

Abstract

Algorithms for solving the consensus problem are fundamental to distributed computing. Despite their brevity, their ability to operate in concurrent, asynchronous and failure-prone environments comes at the cost of complex and subtle behaviors. Accordingly, understanding how they work and proving their correctness is a non-trivial endeavor where abstraction is immensely helpful. Moreover, research on consensus has yielded a large number of algorithms, many of which appear to share common algorithmic ideas. A natural question is whether and how these similarities can be distilled and described in a precise, unified way. In this work, we combine stepwise refinement and lockstep models to provide an abstract and unified view of a sizeable family of consensus algorithms. Our models provide insights into the design choices underlying the different algorithms, and classify them based on those choices.

Consensus Refined

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1 Introduction

Distributed consensus is a fundamental problem in distributed computing: a fixed set of processes must *agree* on a single value from a set of proposed ones. Algorithms that solve this problem provide building blocks for many higher-level tasks, such as distributed leases, group membership, atomic broadcast (also known as total-order broadcast or multi-consensus), and so forth. These in turn provide building blocks for yet higher-level tasks like system replication. In this work, however, our focus is on consensus algorithms “proper”, rather than their applications. Namely, we consider consensus algorithms for the asynchronous message-passing setting with benign link and process failures.

Although the setting we consider explicitly excludes malicious behavior, the interplay of concurrency, asynchrony, and failures can still drive the execution of any consensus algorithm in many different ways. This makes the understanding of both the algorithms and their correctness non-trivial. Furthermore, many consensus algorithms have been proposed in the literature. Many of these algorithms appear to share similar underlying algorithmic ideas, although their presentation, structure and details differ. A natural question is whether these similarities can be distilled and captured in a uniform and generic way. In the same vein, one may ask whether the algorithms can be classified by some natural criteria.

This formalization, which accompanies our conference paper [5], is our contribution towards addressing these issues. Our primary tool in tackling them is *abstraction*. We describe consensus algorithms using *stepwise refinement*. In this method, an algorithm is derived through a sequence of models. The initial models in the sequence can describe the algorithms in arbitrarily abstract terms. In our abstractions, we remove message passing and describe the system using non-local steps that depend on the states of multiple processes. These abstractions allow us to focus on the main algorithmic ideas, without getting bogged down in details, thereby providing simplicity. We then gradually introduce details in successive, more concrete models that refine the abstract ones. In order to be implementable in a distributed setting, the final models must use strictly local steps, and communicate only by passing messages. The link between abstract and concrete models is precisely described and proved using *refinement relations*. Furthermore, the same abstract model can be implemented by different algorithms. This re-

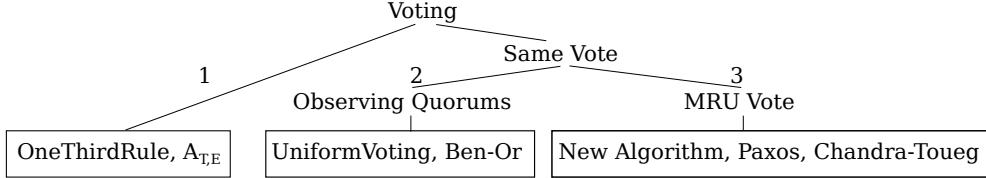


Figure 1: The consensus family tree. Boxes contain models of concrete algorithms.

sults in a *refinement tree* of models, where branching corresponds to different implementations.

Figure 1 shows the resulting refinement tree for our development. It captures the relationships between the different consensus algorithms found at its leaves: OneThirdRule, $A_{T,E}$, Ben-Or’s algorithm, UniformVoting, Paxos, Chandra-Toueg algorithm and a new algorithm that we present. The refinement tree provides a natural classification of these algorithms. The new algorithm answers a question raised in [2], asking whether there exists a leaderless consensus algorithm that requires no waiting to provide safety, while tolerating up to $\frac{N}{2}$ process failures.

Our abstract (non-leaf) models are represented using unlabeled transition systems. For the models of the concrete algorithms, we adopt the Heard-Of model [2]) and reuse its Isabelle formalization by Debrat and Merz [3]. The Heard-Of model belongs to a class of models we refer to as *lockstep*, and which are applicable to algorithms which operate in communication-closed rounds. For this class of algorithms, the asynchronous setting is replaced by what is an essentially a synchronous model weakened by message loss (dual to strengthening the asynchronous model by failure detectors). This provides the illusion that all the processes operate in lockstep. Yet our results translate to the asynchronous setting of the real world, thanks to the preservation result established in [1] (and formalized in [3]).

2 Preliminaries

```
theory Infra imports Main
begin
```

2.1 Prover configuration

```
declare if-split-asm [split]
```

2.2 Forward reasoning ("attributes")

The following lemmas are used to produce intro/elim rules from set definitions and relation definitions.

```
lemmas set-def-to-intro = eqset-imp-iff [THEN iffD2]
lemmas set-def-to-dest = eqset-imp-iff [THEN iffD1]
lemmas set-def-to-elim = set-def-to-dest [elim-format]
```

```
lemmas setc-def-to-intro =
  set-def-to-intro [where B={x. P x}, simplified] for P
```

```
lemmas setc-def-to-dest =
  set-def-to-dest [where B={x. P x}, simplified] for P
```

```
lemmas setc-def-to-elim = setc-def-to-dest [elim-format]
```

```
lemmas rel-def-to-intro = setc-def-to-intro [where x=(s, t)] for s t
lemmas rel-def-to-dest = setc-def-to-dest [where x=(s, t)] for s t
lemmas rel-def-to-elim = rel-def-to-dest [elim-format]
```

2.3 General results

2.3.1 Maps

We usually remove *domIff* from the simpset and clasets due to annoying behavior. Sometimes the lemmas below are more well-behaved than *domIff*. Usually to be used as "dest: dom_lemmas". However, adding them as permanent dest rules slows down proofs too much, so we refrain from doing this.

```
lemma map-definedness:
  f x = Some y ==> x ∈ dom f
  ⟨proof⟩
```

```
lemma map-definedness-contra:
  [| f x = Some y; z ∉ dom f |] ==> x ≠ z
```

$\langle proof \rangle$

lemmas *dom-lemmas* = *map-definedness map-definedness-contra*

2.3.2 Set

declare *image-comp*[*symmetric, simp*]

lemma *vimage-image-subset*: $A \subseteq f^{-1}(f[A])$
 $\langle proof \rangle$

2.3.3 Relations

lemma *Image-compose* [*simp*]:
 $(R1 \circ R2) `` A = R2 `` (R1 `` A)$
 $\langle proof \rangle$

2.3.4 Lists

lemma *map-id*: *map id = id*
 $\langle proof \rangle$
lemma *map-comp*: *map (g o f) = map g o map f*
 $\langle proof \rangle$

declare *map-comp-map* [*simp del*]

lemma *take-prefix*: $\llbracket \text{take } n \text{ } l = xs \rrbracket \implies \exists xs'. l = xs @ xs'$
 $\langle proof \rangle$

2.3.5 Finite sets

Cardinality.

declare *arg-cong* [**where** *f=card, intro*]

lemma *finite-positive-cardI* [*intro!*]:
 $\llbracket A \neq \{\}; \text{finite } A \rrbracket \implies 0 < \text{card } A$
 $\langle proof \rangle$

lemma *finite-positive-cardD* [*dest!*]:
 $\llbracket 0 < \text{card } A; \text{finite } A \rrbracket \implies A \neq \{ \}$

$\langle proof \rangle$

lemma *finite-zero-cardI* [*intro!*]:
 $\llbracket A = \{\}; finite\ A \rrbracket \implies card\ A = 0$
 $\langle proof \rangle$

lemma *finite-zero-cardD* [*dest!*]:
 $\llbracket card\ A = 0; finite\ A \rrbracket \implies A = \{ \}$
 $\langle proof \rangle$

end

2.4 Consensus: types

typeddecl *process*

Once we start taking maximums (e.g. in *Last_Voting*), we will need the process set to be finite

axiomatization **where** *process-finite*:

OFCLASS(*process*, *finite-class*)

instance *process* :: *finite* $\langle proof \rangle$

abbreviation

$N \equiv card\ (UNIV::process\ set)$ — number of processes

typeddecl *val* — Type of values to choose from

type-synonym *round* = *nat*

end

2.5 Quorums

locale *quorum* =
 fixes *Quorum* :: '*a* *set set*
 assumes
 $q_{\text{intersect}}: \llbracket Q \in Quorum; Q' \in Quorum \rrbracket \implies Q \cap Q' \neq \{ \}$

— Non-emptiness needed for some invariants of Coordinated Voting
and *Quorum-not-empty*: $\exists Q. Q \in \text{Quorum}$

lemma (**in** *quorum*) *quorum-non-empty*: $Q \in \text{Quorum} \implies Q \neq \{\}$
<proof>

lemma (**in** *quorum*) *empty-not-quorum*: $\{\} \in \text{Quorum} \implies \text{False}$
<proof>

locale *quorum-process* = *quorum* *Quorum*
for *Quorum* :: *process set set*

locale *mono-quorum* = *quorum-process* +
assumes *mono-quorum*: $\llbracket Q \in \text{Quorum}; Q \subseteq Q' \rrbracket \implies Q' \in \text{Quorum}$

lemma (**in** *mono-quorum*) *UNIV-quorum*:
UNIV $\in \text{Quorum}$
<proof>

definition *majs* :: (*process set*) *set* **where**
 $majs \equiv \{S. \text{card } S > N \text{ div } 2\}$

lemma *majsI*:
 $N \text{ div } 2 < \text{card } S \implies S \in majs$
<proof>

lemma *card-Compl*:
fixes *S* :: (*'a :: finite*) *set*
shows *card* $(-S) = \text{card} (\text{UNIV} :: \text{'a set}) - \text{card } S$
<proof>

lemma *majorities-intersect*:
card $(Q :: \text{process set}) + \text{card } Q' > N \implies Q \cap Q' \neq \{\}$
<proof>

interpretation *majorities*: *mono-quorum* *majs*
<proof>

end

2.6 Miscellaneous lemmas

$\langle ML \rangle$

definition *flip where*

flip-def: $\text{flip } f \equiv \lambda x. y. f y x$

lemma *option-expand':*

$\llbracket (\text{option} = \text{None}) = (\text{option}' = \text{None}) \rrbracket; \bigwedge x y. \llbracket \text{option} = \text{Some } x; \text{option}' = \text{Some } y \rrbracket \implies x = y \rrbracket \implies$
 $\text{option} = \text{option}'$
 $\langle \text{proof} \rangle$

