,8,7],IArray[4,6::real,1]]); b=(IArray[4,5,8]);
      result = (solve-iarrays A b)
      in print-result-system-iarrays (result)
```

**export-code**

```

rank-iarray
inverse-matrix-iarray
det-iarrays
consistent-iarrays
inconsistent-iarrays
independent-and-consistent-iarrays
dependent-and-consistent-iarrays
basis-left-null-space-iarrays
basis-null-space-iarrays
basis-col-space-iarrays
basis-row-space-iarrays
solve-iarrays
  in SML
end

```

## 24 Exporting code to SML and Haskell

```

theory Code-Generation-IArrays
imports
  Examples-Gauss-Jordan-IArrays
begin

```

### 24.1 Exporting code

The following two equations are necessary to execute code. If we don't remove them from code unfold, the exported code will not work (there exist problems with the number 1 and number 0. Those problems appear when the HMA library is imported).

```

lemma [code-unfold del]:  $1 \equiv \text{real-of-rat } 1 \langle \text{proof} \rangle$ 
lemma [code-unfold del]:  $0 \equiv \text{real-of-rat } 0 \langle \text{proof} \rangle$ 

definition matrix-z2 = IArray[IArray[0,1], IArray[1,1::bit], IArray[1,0::bit]]
definition matrix-rat = IArray[IArray[1,0,8], IArray[5.7,22,1], IArray[41,-58/7,78::rat]]
definition matrix-real = IArray[IArray[0,1], IArray[1,-2::real]]
definition vec-rat = IArray[21,5,7::rat]

definition print-result-Gauss A = iarray-of-iarray-to-list-of-list (Gauss-Jordan-iarrays A)
definition print-rank A = rank-iarray A
definition print-det A = det-iarrays A

definition print-result-z2 = print-result-Gauss (matrix-z2)
definition print-result-rat = print-result-Gauss (matrix-rat)
definition print-result-real = print-result-Gauss (matrix-real)

definition print-rank-z2 = print-rank (matrix-z2)
definition print-rank-rat = print-rank (matrix-rat)
definition print-rank-real = print-rank (matrix-real)

```

```

definition print-det-rat = print-det (matrix-rat)
definition print-det-real = print-det (matrix-real)

definition print-inverse A = inverse-matrix-iarray A
definition print-inverse-real A = print-inverse (matrix-real)
definition print-inverse-rat A = print-inverse (matrix-rat)

definition print-system A b = print-result-system-iarrays (solve-iarrays A b)
definition print-system-rat = print-result-system-iarrays (solve-iarrays matrix-rat
vec-rat)

```

## 24.2 The Mathematica bug

Varona et al [1] detected that the commercial software *Mathematica*®, in its versions 8.0, 9.0 and 9.0.1, was computing erroneously determinants of matrices of big integers, even for small dimensions (in their work they present an example of a matrix of dimension  $14 \times 14$ ). The situation is such that even the same determinant, computed twice, produces two different and wrong results.

Here we reproduce that example. The computation of the determinant is correctly carried out by the exported code from this formalization, in both SML and Haskell.

```

definition powersMatrix =
IArray[
IArray[10^123, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 10^152, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 10^185, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 10^220, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 10^397, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 10^449, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 10^503, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 10^563, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 10^979, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 0, 10^1059, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 10^1143, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 10^1229, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 10^1319, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
IArray[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 10^1412)::rat]]

```

  

```

definition basicMatrix =
IArray[
IArray[-32, 69, 89, -60, -83, -22, -14, -58, 85, 56, -65, -30, -86, -9],
IArray[6, 99, 11, 57, 47, -42, -48, -65, 25, 50, -70, -3, -90, 31],
IArray[78, 38, 12, 64, -67, -4, -52, -65, 19, 71, 38, -17, 51, -3],
IArray[-93, 30, 89, 22, 13, 48, -73, 93, 11, -97, -49, 61, -25, -4],
IArray[54, -22, 54, -53, -52, 64, 19, 1, 81, -72, -11, 50, 0, -81],

```