2.7 Argmax

definition *Max-by :: ('a \Rightarrow 'b :: linorder) \Rightarrow 'a set \Rightarrow 'a where*

Max-by f S = (SOME x. x \in S \wedge f x = Max (f ` S))

lemma *Max-by-dest:*

assumes *finite A and A $\neq \{\}$*

shows *Max-by f A \in A \wedge f (Max-by f A) = Max (f ` A) (is ?P (Max-by f A))*

$\langle \text{proof} \rangle$

lemma *Max-by-in:*

assumes *finite A and A $\neq \{\}$*

shows *Max-by f A \in A* $\langle \text{proof} \rangle$

lemma *Max-by-ge:*

assumes *finite A x \in A*

shows *f x \leq f (Max-by f A)*

$\langle \text{proof} \rangle$

lemma *finite-UN-D:*

finite ($\bigcup S$) $\implies \forall A \in S. \text{finite } A$

$\langle \text{proof} \rangle$

lemma *Max-by-eqI:*

assumes

fin: finite A

and $\bigwedge y. y \in A \implies \text{cmp-f } y \leq \text{cmp-f } x$

and *in-X: x \in A*

and *inj*: *inj-on cmp-f A*
shows *Max-by cmp-f A = x*
(proof)

lemma *Max-by-Union-distrib*:
 $\llbracket \text{finite } A; A = \bigcup S; S \neq \{\}; \{\} \notin S; \text{inj-on cmp-f } A \rrbracket \implies$
 $\text{Max-by cmp-f } A = \text{Max-by cmp-f} (\text{Max-by cmp-f} ' S)$
(proof)

lemma *Max-by-UNION-distrib*:
 $\llbracket \text{finite } A; A = (\bigcup_{x \in S} f x); S \neq \{\}; \{\} \notin f ' S; \text{inj-on cmp-f } A \rrbracket \implies$
 $\text{Max-by cmp-f } A = \text{Max-by cmp-f} (\text{Max-by cmp-f} ' (f ' S))$
(proof)

lemma *Max-by-eta*:
 $\text{Max-by } f = (\lambda S. (\text{SOME } x. x \in S \wedge f x = \text{Max} (f ' S)))$
(proof)

lemma *Max-is-Max-by-id*:
 $\llbracket \text{finite } S; S \neq \{\} \rrbracket \implies \text{Max } S = \text{Max-by id } S$
(proof)

definition *option-Max-by* :: $('a \Rightarrow 'b : linorder) \Rightarrow 'a \text{ set} \Rightarrow 'a \text{ option where}$
 $\text{option-Max-by cmp-f } A \equiv \text{if } A = \{\} \text{ then None else Some } (\text{Max-by cmp-f } A)$

2.8 Function and map graphs

definition *fun-graph* **where**
 $\text{fun-graph } f = \{(x, f x) | x. \text{True}\}$

definition *map-graph* :: $('a, 'b) \text{ map} \Rightarrow ('a \times 'b) \text{ set where}$
 $\text{map-graph } f = \{(x, y) | x y. (x, \text{Some } y) \in \text{fun-graph } f\}$

lemma *map-graph-mem[simp]*:
 $((x, y) \in \text{map-graph } f) = (f x = \text{Some } y)$
(proof)

lemma *finite-fun-graph*:
 $\text{finite } A \implies \text{finite } (\text{fun-graph } f \cap (A \times \text{UNIV}))$
(proof)

lemma *finite-map-graph*:
 $\text{finite } A \implies \text{finite}(\text{map-graph } f \cap (A \times \text{UNIV}))$
 $\langle \text{proof} \rangle$

lemma *finite-dom-finite-map-graph*:
 $\text{finite}(\text{dom } f) \implies \text{finite}(\text{map-graph } f)$
 $\langle \text{proof} \rangle$

lemma *ran-map-addD*:
 $x \in \text{ran}(m ++ f) \implies x \in \text{ran } m \vee x \in \text{ran } f$
 $\langle \text{proof} \rangle$

2.9 Constant maps

definition *const-map* :: $'v \Rightarrow 'k \text{ set} \Rightarrow ('k, 'v)\text{map}$ **where**
 $\text{const-map } v S \equiv (\lambda-. \text{ Some } v) |` S$

lemma *const-map-empty[simp]*:
 $\text{const-map } v \{\} = \text{Map.empty}$
 $\langle \text{proof} \rangle$

lemma *const-map-ran[simp]*: $x \in \text{ran}(\text{const-map } v S) = (S \neq \{} \wedge x = v)$
 $\langle \text{proof} \rangle$

lemma *const-map-is-None*:
 $(\text{const-map } y A \ x = \text{None}) = (x \notin A)$
 $\langle \text{proof} \rangle$

lemma *const-map-is-Some*:
 $(\text{const-map } y A \ x = \text{Some } z) = (z = y \wedge x \in A)$
 $\langle \text{proof} \rangle$

lemma *const-map-in-set*:
 $x \in A \implies \text{const-map } v A \ x = \text{Some } v$
 $\langle \text{proof} \rangle$

lemma *const-map-notin-set*:
 $x \notin A \implies \text{const-map } v A \ x = \text{None}$

$\langle proof \rangle$

lemma *dom-const-map*:

dom (*const-map v S*) = *S*

$\langle proof \rangle$

2.10 Votes with maximum timestamps.

definition *vote-set* :: ('round \Rightarrow ('process, 'val)map) \Rightarrow 'process set \Rightarrow ('round \times 'val)set **where**

vote-set vs Q \equiv $\{(r, v) | a \in r \text{ v. } ((r, a), v) \in \text{map-graph}(\text{case-prod } vs) \wedge a \in Q\}$

lemma *inj-on-fst-vote-set*:

inj-on fst (vote-set v-hist {p})

$\langle proof \rangle$

lemma *finite-vote-set*:

assumes $\forall r' \geq (r :: \text{nat}). \text{v-hist } r' = \text{Map.empty}$

finite S

shows *finite (vote-set v-hist S)*

$\langle proof \rangle$

definition *mru-of-set*

:: ('round :: linorder \Rightarrow ('process, 'val)map) \Rightarrow ('process set, 'round \times 'val)map

where

mru-of-set vs $\equiv \lambda Q. \text{option-Max-by fst (vote-set vs Q)}$

definition *process-mru*

:: ('round :: linorder \Rightarrow ('process, 'val)map) \Rightarrow ('process, 'round \times 'val)map

where

process-mru vs $\equiv \lambda a. \text{mru-of-set vs } \{a\}$

lemma *process-mru-is-None*:

(process-mru v-f a = None) = (vote-set v-f {a} = {})

$\langle proof \rangle$

lemma *process-mru-is-Some*:

(process-mru v-f a = Some rv) = (vote-set v-f {a} \neq {} \wedge rv = Max-by fst (vote-set v-f {a}))

$\langle proof \rangle$

```

lemma vote-set-upd:
  vote-set (v-hist(r := v-f)) {p} =
    (if p ∈ dom v-f
      then insert (r, the (v-f p))
      else id
    )
    (if v-hist r p = None
      then vote-set v-hist {p}
      else vote-set v-hist {p} - {(r, the (v-hist r p))})
  )

```

$\langle proof \rangle$

```

lemma finite-vote-set-upd:
  finite (vote-set v-hist {a})  $\implies$ 
    finite (vote-set (v-hist(r := v-f)) {a})

```

$\langle proof \rangle$

```

lemma vote-setD:
  rv ∈ vote-set v-f {a}  $\implies$  v-f (fst rv) a = Some (snd rv)

```

$\langle proof \rangle$

```

lemma process-mru-new-votes:
  assumes
     $\forall r' \geq (r :: nat). v\text{-hist } r' = Map.empty$ 
  shows
    process-mru (v-hist(r := v-f)) =
      (process-mru v-hist ++ ( $\lambda p. map\text{-option } (Pair r) (v-f p)$ ))

```

$\langle proof \rangle$

end

2.11 Step definitions for 2-step algorithms

definition two-phase **where** two-phase (r::nat) \equiv r div 2

definition two-step **where** two-step (r::nat) \equiv r mod 2

```

lemma two-phase-zero [simp]: two-phase 0 = 0
⟨proof⟩

lemma two-step-zero [simp]: two-step 0 = 0
⟨proof⟩

lemma two-phase-step: (two-phase r * 2) + two-step r = r
⟨proof⟩

lemma two-step-phase-Suc:
  two-step r = 0  $\implies$  two-phase (Suc r) = two-phase r
  two-step r = 0  $\implies$  two-step (Suc r) = 1
  two-step r = 0  $\implies$  two-phase (Suc (Suc r)) = Suc (two-phase r)
  two-step r = (Suc 0)  $\implies$  two-phase (Suc r) = Suc (two-phase r)
  two-step r = (Suc 0)  $\implies$  two-step (Suc r) = 0
⟨proof⟩

end

```

2.12 Step definitions for 3-step algorithms

```

abbreviation (input) nr-steps  $\equiv$  3

definition three-phase where three-phase (r::nat)  $\equiv$  r div nr-steps

definition three-step where three-step (r::nat)  $\equiv$  r mod nr-steps

lemma three-phase-zero [simp]: three-phase 0 = 0
⟨proof⟩

lemma three-step-zero [simp]: three-step 0 = 0
⟨proof⟩

lemma three-phase-step: (three-phase r * nr-steps) + three-step r = r
⟨proof⟩

lemma three-step-Suc:
  three-step r = 0  $\implies$  three-step (Suc (Suc r)) = 2
  three-step r = 0  $\implies$  three-step (Suc r) = 1
  three-step r = (Suc 0)  $\implies$  three-step (Suc r) = 2

```

```

three-step r = (Suc 0) ==> three-step (Suc (Suc r)) = 0
three-step r = (Suc (Suc 0)) ==> three-step ((Suc r)) = 0
⟨proof⟩

```

lemma *three-step-phase-Suc*:

```

three-step r = 0 ==> three-phase (Suc r) = three-phase r
three-step r = 0 ==> three-phase (Suc (Suc r)) = three-phase r
three-step r = 0 ==> three-phase (Suc (Suc (Suc r))) = Suc (three-phase r)
three-step r = (Suc 0) ==> three-phase (Suc r) = three-phase r
three-step r = (Suc 0) ==> three-phase (Suc (Suc r)) = Suc (three-phase r)
three-step r = (Suc (Suc 0)) ==> three-phase (Suc r) = Suc (three-phase r)
⟨proof⟩

```

lemma *three-step2-phase-Suc*:

```

three-step r = 2 ==> (3 * (Suc (three-phase r)) - 1) = r
⟨proof⟩

```

lemma *three-stepE*:

```

[ three-step r = 0 ==> P; three-step r = 1 ==> P; three-step r = 2 ==> P ] ==>
P
⟨proof⟩

```

end

3 Models, Invariants and Refinements

```

theory Refinement imports Infra
begin

```

3.1 Specifications, reachability, and behaviours.

Transition systems are multi-pointed graphs.

```

record 's TS =
  init :: 's set
  trans :: ('s × 's) set

```

The inductive set of reachable states.

inductive-set

```

  reach :: ('s, 'a) TS-scheme ⇒ 's set

```

for $T :: ('s, 'a)$ TS-scheme

where

| $r\text{-init}$ [intro]: $s \in init T \implies s \in reach T$
| $r\text{-trans}$ [intro]: $\llbracket (s, t) \in trans T; s \in reach T \rrbracket \implies t \in reach T$

3.1.1 Finite behaviours

Note that behaviours grow at the head of the list, i.e., the initial state is at the end.

inductive-set

$beh :: ('s, 'a)$ TS-scheme $\Rightarrow ('s list)$ set

for $T :: ('s, 'a)$ TS-scheme

where

| $b\text{-empty}$ [iff]: $\llbracket \rrbracket \in beh T$
| $b\text{-init}$ [intro]: $s \in init T \implies [s] \in beh T$
| $b\text{-trans}$ [intro]: $\llbracket s \# b \in beh T; (s, t) \in trans T \rrbracket \implies t \# s \# b \in beh T$

inductive-cases $beh\text{-non-empty}$: $s \# b \in beh T$

Behaviours are prefix closed.

lemma $beh\text{-immediate-prefix-closed}$:

$s \# b \in beh T \implies b \in beh T$

$\langle proof \rangle$

lemma $beh\text{-prefix-closed}$:

$c @ b \in beh T \implies b \in beh T$

$\langle proof \rangle$

States in behaviours are exactly reachable.

lemma $beh\text{-in-reach}$ [rule-format]:

$b \in beh T \implies (\forall s \in set b. s \in reach T)$

$\langle proof \rangle$

lemma $reach\text{-in-beh}$:

$s \in reach T \implies \exists b \in beh T. s \in set b$

$\langle proof \rangle$

lemma $reach\text{-equiv-beh-states}$: $reach T = (\bigcup_{b \in beh T} set b)$

$\langle proof \rangle$

Consecutive states in a behavior are connected by the transition relation

lemma *beh-consecutive-in-trans*:

```
assumes b ∈ beh TS
and Suc i < length b
and s = b ! Suc i
and t = b ! i
shows (s, t) ∈ trans TS
⟨proof⟩
```

3.1.2 Specifications, observability, and implementation

Specifications add an observer function to transition systems.

```
record ('s, 'o) spec = 's TS +
  obs :: 's ⇒ 'o
```

lemma *beh-obs-upd [simp]*: beh (S(| obs := x |)) = beh S
 $\langle \text{proof} \rangle$

lemma *reach-obs-upd [simp]*: reach (S(| obs := x |)) = reach S
 $\langle \text{proof} \rangle$

Observable behaviour and reachability.

definition

```
obeh :: ('s, 'o) spec ⇒ ('o list) set where
  obeh S ≡ (map (obs S))‘(beh S)
```

definition

```
oreach :: ('s, 'o) spec ⇒ 'o set where
  oreach S ≡ (obs S)‘(reach S)
```

lemma *oreach-equiv-obeh-states*: oreach S = ($\bigcup_{b \in \text{obeh } S}$. set b)
 $\langle \text{proof} \rangle$

lemma *obeh-pi-translation*:

```
(map pi)‘(obeh S) = obeh (S(| obs := pi o (obs S) |))  

⟨proof⟩
```

lemma *oreach-pi-translation*:

$\text{pi}^*(\text{oreach } S) = \text{oreach } (S(| \text{obs} := \text{pi } o (\text{obs } S) |))$
 $\langle \text{proof} \rangle$

A predicate P on the states of a specification is *observable* if it cannot distinguish between states yielding the same observation. Equivalently, P is observable if it is the inverse image under the observation function of a predicate on observations.

definition

$\text{observable} :: [s \Rightarrow 'o, 's \text{ set}] \Rightarrow \text{bool}$

where

$\text{observable } ob P \equiv \forall s s'. ob s = ob s' \longrightarrow s' \in P \longrightarrow s \in P$

definition

$\text{observable2} :: [s \Rightarrow 'o, 's \text{ set}] \Rightarrow \text{bool}$

where

$\text{observable2 } ob P \equiv \exists Q. P = ob-'Q$

definition

$\text{observable3} :: [s \Rightarrow 'o, 's \text{ set}] \Rightarrow \text{bool}$

where

$\text{observable3 } ob P \equiv ob-'ob'P \subseteq P \quad \text{--- other direction holds trivially}$

lemma $\text{observableE} [\text{elim}]:$

$\llbracket \text{observable } ob P; ob s = ob s'; s' \in P \rrbracket \implies s \in P$

$\langle \text{proof} \rangle$

lemma $\text{observable2-equiv-observable}: \text{observable2 } ob P = \text{observable } ob P$
 $\langle \text{proof} \rangle$

lemma $\text{observable3-equiv-observable2}: \text{observable3 } ob P = \text{observable2 } ob P$
 $\langle \text{proof} \rangle$

lemma $\text{observable-id} [\text{simp}]: \text{observable id } P$
 $\langle \text{proof} \rangle$

The set extension of a function ob is the left adjoint of a Galois connection on the powerset lattices over domain and range of ob where the right adjoint is the inverse image function.

lemma $\text{image-vimage-adjoints}: (ob'P \subseteq Q) = (P \subseteq ob-'Q)$
 $\langle \text{proof} \rangle$

declare *image-vimage-subset* [*simp, intro*]
declare *vimage-image-subset* [*simp, intro*]

Similar but "reversed" (wrt to adjointness) relationships only hold under additional conditions.

lemma *image-r-vimage-l*: $\llbracket Q \subseteq ob^{\prime}P; observable ob P \rrbracket \implies ob^{-\prime}Q \subseteq P$
(proof)

lemma *vimage-l-image-r*: $\llbracket ob^{-\prime}Q \subseteq P; Q \subseteq range ob \rrbracket \implies Q \subseteq ob^{\prime}P$
(proof)

Internal and external invariants

lemma *external-from-internal-invariant*:
 $\llbracket reach S \subseteq P; (obs S)^{\prime}P \subseteq Q \rrbracket$
 $\implies oreach S \subseteq Q$
(proof)

lemma *external-from-internal-invariant-vimage*:
 $\llbracket reach S \subseteq P; P \subseteq (obs S)^{-\prime}Q \rrbracket$
 $\implies oreach S \subseteq Q$
(proof)

lemma *external-to-internal-invariant-vimage*:
 $\llbracket oreach S \subseteq Q; (obs S)^{-\prime}Q \subseteq P \rrbracket$
 $\implies reach S \subseteq P$
(proof)

lemma *external-to-internal-invariant*:
 $\llbracket oreach S \subseteq Q; Q \subseteq (obs S)^{\prime}P; observable (obs S) P \rrbracket$
 $\implies reach S \subseteq P$
(proof)

lemma *external-equiv-internal-invariant-vimage*:
 $\llbracket P = (obs S)^{-\prime}Q \rrbracket$
 $\implies (oreach S \subseteq Q) = (reach S \subseteq P)$
(proof)

lemma *external-equiv-internal-invariant*:

$$\begin{aligned} & \llbracket (\text{obs } S) 'P = Q; \text{observable } (\text{obs } S) P \rrbracket \\ & \implies (\text{oreach } S \subseteq Q) = (\text{reach } S \subseteq P) \end{aligned}$$

(proof)

Our notion of implementation is inclusion of observable behaviours.

definition

$$\begin{aligned} \text{implements} :: [{}'p \Rightarrow {}'o, ({}'s, {}'o) \text{ spec}, ({}'t, {}'p) \text{ spec}] \Rightarrow \text{bool where} \\ \text{implements } pi \text{ Sa Sc} \equiv (\text{map } pi) '(\text{obeh } Sc) \subseteq \text{obeh } Sa \end{aligned}$$

Reflexivity and transitivity

lemma *implements-refl*: *implements id S S*

(proof)

lemma *implements-trans*:

$$\begin{aligned} & \llbracket \text{implements } pi1 \text{ S1 S2}; \text{implements } pi2 \text{ S2 S3} \rrbracket \\ & \implies \text{implements } (pi1 \circ pi2) \text{ S1 S3} \end{aligned}$$

(proof)

Preservation of external invariants

lemma *implements-oreach*:

$$\begin{aligned} \text{implements } pi \text{ Sa Sc} \implies pi '(\text{oreach } Sc) \subseteq \text{oreach } Sa \end{aligned}$$

(proof)

lemma *external-invariant-preservation*:

$$\begin{aligned} & \llbracket \text{oreach } Sa \subseteq Q; \text{implements } pi \text{ Sa Sc} \rrbracket \\ & \implies pi '(\text{oreach } Sc) \subseteq Q \end{aligned}$$

(proof)

lemma *external-invariant-translation*:

$$\begin{aligned} & \llbracket \text{oreach } Sa \subseteq Q; pi - 'Q \subseteq P; \text{implements } pi \text{ Sa Sc} \rrbracket \\ & \implies \text{oreach } Sc \subseteq P \end{aligned}$$

(proof)

Preservation of internal invariants

lemma *internal-invariant-translation*:

$$\begin{aligned} & \llbracket \text{reach } Sa \subseteq Pa; Pa \subseteq \text{obs } Sa - 'Qa; pi - 'Qa \subseteq Q; \text{obs } S - 'Q \subseteq P; \\ & \quad \text{implements } pi \text{ Sa S} \rrbracket \\ & \implies \text{reach } S \subseteq P \end{aligned}$$

(proof)

3.2 Invariants

First we define Hoare triples over transition relations and then we derive proof rules to establish invariants.