```

IArray[65,-58, 3, 57, 19, 77, 76,-57,-80, 22, 93,-85, 67, 58],
IArray[29,-58, 47, 87, 3,-6,-81, 5, 98, 86,-98, 51,-62,-66],
IArray[93,-77, 16,-64, 48, 84, 97, 75, 89, 63, 34,-98,-94, 19],
IArray[45,-99, 3,-57, 32, 60, 74, 4, 69, 98,-40,-69,-28,-26],
IArray[-13, 51,-99,-2, 48, 71,-81,-32, 78, 27,-28,-22, 22, 94],
IArray[11, 72,-74, 86, 79,-58,-89, 80, 70, 55,-49, 51,-42, 66],
IArray[-72, 53, 49,-46, 17,-22,-48,-40,-28,-85, 88,-30, 74, 32],
IArray[-92,-22,-90, 67,-25,-28,-91,-8, 32,-41, 10, 6, 85, 21],
IArray[47,-73,-30,-60, 99, 9,-86,-70, 84, 55, 19, 69, 11,-84::rat]]

definition smallMatrix=
IArray[
IArray[528, 853,-547,-323, 393,-916,-11,-976, 279,-665, 906,-277, 103,-485],
IArray[878, 910,-306,-260, 575,-765,-32, 94, 254, 276,-156, 625,-8,-566],
IArray[-357, 451,-475, 327,-84, 237, 647, 505,-137, 363,-808, 332, 222,-998],
IArray[-76, 26,-778, 505, 942,-561,-350, 698,-532,-507,-78,-758, 346,-545],
IArray[-358, 18,-229,-880,-955,-346, 550,-958, 867,-541,-962, 646, 932,
168],
IArray[192, 233, 620,955,-877, 281, 357,-226,-820, 513,-882, 536,-237, 877],
IArray[-234,-71,-831, 880,-135,-249,-427, 737, 664, 298,-552,-1,-712,-691],
IArray[80, 748, 684, 332, 730,-111,-643, 102,-242,-82,-28, 585, 207,-986],
IArray[967, 1,-494, 633, 891,-907,-586, 129, 688, 150,-501,-298, 704,-68],
IArray[406,-944,-533,-827, 615, 907,-443,-350, 700,-878, 706, 1,800, 120],
IArray[33,-328,-543, 583,-443,-635,904,-745,-398,-110, 751, 660, 474, 255],
IArray[-537,-311, 829, 28, 175, 182,-930, 258,-808,-399,-43,-68,-553, 421],
IArray[-373,-447,-252,-619,-418, 764, 994,-543,-37,-845, 30,-704, 147,-534],
IArray[638,-33, 932,-335,-75,-676,-934, 239, 210, 665, 414,-803, 564,-805::rat]]]

definition bigMatrix=(basicMatrix **i powersMatrix) + smallMatrix

end

```

## 25 Exporting code to SML

```

theory Code-Generation-IArrays-SML
imports
  HOL-Library.Code-Real-Approx-By-Float
  Code-Generation-IArrays
begin

```

Some serializations of gcd and abs in SML. Since gcd is not part of the standard SML library, we have serialized it to the corresponding operation in PolyML and MLton.

```

context
includes integer.lifting
begin

lift-definition gcd-integer :: integer => integer => integer

```

```
is gcd :: int => int => int ⟨proof⟩
```

```
lemma gcd-integer-code[code]:
gcd-integer l k = |if l = (0::integer) then k else gcd-integer l (|k| mod |l|)|
⟨proof⟩
end

code-printing
constant abs :: integer => - → (SML) IntInf.abs
| constant gcd-integer :: integer => - => - → (SML) (PolyML.IntInf.gcd ((-),(-)))
```

```
lemma gcd-code[code]:
gcd a b = int-of-integer (gcd-integer (of-int a) (of-int b))
⟨proof⟩
```

```
code-printing
constant abs :: real => real →
(SML) Real.abs
```

```
declare [[code drop: abs :: real ⇒ real]]
```

There are several ways to serialize div and mod. The following ones are four examples of it:

```
code-printing
constant divmod-integer :: integer => - => - → (SML) (IntInf.quotRem ((-),(-)))

export-code
print-rank-real
print-rank-rat
print-rank-z2
print-rank
print-result-real
print-result-rat
print-result-z2
print-result-Gauss
print-det-rat
print-det-real
print-det
print-inverse-real
print-inverse-rat
print-inverse
print-system-rat
print-system
in SML module-name Gauss-SML
```

```
end
```

## 26 Code Generation for rational numbers in Haskell

```
theory Code-Rational
imports
```

*HOL-Library.Code-Real-Approx-By-Float  
Code-Generation-IArrays*

*HOL-Library.Code-Target-Int  
begin*

### 26.1 Serializations

The following *code-printing code-module* module is the usual way to import libraries in Haskell. In this case, we rebind some functions from Data.Ratio. See <https://lists.cam.ac.uk/pipermail/cl-isabelle-users/2013-June/msg00007.html>