3.2.1 Hoare triples

definition

$$\text{PO-hoare} :: [s \text{ set}, (s \times s) \text{ set}, s \text{ set}] \Rightarrow \text{bool}$$

$$((\exists \{ \cdot \} - \{ > \cdot \}) [0, 0, 0] 90)$$

where

$$\{ \text{pre} \} R \{ > \text{post} \} \equiv R^{\text{“}} \text{pre} \subseteq \text{post}$$

lemmas *PO-hoare-defs* = *PO-hoare-def* *Image-def*

lemma $\{P\} R \{ > Q \} = (\forall s t. s \in P \rightarrow (s, t) \in R \rightarrow t \in Q)$
(proof)

lemma *hoareD*:

$$[\{I\} R \{ > J \}; s \in I; (s, s') \in R] \implies s' \in J$$

Some essential facts about Hoare triples.

lemma *hoare-conseq-left* [*intro*]:

$$[\{P'\} R \{ > Q \}; P \subseteq P'] \implies \{P\} R \{ > Q \}$$

lemma *hoare-conseq-right*:

$$[\{P\} R \{ > Q' \}; Q' \subseteq Q] \implies \{P\} R \{ > Q \}$$

(proof)

lemma *hoare-false-left* [*simp*]:

$$\{\{\}\} R \{ > Q \}$$

(proof)

lemma *hoare-true-right* [*simp*]:

$$\{P\} R \{ > \text{UNIV} \}$$

(proof)

lemma *hoare-conj-right* [*intro!*]:
 $\llbracket \{P\} R \{> Q_1\}; \{P\} R \{> Q_2\} \rrbracket$
 $\implies \{P\} R \{> Q_1 \cap Q_2\}$
⟨proof⟩

Special transition relations.

lemma *hoare-stop* [*simp, intro!*]:
 $\{P\} \{\} \{> Q\}$
⟨proof⟩

lemma *hoare-skip* [*simp, intro!*]:
 $P \subseteq Q \implies \{P\} \text{Id} \{> Q\}$
⟨proof⟩

lemma *hoare-trans-Un* [*iff*]:
 $\{P\} R1 \cup R2 \{> Q\} = (\{P\} R1 \{> Q\} \wedge \{P\} R2 \{> Q\})$
⟨proof⟩

lemma *hoare-trans-UN* [*iff*]:
 $\{P\} \bigcup x. R x \{> Q\} = (\forall x. \{P\} R x \{> Q\})$
⟨proof⟩

3.2.2 Characterization of reachability

lemma *reach-init*: $\text{reach } T \subseteq I \implies \text{init } T \subseteq I$
⟨proof⟩

lemma *reach-trans*: $\text{reach } T \subseteq I \implies \{\text{reach } T\} \text{ trans } T \{> I\}$
⟨proof⟩

Useful consequences.

corollary *init-reach* [*iff*]: $\text{init } T \subseteq \text{reach } T$
⟨proof⟩

corollary *trans-reach* [*iff*]: $\{\text{reach } T\} \text{ trans } T \{> \text{reach } T\}$
⟨proof⟩

3.2.3 Invariant proof rules

Basic proof rule for invariants.

lemma *inv-rule-basic*:

$\llbracket \text{init } T \subseteq P; \{P\} (\text{trans } T) \{> P\} \rrbracket$

$\implies \text{reach } T \subseteq P$

(proof)

General invariant proof rule. This rule is complete (set $I = \text{reach } T$).

lemma *inv-rule*:

$\llbracket \text{init } T \subseteq I; I \subseteq P; \{I\} (\text{trans } T) \{> I\} \rrbracket$

$\implies \text{reach } T \subseteq P$

(proof)

The following rule is equivalent to the previous one.

lemma *INV-rule*:

$\llbracket \text{init } T \subseteq I; \{I \cap \text{reach } T\} (\text{trans } T) \{> I\} \rrbracket$

$\implies \text{reach } T \subseteq I$

(proof)

Proof of equivalence.

lemma *inv-rule-from-INV-rule*:

$\llbracket \text{init } T \subseteq I; I \subseteq P; \{I\} (\text{trans } T) \{> I\} \rrbracket$

$\implies \text{reach } T \subseteq P$

(proof)

lemma *INV-rule-from-inv-rule*:

$\llbracket \text{init } T \subseteq I; \{I \cap \text{reach } T\} (\text{trans } T) \{> I\} \rrbracket$

$\implies \text{reach } T \subseteq I$

(proof)

Incremental proof rule for invariants using auxiliary invariant(s). This rule might have become obsolete by addition of *INV_rule*.

lemma *inv-rule-incr*:

$\llbracket \text{init } T \subseteq I; \{I \cap J\} (\text{trans } T) \{> I\}; \text{reach } T \subseteq J \rrbracket$

$\implies \text{reach } T \subseteq I$

(proof)

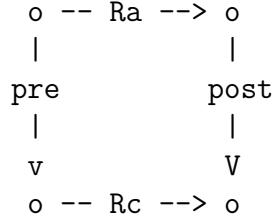
3.3 Refinement

Our notion of refinement is simulation. We first define a general notion of relational Hoare tuple, which we then use to define the refinement proof

obligation. Finally, we show that observation-consistent refinement of specifications implies the implementation relation between them.

3.3.1 Relational Hoare tuples

Relational Hoare tuples formalize the following generalized simulation diagram:



Here, Ra and Rc are the abstract and concrete transition relations, and pre and $post$ are the pre- and post-relations. (In the definition below, the operator (O) stands for relational composition, which is defined as follows: $(O) \equiv \lambda r s. \{(xa, x). ((\lambda x xa. (x, xa) \in r) OO (\lambda x xa. (x, xa) \in s)) xa x\}.$)

definition

```

PO-rhoare :: 
  [('s × 't) set, ('s × 's) set, ('t × 't) set, ('s × 't) set] ⇒ bool
  ⟨⟨(4{-}, - {>} -)⟩ [0, 0, 0] 90)

```

where

```
{pre} Ra, Rc {> post} ≡ pre O Rc ⊆ Ra O post
```

lemmas *PO-rhoare-defs* = *PO-rhoare-def relcomp-unfold*

Facts about relational Hoare tuples.

lemma *relhoare-conseq-left* [*intro*]:

```

[ {pre'} Ra, Rc {> post}; pre ⊆ pre' ]
  ⇒ {pre} Ra, Rc {> post}
⟨proof⟩

```

lemma *relhoare-conseq-right*:

— do NOT declare [*intro*]

```

[ {pre} Ra, Rc {> post'}; post' ⊆ post ]
  ⇒ {pre} Ra, Rc {> post}
⟨proof⟩

```

lemma *relhoare-false-left* [simp]:
 $\{ \{ \} \} Ra, Rc \{ > post \}$
⟨proof⟩

lemma *relhoare-true-right* [simp]: — not true in general
 $\{ pre \} Ra, Rc \{ > UNIV \} = (Domain (pre O Rc) \subseteq Domain Ra)$
⟨proof⟩

lemma *Domain-rel-comp* [intro]:
 $Domain pre \subseteq R \implies Domain (pre O Rc) \subseteq R$
⟨proof⟩

lemma *rel-hoare-skip* [iff]: $\{R\} Id, Id \{ > R \}$
⟨proof⟩

Reflexivity and transitivity.

lemma *relhoare-refl* [simp]: $\{ Id \} R, R \{ > Id \}$
⟨proof⟩

lemma *rhoare-trans*:
 $\llbracket \{R1\} T1, T2 \{ > R1 \}; \{R2\} T2, T3 \{ > R2 \} \rrbracket$
 $\implies \{R1 O R2\} T1, T3 \{ > R1 O R2 \}$
⟨proof⟩

Conjunction in the post-relation cannot be split in general. However, here are two useful special cases. In the first case the abstract transition relation is deterministic and in the second case one conjunct is a cartesian product of two state predicates.

lemma *relhoare-conj-right-det*:
 $\llbracket \{ pre \} Ra, Rc \{ > post1 \}; \{ pre \} Ra, Rc \{ > post2 \};$
 $single-valued Ra \rrbracket$ — only for deterministic Ra !
 $\implies \{ pre \} Ra, Rc \{ > post1 \cap post2 \}$
⟨proof⟩

lemma *relhoare-conj-right-cartesian* [intro]:
 $\llbracket \{ Domain pre \} Ra \{ > I \}; \{ Range pre \} Rc \{ > J \};$
 $\{ pre \} Ra, Rc \{ > post \} \rrbracket$
 $\implies \{ pre \} Ra, Rc \{ > post \cap I \times J \}$
⟨proof⟩

Separate rule for cartesian products.

corollary *relhoare-cartesian*:

$$\begin{aligned} & \llbracket \{\text{Domain pre}\} Ra \{> I\}; \{\text{Range pre}\} Rc \{> J\}; \\ & \quad \{\text{pre}\} Ra, Rc \{> \text{post}\} \rrbracket \qquad \qquad \qquad \text{— any post, including UNIV!} \\ & \implies \{\text{pre}\} Ra, Rc \{> I \times J\} \\ & \langle \text{proof} \rangle \end{aligned}$$

Unions of transition relations.

lemma *relhoare-concrete-Un* [simp]:

$$\begin{aligned} & \{\text{pre}\} Ra, Rc1 \cup Rc2 \{> \text{post}\} \\ & = (\{\text{pre}\} Ra, Rc1 \{> \text{post}\} \wedge \{\text{pre}\} Ra, Rc2 \{> \text{post}\}) \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *relhoare-concrete-UN* [simp]:

$$\begin{aligned} & \{\text{pre}\} Ra, \bigcup x. Rc x \{> \text{post}\} = (\forall x. \{\text{pre}\} Ra, Rc x \{> \text{post}\}) \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *relhoare-abstract-Un-left* [intro]:

$$\begin{aligned} & \llbracket \{\text{pre}\} Ra1, Rc \{> \text{post}\} \rrbracket \\ & \implies \{\text{pre}\} Ra1 \cup Ra2, Rc \{> \text{post}\} \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *relhoare-abstract-Un-right* [intro]:

$$\begin{aligned} & \llbracket \{\text{pre}\} Ra2, Rc \{> \text{post}\} \rrbracket \\ & \implies \{\text{pre}\} Ra1 \cup Ra2, Rc \{> \text{post}\} \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *relhoare-abstract-UN* [intro!]: — might be too aggressive?

$$\begin{aligned} & \llbracket \{\text{pre}\} Ra x, Rc \{> \text{post}\} \rrbracket \\ & \implies \{\text{pre}\} \bigcup x. Ra x, Rc \{> \text{post}\} \\ & \langle \text{proof} \rangle \end{aligned}$$

3.3.2 Refinement proof obligations

A transition system refines another one if the initial states and the transitions are refined. Initial state refinement means that for each concrete initial state there is a related abstract one. Transition refinement means that the simulation relation is preserved (as expressed by a relational Hoare tuple).

definition

PO-refines ::

$[('s \times 't) \text{ set}, ('s, 'a) \text{ TS-scheme}, ('t, 'b) \text{ TS-scheme}] \Rightarrow \text{bool}$

where

PO-refines R Ta Tc \equiv (

- $\text{init } Tc \subseteq R^{‘(\text{init } Ta)}$
- $\wedge \{R\} (\text{trans } Ta), (\text{trans } Tc) \{> R\}$

)

Basic refinement rule. This is just an introduction rule for the definition.

lemma *refine-basic*:

$\llbracket \text{init } Tc \subseteq R^{‘(\text{init } Ta)}; \{R\} (\text{trans } Ta), (\text{trans } Tc) \{> R\} \rrbracket$
 $\implies \text{PO-refines } R \text{ Ta Tc}$

{proof}

The following proof rule uses individual invariants I and J of the concrete and abstract systems to strengthen the simulation relation R .

The hypotheses state that these state predicates are indeed invariants. Note that the pre-condition of the invariant preservation hypotheses for I and J are strengthened by adding the predicates *Domain* ($R \cap \text{UNIV} \times J$) and *Range* ($R \cap I \times \text{UNIV}$), respectively. In particular, the latter predicate may be essential, if a concrete invariant depends on the simulation relation and an abstract invariant, i.e. to "transport" abstract invariants to the concrete system.

lemma *refine-init-using-invariants*:

$\llbracket \text{init } Tc \subseteq R^{‘(\text{init } Ta)}; \text{init } Ta \subseteq I; \text{init } Tc \subseteq J \rrbracket$
 $\implies \text{init } Tc \subseteq (R \cap I \times J)^{‘(\text{init } Ta)}$

{proof}

lemma *refine-trans-using-invariants*:

$\llbracket \{R \cap I \times J\} (\text{trans } Ta), (\text{trans } Tc) \{> R\};$
 $\{I \cap \text{Domain } (R \cap \text{UNIV} \times J)\} (\text{trans } Ta) \{> I\};$
 $\{J \cap \text{Range } (R \cap I \times \text{UNIV})\} (\text{trans } Tc) \{> J\} \rrbracket$
 $\implies \{R \cap I \times J\} (\text{trans } Ta), (\text{trans } Tc) \{> R \cap I \times J\}$

{proof}

This is our main rule for refinements.

lemma *refine-using-invariants*:

$\llbracket \{R \cap I \times J\} (\text{trans } Ta), (\text{trans } Tc) \{> R\};$
 $\{I \cap \text{Domain } (R \cap \text{UNIV} \times J)\} (\text{trans } Ta) \{> I\};$

$$\begin{aligned} & \{J \cap \text{Range}(R \cap I \times \text{UNIV})\} \text{ (trans } Tc\text{) } \{> J\}; \\ & \text{init } Tc \subseteq R``(\text{init } Ta); \\ & \text{init } Ta \subseteq I; \text{ init } Tc \subseteq J \\ & \implies \text{PO-refines } (R \cap I \times J) \text{ } Ta \text{ } Tc \\ & \langle \text{proof} \rangle \end{aligned}$$

3.3.3 Deriving invariants from refinements

Some invariants can only be proved after the simulation has been established, because they depend on the simulation relation and some abstract invariants. Here is a rule to derive invariant theorems from the refinement.

lemma *PO-refines-implies-Range-init*:

$$\begin{aligned} & \text{PO-refines } R \text{ } Ta \text{ } Tc \implies \text{init } Tc \subseteq \text{Range } R \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *PO-refines-implies-Range-trans*:

$$\begin{aligned} & \text{PO-refines } R \text{ } Ta \text{ } Tc \implies \{\text{Range } R\} \text{ trans } Tc \{> \text{Range } R\} \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *PO-refines-implies-Range-invariant*:

$$\begin{aligned} & \text{PO-refines } R \text{ } Ta \text{ } Tc \implies \text{reach } Tc \subseteq \text{Range } R \\ & \langle \text{proof} \rangle \end{aligned}$$

The following rules are more useful in proofs.

corollary *INV-init-from-refinement*:

$$\begin{aligned} & [\text{PO-refines } R \text{ } Ta \text{ } Tc; \text{Range } R \subseteq I] \\ & \implies \text{init } Tc \subseteq I \\ & \langle \text{proof} \rangle \end{aligned}$$

corollary *INV-trans-from-refinement*:

$$\begin{aligned} & [\text{PO-refines } R \text{ } Ta \text{ } Tc; K \subseteq \text{Range } R; \text{Range } R \subseteq I] \\ & \implies \{K\} \text{ trans } Tc \{> I\} \\ & \langle \text{proof} \rangle \end{aligned}$$

corollary *INV-from-refinement*:

$$\begin{aligned} & [\text{PO-refines } R \text{ } Ta \text{ } Tc; \text{Range } R \subseteq I] \\ & \implies \text{reach } Tc \subseteq I \\ & \langle \text{proof} \rangle \end{aligned}$$

3.3.4 Transferring abstract invariants to concrete systems

lemmas *hoare-conseq* = *hoare-conseq-right*[*OF hoare-conseq-left*] **for** *P' R Q'*

lemma *PO-refines-implies-R-image-init*:

PO-refines R Ta Tc \implies *init Tc* \subseteq *R* “(*init Ta*)
(proof)

lemma *commute-dest*:

$\llbracket R \circ Tc \subseteq Ta \circ R; (sa, sc) \in R; (sc, sc') \in Tc \rrbracket \implies \exists sa'. (sa, sa') \in Ta \wedge (sa', sc') \in R$
(proof)

lemma *PO-refines-implies-R-image-trans*:

assumes *PO-refines R Ta Tc*
shows {*R* “reach *Ta*} trans *Tc* {> *R* “reach *Ta*} *(proof)*

lemma *PO-refines-implies-R-image-invariant*:

assumes *PO-refines R Ta Tc*
shows reach *Tc* \subseteq *R* “reach *Ta*
(proof)

lemma *abs-INV-init-transfer*:

assumes
PO-refines R Ta Tc
init Ta \subseteq *I*
shows *init Tc* \subseteq *R* “*I* *(proof)*

lemma *abs-INV-trans-transfer*:

assumes
ref: PO-refines R Ta Tc
and *abs-hoare: {I} trans Ta {> J}*
shows {*R* “*I*} trans *Tc* {> *R* “*J*}
(proof)

lemma *abs-INV-transfer*:

assumes
PO-refines R Ta Tc
reach Ta \subseteq *I*
shows *reach Tc* \subseteq *R* “*I* *(proof)*

3.3.5 Refinement of specifications

Lift relation membership to finite sequences

inductive-set

seq-lift :: $('s \times 't) set \Rightarrow ('s list \times 't list) set$

for $R :: ('s \times 't) set$

where

sl-nil [iff]: $([], []) \in seq-lift R$

| *sl-cons* [intro]:

$\llbracket (xs, ys) \in seq-lift R; (x, y) \in R \rrbracket \implies (x\#xs, y\#ys) \in seq-lift R$

inductive-cases *sl-cons-right-invert*: $(ba', t \# bc) \in seq-lift R$

For each concrete behaviour there is a related abstract one.

lemma *behaviour-refinement*:

assumes *PO-refines* $R Ta Tc bc \in beh Tc$

shows $\exists ba \in beh Ta. (ba, bc) \in seq-lift R$

$\langle proof \rangle$

Observation consistency of a relation is defined using a mediator function pi to abstract the concrete observation. This allows us to also refine the observables as we move down a refinement branch.

definition

obs-consistent ::

$[('s \times 't) set, 'p \Rightarrow 'o, ('s, 'o) spec, ('t, 'p) spec] \Rightarrow bool$

where

obs-consistent $R pi Sa Sc \equiv (\forall s t. (s, t) \in R \longrightarrow pi(obs Sc t) = obs Sa s)$

lemma *obs-consistent-refl* [iff]: *obs-consistent* $Id id S S$

$\langle proof \rangle$

lemma *obs-consistent-trans* [intro]:

$\llbracket obs\text{-consistent } R1 pi1 S1 S2; obs\text{-consistent } R2 pi2 S2 S3 \rrbracket$