```
code-printing code-module Rational -> (Haskell)
  <module Rational(fract, numerator, denominator) where

    import qualified Data.Ratio
    import Data.Ratio(numerator, denominator)

    fract (a, b) = a Data.Ratio.% b

  context
  includes integer.lifting
  begin
    lift-definition Frct-integer :: integer × integer => rat
      is Frct :: int × int => rat ⟨proof⟩
  end

  consts Foo::rat
  code-datatype Foo

  context
  includes integer.lifting
  begin

  lemma [code]:
```

*Frct a = Frct-integer ((of-int (fst a)), (of-int (snd a)))*  
*⟨proof⟩*

**lemma** [code]:

*Rat.of-int a = Frct-integer (of-int a, 1)*  
*⟨proof⟩*

**definition** *numerator :: rat => int*  
**where** *numerator x = fst (quotient-of x)*

**definition** *denominator :: rat => int*  
**where** *denominator x = snd (quotient-of x)*

**lift-definition** *numerator-integer :: rat => integer*  
**is** *numerator ⟨proof⟩*

**lift-definition** *denominator-integer :: rat => integer*  
**is** *denominator ⟨proof⟩*

**lemma** [code]:

*inverse x = Frct-integer (denominator-integer x, numerator-integer x)*  
*⟨proof⟩*

**lemma** *quotient-of-num-den: quotient-of x = ((numerator x), (denominator x))*  
*⟨proof⟩*

**lemma** [code]: *quotient-of x = (int-of-integer (numerator-integer x), int-of-integer(denominator-integer x))*  
*⟨proof⟩*  
**end**

**code-printing**

- | **type-constructor** *rat* → (Haskell) *Prelude.Rational*
- | **class-instance** *rat* :: *HOL.equal* => (Haskell) –
- | **constant** *0* :: *rat* → (Haskell) (*Prelude.toRational (0::Integer)*)
- | **constant** *1* :: *rat* → (Haskell) (*Prelude.toRational (1::Integer)*)
- | **constant** *Frct-integer* → (Haskell) *Rational.fract (-)*
- | **constant** *numerator-integer* → (Haskell) *Rational.numerator (-)*
- | **constant** *denominator-integer* → (Haskell) *Rational.denominator (-)*
- | **constant** *HOL.equal* :: *rat* ⇒ *rat* ⇒ *bool* → (Haskell) *(-) == (-)*
- | **constant** *(<)* :: *rat* => *rat* => *bool* → (Haskell) *- < -*
- | **constant** *(≤)* :: *rat* => *rat* => *bool* → (Haskell) *- ≤ -*
- | **constant** *(+)* :: *rat* ⇒ *rat* ⇒ *rat* → (Haskell) *(-) + (-)*
- | **constant** *(-)* :: *rat* ⇒ *rat* ⇒ *rat* →

```

(Haskell) (-) - (-)
| constant (*) :: rat  $\Rightarrow$  rat  $\Rightarrow$  rat  $\rightarrow$ 
(Haskell) (-) * (-)
| constant (/) :: rat  $\Rightarrow$  rat  $\Rightarrow$  rat  $\rightarrow$ 
(Haskell) (-) '/ (-)
| constant uminus :: rat  $=>$  rat  $\rightarrow$ 
(Haskell) Prelude.negate

```

**end**

## 27 Exporting code to Haskell

**theory** *Code-Generation-IArrays-Haskell*  
**imports**

*Code-Rational*

**begin**

**export-code**

*print-rank-real*  
*print-rank-rat*  
*print-rank-z2*  
*print-rank*  
*print-result-real*  
*print-result-rat*  
*print-result-z2*  
*print-result-Gauss*  
*print-det-rat*  
*print-det-real*  
*print-det*  
*print-inverse-real*  
*print-inverse-rat*  
*print-inverse*  
*print-system-rat*  
*print-system*

**in Haskell**

**module-name** *Gauss-Haskell*

**end**

## References

- [1] M. P. Antonio J. Durán and J. L. Varona. Misfortunes of a mathematicians' trio using computer algebra systems: Can we trust? *CoRR*, abs/1312.3270, 2013. <http://arxiv.org/abs/1312.3270>.