$\implies obs\text{-consistent } (R1 O R2) (pi1 o pi2) S1 S3$

$\langle proof \rangle$

lemma *obs-consistent-empty*: *obs-consistent* $\{\} pi Sa Sc$

$\langle proof \rangle$

lemma *obs-consistent-conj1* [intro]:

obs-consistent $R \ pi \ Sa \ Sc \implies$ *obs-consistent* $(R \cap R') \ pi \ Sa \ Sc$
 $\langle proof \rangle$

lemma *obs-consistent-conj2* [intro]:

obs-consistent $R \ pi \ Sa \ Sc \implies$ *obs-consistent* $(R' \cap R) \ pi \ Sa \ Sc$
 $\langle proof \rangle$

lemma *obs-consistent-behaviours*:

$\llbracket \text{obs-consistent } R \ pi \ Sa \ Sc; bc \in beh \ Sc; ba \in beh \ Sa; (ba, bc) \in seq-lift \ R \rrbracket$
 $\implies map \ pi \ (map \ (obs \ Sc) \ bc) = map \ (obs \ Sa) \ ba$
 $\langle proof \rangle$

Definition of refinement proof obligations.

definition

refines ::
 $[('s \times 't) \ set, 'p \Rightarrow 'o, ('s, 'o) \ spec, ('t, 'p) \ spec] \Rightarrow bool$

where

refines $R \ pi \ Sa \ Sc \equiv$ *obs-consistent* $R \ pi \ Sa \ Sc \wedge PO\text{-refines}$ $R \ Sa \ Sc$

lemmas *refines-defs* =
refines-def *PO-refines-def*

lemma *refinesI*:

$\llbracket PO\text{-refines } R \ Sa \ Sc; obs\text{-consistent } R \ pi \ Sa \ Sc \rrbracket$
 $\implies refines \ R \ pi \ Sa \ Sc$
 $\langle proof \rangle$

lemma *PO-refines-from-refines*:

refines $R \ pi \ Sa \ Sc \implies PO\text{-refines}$ $R \ Sa \ Sc$
 $\langle proof \rangle$

Reflexivity and transitivity of refinement.

lemma *refinement-reflexive*: *refines* *Id* *id* *S S*
 $\langle proof \rangle$

lemma *refinement-transitive*:

$\llbracket refines \ R1 \ pi1 \ S1 \ S2; refines \ R2 \ pi2 \ S2 \ S3 \rrbracket$
 $\implies refines \ (R1 \ O \ R2) \ (pi1 \ o \ pi2) \ S1 \ S3$
 $\langle proof \rangle$

Soundness of refinement for proving implementation

lemma *observable-behaviour-refinement*:

$\llbracket \text{refines } R \text{ } pi \text{ } Sa \text{ } Sc; bc \in obeh \text{ } Sc \rrbracket \implies \text{map } pi \text{ } bc \in obeh \text{ } Sa$
 $\langle proof \rangle$

theorem *refinement-soundness*:

$\text{refines } R \text{ } pi \text{ } Sa \text{ } Sc \implies \text{implements } pi \text{ } Sa \text{ } Sc$
 $\langle proof \rangle$

Extended versions of proof rules including observations

lemmas *Refinement-basic* = *refine-basic* [THEN *refinesI*]

lemmas *Refinement-using-invariants* = *refine-using-invariants* [THEN *refinesI*]

lemmas *INV-init-from-Refinement* =

INV-init-from-refinement [OF *PO-refines-from-refines*]

lemmas *INV-trans-from-Refinement* =

INV-trans-from-refinement [OF *PO-refines-from-refines*]

lemmas *INV-from-Refinement* =

INV-from-refinement [OF *PO-refines-from-refines*]

end

3.4 Transition system semantics for HO models

The HO development already defines two trace semantics for algorithms in this model, the coarse- and fine-grained ones. However, both of these are defined on infinite traces. Since the semantics of our transition systems are defined on finite traces, we also provide such a semantics for the HO model. Since we only use refinement for safety properties, the result also extend to infinite traces (although we do not prove this in Isabelle).

definition *CHO-trans* **where**

CHO-trans A *HOS* *SHOS* *coord* =
 $\{((r, st), (r', st')) | r \ r' \ st \ st'.$
 $r' = Suc \ r$
 $\wedge \ CSHOnextConfig \ A \ r \ st \ (HOS \ r) \ (SHOS \ r) \ (coord \ r) \ st'$
 $\}$

definition *CHO-to-TS* ::
 $('proc, 'pst, 'msg) CHOAlgorithm$
 $\Rightarrow (nat \Rightarrow 'proc HO)$
 $\Rightarrow (nat \Rightarrow 'proc HO)$
 $\Rightarrow (nat \Rightarrow 'proc coord)$
 $\Rightarrow (nat \times ('proc \Rightarrow 'pst)) TS$

where

CHO-to-TS A HOs SHOs coord $\equiv ()$
 $init = \{(0, st) | st. CHOinitConfig A st (coord 0)\},$
 $trans = CHO\text{-}trans A HOs SHOs coord$
 \emptyset

definition *get-msgs* ::
 $('proc \Rightarrow 'proc \Rightarrow 'pst \Rightarrow 'msg)$
 $\Rightarrow ('proc \Rightarrow 'pst)$
 $\Rightarrow 'proc HO$
 $\Rightarrow 'proc HO$
 $\Rightarrow 'proc \Rightarrow ('proc \multimap 'msg) set$

where

get-msgs snd-f cfg HO SHO $\equiv \lambda p.$
 $\{\mu. (\forall q. q \in HO p \longleftrightarrow \mu q \neq None)$
 $\wedge (\forall q. q \in SHO p \cap HO p \longrightarrow \mu q = Some (snd-f q p (cfg q)))\}$

definition *CSHO-trans-alt*

::
 $(nat \Rightarrow 'proc \Rightarrow 'proc \Rightarrow 'pst \Rightarrow 'msg)$
 $\Rightarrow (nat \Rightarrow 'proc \Rightarrow 'pst \Rightarrow ('proc \multimap 'msg) \Rightarrow 'proc \Rightarrow 'pst \Rightarrow bool)$
 $\Rightarrow (nat \Rightarrow 'proc HO)$
 $\Rightarrow (nat \Rightarrow 'proc HO)$
 $\Rightarrow (nat \Rightarrow 'proc \Rightarrow 'proc)$
 $\Rightarrow ((nat \times ('proc \Rightarrow 'pst)) \times (nat \times ('proc \Rightarrow 'pst))) set$

where

CSHO-trans-alt snd-f nxt-st HOs SHOs coords \equiv
 $\bigcup r \mu. \{((r, cfg), (Suc r, cfg')) | cfg \neq cfg'. \forall p.$
 $\mu p \in (get-msgs (snd-f r) cfg (HOs r) (SHOs r) p)$
 $\wedge (\forall p. nxt-st r p (cfg p) (\mu p) (coords r p) (cfg' p))$
 $\}$

lemma *CHO-trans-alt*:

*CHO-trans A HOs SHOs coords = CSHO-trans-alt (sendMsg A) (CnextState A)
 HOs SHOs coords*
(proof)

definition K where

$$K y \equiv \lambda x. y$$

lemma SHOmsgVectors-get-msgs:

*SHOmsgVectors A r p cfg HOOp SHOp = get-msgs (sendMsg A r) cfg (K HOOp)
 (K SHOp) p*
(proof)

lemma get-msgs-K:

$$\begin{aligned} & \text{get-msgs snd-f cfg (K (HOs r p)) (K (SHOs r p)) p} \\ &= \text{get-msgs snd-f cfg (HOs r) (SHOs r) p} \end{aligned}$$

(proof)

lemma CSHORun-get-msgs:

CSHORun (A :: ('proc, 'pst, 'msg) CHOAlgorithm) rho HOs SHOs coords = (
CHOinitConfig A (rho 0) (coords 0)
^ (forall r. exists mu.
(forall p.
mu p in get-msgs (sendMsg A r) (rho r) (HOs r) (SHOs r) p
^ CnextState A r p (rho r p) (mu p) (coords (Suc r) p) (rho (Suc r) p))))
(proof)

lemmas CSHORun-step = CSHORun-get-msgs[THEN iffD1, THEN conjunct2]

lemma get-msgs-dom:

msgs in get-msgs send s HOs SHOs p ==> dom msgs = HOs p
(proof)

lemma get-msgs-benign:

get-msgs snd-f cfg HOs HOs p = { (Some o (lambda q. (snd-f q p (cfg q)))) | ' (HOs p)}
(proof)

end

4 The Voting Model

theory *Voting imports Refinement Consensus-Misc Quorums*
begin

4.1 Model definition

record *v-state* =

next-round :: *round*
votes :: *round* \Rightarrow (*process, val*) *map*
decisions :: (*process, val*)*map*

Initially, no rounds have been executed (the next round is 0), no votes have been cast, and no decisions have been made.

definition *v-init* :: *v-state set where*

v-init = { () *next-round* = 0, *votes* = $\lambda r. a. None$, *decisions* = *Map.empty* () }

context *quorum-process* **begin**

definition *quorum-for* :: *process set* \Rightarrow *val* \Rightarrow (*process, val*)*map* \Rightarrow *bool* **where**
quorum-for-def':
quorum-for *Q v v-f* \equiv *Q* \in *Quorum* \wedge *v-f* ‘ *Q* = {Some *v*}

The following definition of *quorum-for* is easier to reason about in Isabelle.

lemma *quorum-for-def*:

quorum-for *Q v v-f* = (*Q* \in *Quorum* \wedge ($\forall p \in Q. v-f p = Some v$))
⟨proof⟩

definition *locked-in-vf* :: (*process, val*)*map* \Rightarrow *val* \Rightarrow *bool* **where**
locked-in-vf *v-f v* \equiv $\exists Q. quorum-for *Q v v-f*$

definition *locked-in* :: *v-state* \Rightarrow *round* \Rightarrow *val* \Rightarrow *bool* **where**
locked-in *s r v* = *locked-in-vf* (*votes s r*) *v*

definition *d-guard* :: (*process* \Rightarrow *val option*) \Rightarrow (*process* \Rightarrow *val option*) \Rightarrow *bool*
where
d-guard r-decisions r-votes \equiv $\forall p. v$.
r-decisions p = Some v \longrightarrow *locked-in-vf r-votes v*

```

definition no-defection :: v-state  $\Rightarrow$  (process, val)map  $\Rightarrow$  round  $\Rightarrow$  bool where
  no-defection-def':
    no-defection s r-votes r  $\equiv$ 
       $\forall r' < r. \forall Q \in Quorum. \forall v. (votes s r')`Q = \{Some v\} \longrightarrow r\text{-votes}`Q \subseteq \{None, Some v\}$ 

```

The following definition of *no-defection* is easier to reason about in Isabelle.

lemma no-defection-def:

```

  no-defection s round-votes r =
     $(\forall r' < r. \forall a Q v. quorum\text{-for } Q v (votes s r') \wedge a \in Q \longrightarrow round\text{-votes } a \in \{None, Some v\})$ 
  ⟨proof⟩

```

```

definition locked :: v-state  $\Rightarrow$  val set where
  locked s = {v.  $\exists r. locked\text{-in } s r v$ }

```

The sole system event.

```

definition v-round :: round  $\Rightarrow$  (process, val)map  $\Rightarrow$  (process, val)map  $\Rightarrow$  (v-state  $\times$  v-state) set where
  v-round r r-votes r-decisions = {(s, s')}.
    — guards
    r = next-round s
     $\wedge$  no-defection s r-votes r
     $\wedge$  d-guard r-decisions r-votes
     $\wedge$  — actions
    s' = s()
    next-round := Suc r,
    votes := (votes s)(r := r-votes),
    decisions := (decisions s) ++ r-decisions
  }

```

lemmas v-evt-defs = v-round-def

```

definition v-trans :: (v-state  $\times$  v-state) set where
  v-trans = ( $\bigcup r v\text{-f } d\text{-f. v-round } r v\text{-f } d\text{-f}$ )  $\cup$  Id

```

```

definition v-TS :: v-state TS where
  v-TS = () init = v-init, trans = v-trans ()

```

lemmas $v\text{-}TS\text{-}defs = v\text{-}TS\text{-}def\ v\text{-}init\text{-}def\ v\text{-}trans\text{-}def$

4.2 Invariants

The only rounds where votes could have been cast are the ones preceding the next round.

definition $Vinv1$ **where**

$$Vinv1 = \{s. \forall r. \text{next-round } s \leq r \longrightarrow \text{votes } s r = \text{Map.empty}\}$$

lemmas $Vinv1I = Vinv1\text{-def [THEN setc-def-to-intro, rule-format]}$

lemmas $Vinv1E [\text{elim}] = Vinv1\text{-def [THEN setc-def-to-elim, rule-format]}$

lemmas $Vinv1D = Vinv1\text{-def [THEN setc-def-to-dest, rule-format]}$

The votes cast must respect the *no-defection* property.

definition $Vinv2$ **where**

$$Vinv2 = \{s. \forall r. \text{no-defection } s (\text{votes } s r) r\}$$

lemmas $Vinv2I = Vinv2\text{-def [THEN setc-def-to-intro, rule-format]}$

lemmas $Vinv2E [\text{elim}] = Vinv2\text{-def [THEN setc-def-to-elim, rule-format]}$

lemmas $Vinv2D = Vinv2\text{-def [THEN setc-def-to-dest, rule-format]}$

definition $Vinv3$ **where**

$$Vinv3 = \{s. \text{ran } (\text{decisions } s) \subseteq \text{locked } s\}$$

lemmas $Vinv3I = Vinv3\text{-def [THEN setc-def-to-intro, rule-format]}$

lemmas $Vinv3E [\text{elim}] = Vinv3\text{-def [THEN setc-def-to-elim, rule-format]}$

lemmas $Vinv3D = Vinv3\text{-def [THEN setc-def-to-dest, rule-format]}$

4.2.1 Proofs of invariants

lemma $Vinv1\text{-v-round}:$

$$\{\text{Vinv1}\} \text{ v-round } r \text{ v-f d-f } \{> \text{Vinv1}\} \\ \langle \text{proof} \rangle$$

lemmas $Vinv1\text{-event-pres} = Vinv1\text{-v-round}$

lemma $Vinv1\text{-inductive}:$

$$\text{init } v\text{-}TS \subseteq \text{Vinv1} \\ \{\text{Vinv1}\} \text{ trans } v\text{-}TS \{> \text{Vinv1}\} \\ \langle \text{proof} \rangle$$

lemma *Vinv1-invariant: reach v-TS \subseteq Vinv1*
 $\langle proof \rangle$

The following two lemmas will be useful later, when we start taking votes with the maximum timestamp.

lemma *Vinv1-finite-map-graph:*
 $s \in Vinv1 \implies \text{finite}(\text{map-graph}(\text{case-prod}(\text{votes } s)))$
 $\langle proof \rangle$

lemma *Vinv1-finite-vote-set:*
 $s \in Vinv1 \implies \text{finite}(\text{vote-set}(\text{votes } s) Q)$
 $\langle proof \rangle$

lemma *process-mru-map-add:*
assumes
 $s \in Vinv1$
shows
 $\text{process-mru}((\text{votes } s)(\text{next-round } s := v-f)) =$
 $(\text{process-mru } (\text{votes } s) ++ (\lambda p. \text{map-option}(\text{Pair } (\text{next-round } s)) (v-f p)))$
 $\langle proof \rangle$

lemma *no-defection-empty:*
 $\text{no-defection } s \text{ Map.empty } r'$
 $\langle proof \rangle$

lemma *no-defection-preserved:*
assumes
 $s \in Vinv1$
 $r = \text{next-round } s$
 $\text{no-defection } s \text{ v-f } r$
 $\text{no-defection } s \text{ (votes } s \text{ r') } r'$
 $\text{votes } s' = (\text{votes } s)(r := v-f)$
shows
 $\text{no-defection } s' \text{ (votes } s' \text{ r') } r' \langle proof \rangle$

lemma *Vinv2-v-round*:

$\{Vinv2 \cap Vinv1\} \text{ v-round } r \text{ v-f d-f } \{> Vinv2\}$
 $\langle proof \rangle$

lemmas *Vinv2-event-pres = Vinv2-v-round*

lemma *Vinv2-inductive*:

init v-TS \subseteq *Vinv2*
 $\{Vinv2 \cap Vinv1\} \text{ trans } v-TS \{> Vinv2\}$
 $\langle proof \rangle$

lemma *Vinv2-invariant: reach v-TS* \subseteq *Vinv2*

$\langle proof \rangle$

lemma *locked-preserved*:

assumes

$s \in Vinv1$
 $r = \text{next-round } s$
 $\text{votes } s' = (\text{votes } s)(r := \text{v-f})$

shows

$\text{locked } s \subseteq \text{locked } s' \langle proof \rangle$

lemma *Vinv3-v-round*:

$\{Vinv3 \cap Vinv1\} \text{ v-round } r \text{ v-f d-f } \{> Vinv3\}$
 $\langle proof \rangle$

lemmas *Vinv3-event-pres = Vinv3-v-round*

lemma *Vinv3-inductive*:

init v-TS \subseteq *Vinv3*
 $\{Vinv3 \cap Vinv1\} \text{ trans } v-TS \{> Vinv3\}$
 $\langle proof \rangle$

lemma *Vinv3-invariant: reach v-TS* \subseteq *Vinv3*

$\langle proof \rangle$

4.3 Agreement and stability

Only a single value can be locked within the votes for one round.

lemma *locked-in-vf-same*:

$$[\![\text{locked-in-vf } v \text{-f } v; \text{locked-in-vf } v \text{-f } w]\!] \implies v = w \langle \text{proof} \rangle$$

In any reachable state, no two different values can be locked in different rounds.

theorem *locked-in-different*:

assumes

$$s \in Vinv2$$

$$\text{locked-in } s \text{ r1 } v$$

$$\text{locked-in } s \text{ r2 } w$$

$$r1 < r2$$

shows

$$v = w$$

$$\langle \text{proof} \rangle$$

It is simple to extend the previous theorem to any two (not necessarily different) rounds.

theorem *locked-unique*:

assumes

$$s \in Vinv2$$

$$v \in \text{locked } s \text{ } w \in \text{locked } s$$

shows

$$v = w$$

$$\langle \text{proof} \rangle$$

We now prove that decisions are stable; once a process makes a decision, it never changes it, and it does not go back to an undecided state. Note that behaviors grow at the front; hence $tr ! (i - j)$ is later in the trace than $tr ! i$.

lemma *stable-decision*:

assumes $beh: tr \in beh \text{ } v\text{-TS}$

and $len: i < \text{length } tr$

and $s: s = \text{nth } tr \text{ } i$

and $t: t = \text{nth } tr \text{ } (i - j)$

and $dec:$

$\text{decisions } s \text{ } p = \text{Some } v$

shows

decisions $t p = \text{Some } v$
 $\langle proof \rangle$

Finally, we prove that the Voting model ensures agreement. Without a loss of generality, we assume that t precedes s in the trace.

lemma *Voting-agreement*:

assumes beh: $tr \in \text{beh } v\text{-TS}$
and len: $i < \text{length } tr$
and s: $s = \text{nth } tr i$
and t: $t = \text{nth } tr (i - j)$
and dec:
decisions $s p = \text{Some } v$
decisions $t q = \text{Some } w$

shows $w = v$
 $\langle proof \rangle$

end

end

5 The Optimized Voting Model

theory *Voting-Opt*

imports *Voting*

begin

5.1 Model definition

record *opt-v-state* =
next-round :: round
last-vote :: (*process*, *val*) map
decisions :: (*process*, *val*) map

definition *flv-init* **where**

$\text{flv-init} = \{ () \mid \text{next-round} = 0, \text{last-vote} = \text{Map.empty}, \text{decisions} = \text{Map.empty} \}$

context *quorum-process* **begin**

definition $fmr\text{-}lv :: (\text{process}, \text{round} \times \text{val})\text{map} \Rightarrow (\text{process set}, \text{round} \times \text{val})\text{map}$

where

$fmr\text{-}lv lvs Q = \text{option-Max-by fst} (\text{ran} (lvs \mid^{\cdot} Q))$

definition $flv\text{-guard} :: (\text{process}, \text{round} \times \text{val})\text{map} \Rightarrow \text{process set} \Rightarrow \text{val} \Rightarrow \text{bool}$

where

$flv\text{-guard} lvs Q v \equiv Q \in \text{Quorum} \wedge$

$(\text{let } alv = fmr\text{-}lv lvs Q \text{ in } alv = \text{None} \vee (\exists r. alv = \text{Some} (r, v)))$

definition $opt\text{-no-defection} :: opt\text{-v-state} \Rightarrow (\text{process}, \text{val})\text{map} \Rightarrow \text{bool}$ **where**

$opt\text{-no-defection-def}':$

$opt\text{-no-defection} s \text{ round-votes} \equiv$

$\forall v. \forall Q. \text{quorum-for } Q v (\text{last-vote } s) \longrightarrow \text{round-votes}^{\cdot} Q \subseteq \{\text{None}, \text{Some } v\}$

lemma $opt\text{-no-defection-def}:$

$opt\text{-no-defection} s \text{ round-votes} =$

$(\forall a Q v. \text{quorum-for } Q v (\text{last-vote } s) \wedge a \in Q \longrightarrow \text{round-votes } a \in \{\text{None}, \text{Some } v\})$

$\langle \text{proof} \rangle$

definition $flv\text{-round} :: \text{round} \Rightarrow (\text{process}, \text{val})\text{map} \Rightarrow (\text{process}, \text{val})\text{map} \Rightarrow (\text{opt-v-state} \times \text{opt-v-state}) \text{ set}$ **where**

$flv\text{-round} r r\text{-votes} r\text{-decisions} = \{(s, s') .$

— guards

$r = \text{next-round } s$

$\wedge opt\text{-no-defection} s r\text{-votes}$

$\wedge d\text{-guard } r\text{-decisions } r\text{-votes}$

$\wedge — \text{actions}$

$s' = s()$

$\text{next-round} := \text{Suc } r$

$, \text{last-vote} := \text{last-vote } s ++ r\text{-votes}$

$, \text{decisions} := (\text{decisions } s) ++ r\text{-decisions}$

)

}

lemmas $flv\text{-evt-defs} = flv\text{-round-def} flv\text{-guard-def}$

definition $flv\text{-trans} :: (\text{opt-v-state} \times \text{opt-v-state}) \text{ set}$ **where**

$flv\text{-trans} = (\bigcup r v\text{-f } d\text{-f}. flv\text{-round } r v\text{-f } d\text{-f})$

```

definition flv-TS :: opt-v-state TS where
  flv-TS = () init = flv-init, trans = flv-trans ()

lemmas flv-TS-defs = flv-TS-def flv-init-def flv-trans-def

```

5.2 Refinement

```

definition flv-ref-rel :: (v-state × opt-v-state) set where
  flv-ref-rel = {(sa, sc).
    sc = ()
    next-round = v-state.next-round sa
    , last-vote = map-option snd o (process-mru (votes sa))
    , decisions = v-state.decisions sa
  }
}

```

5.2.1 Guard strengthening

```

lemma process-mru-Max:
  assumes
    inv: sa ∈ Vinv1
    and process-mru: process-mru (votes sa) p = Some (r, v)
  shows
    votes sa r p = Some v ∧ (∀ r' > r. votes sa r' p = None)
  ⟨proof⟩

```

```

lemma opt-no-defection-imp-no-defection:
  assumes
    conc-guard: opt-no-defection sc round-votes
    and R: (sa, sc) ∈ flv-ref-rel
    and ainv: sa ∈ Vinv1 sa ∈ Vinv2
  shows
    no-defection sa round-votes r
  ⟨proof⟩

```

5.2.2 Action refinement

```

lemma act-ref:
  assumes
    inv: s ∈ Vinv1

```

shows

$$\begin{aligned} & \text{map-option snd } o (\text{process-mru } ((\text{votes } s)(v\text{-state.next-round } s := v\text{-f}))) \\ & = ((\text{map-option snd } o (\text{process-mru } (\text{votes } s))) ++ v\text{-f}) \end{aligned}$$

$\langle \text{proof} \rangle$

5.2.3 The complete refinement proof

lemma *flv-round-refines*:

$$\begin{aligned} & \{\text{flv-ref-rel} \cap (\text{Vinv1} \cap \text{Vinv2}) \times \text{UNIV}\} \\ & \quad v\text{-round } r \text{ v-f d-f, flv-round } r \text{ v-f d-f} \\ & \{> \text{flv-ref-rel}\} \\ & \langle \text{proof} \rangle \end{aligned}$$

lemma *Last-Voting-Refines*:

$$\begin{aligned} & \text{PO-refines } (\text{flv-ref-rel} \cap (\text{Vinv1} \cap \text{Vinv2}) \times \text{UNIV}) \text{ v-TS flv-TS} \\ & \langle \text{proof} \rangle \end{aligned}$$

end

end

6 The OneThirdRule Algorithm

```
theory OneThirdRule-Defs
imports Heard-Of.HOModel .. / Consensus-Types
begin
```

The contents of this file have been taken almost verbatim from the Heard Of Model AFP entry. The only difference is that the types have been changed.

6.1 Model of the algorithm

The state of each process consists of two fields: *last-vote* holds the current value proposed by the process and *decision* the value (if any, hence the option type) it has decided.

```
record 'val pstate =
  last-vote :: 'val
  decision :: 'val option
```

The initial value of field *last-vote* is unconstrained, but no decision has been taken initially.

definition *OTR-initState* **where**

$$\text{OTR-initState } p \text{ st} \equiv \text{decision st} = \text{None}$$

Given a vector *msgs* of values (possibly null) received from each process, *HOV msgs v* denotes the set of processes from which value *v* was received.

definition *HOV* :: (*process* \Rightarrow '*val option*') \Rightarrow '*val* \Rightarrow *process set* **where**

$$\text{HOV msgs v} \equiv \{ q . \text{msgs } q = \text{Some v} \}$$

MFR msgs v ("most frequently received") holds for vector *msgs* if no value has been received more frequently than *v*.

Some such value always exists, since there is only a finite set of processes and thus a finite set of possible cardinalities of the sets *HOV msgs v*.

definition *MFR* :: (*process* \Rightarrow '*val option*') \Rightarrow '*val* \Rightarrow *bool* **where**

$$\text{MFR msgs v} \equiv \forall w. \text{card} (\text{HOV msgs w}) \leq \text{card} (\text{HOV msgs v})$$

lemma *MFR-exists*: $\exists v. \text{MFR msgs v}$

(proof)

Also, if a process has heard from at least one other process, the most frequently received values are among the received messages.

lemma *MFR-in-msgs*:

assumes *HO:HOs m p* $\neq \{\}$

and *v: MFR (HOrcvdMsgs OTR-M m p (HOs m p) (rho m)) v*

(is MFR ?msgs v)

shows $\exists q \in \text{HOs m p}. v = \text{the} (\text{?msgs } q)$

(proof)

TwoThirds msgs v holds if value *v* has been received from more than 2/3 of all processes.

definition *TwoThirds* **where**

$$\text{TwoThirds msgs v} \equiv (2*N) \text{ div } 3 < \text{card} (\text{HOV msgs v})$$

The next-state relation of algorithm *One-Third Rule* for every process is defined as follows: if the process has received values from more than 2/3 of all processes, the *last-vote* field is set to the smallest among the most frequently received values, and the process decides value *v* if it received *v* from more than 2/3 of all processes. If *p* hasn't heard from more than

$2/3$ of all processes, the state remains unchanged. (Note that *Some* is the constructor of the option datatype, whereas ϵ is Hilbert’s choice operator.) We require the type of values to be linearly ordered so that the minimum is guaranteed to be well-defined.

definition *OTR-nextState* **where**

```

OTR-nextState r p (st::('val::linorder) pstate) msgs st' ≡
  if (2*N) div 3 < card {q. msgs q ≠ None}
    then st' = () last-vote = Min {v . MFR msgs v},
        decision = (if (exists v. TwoThirds msgs v)
                     then Some (epsilon v. TwoThirds msgs v)
                     else decision st)
    else st' = st

```

The message sending function is very simple: at every round, every process sends its current proposal (field *last-vote* of its local state) to all processes.

definition *OTR-sendMsg* **where**

```
OTR-sendMsg r p q st ≡ last-vote st
```

6.2 Communication predicate for *One-Third Rule*

We now define the communication predicate for the *One-Third Rule* algorithm to be correct. It requires that, infinitely often, there is a round where all processes receive messages from the same set Π of processes where Π contains more than two thirds of all processes. The “per-round” part of the communication predicate is trivial.

definition *OTR-commPerRd* **where**

```
OTR-commPerRd HOrs ≡ True
```

definition *OTR-commGlobal* **where**

```

OTR-commGlobal HOs ≡
   $\forall r. \exists r0 \Pi. r0 \geq r \wedge (\forall p. HOs r0 p = \Pi) \wedge \text{card } \Pi > (2*N) \text{ div } 3$ 

```

6.3 The *One-Third Rule* Heard-Of machine

We now define the HO machine for the *One-Third Rule* algorithm by assembling the algorithm definition and its communication-predicate. Because this is an uncoordinated algorithm, the *crd* arguments of the initial- and next-state predicates are unused.

```

definition OTR-HOMachine where
  OTR-HOMachine =
    () CinitState = (λ p st crd. OTR-initState p st),
    sendMsg = OTR-sendMsg,
    CnextState = (λ r p st msgs crd st'. OTR-nextState r p st msgs st'),
    HOcommPerRd = OTR-commPerRd,
    HOcommGlobal = OTR-commGlobal )

abbreviation OTR-M ≡ OTR-HOMachine::(process, 'val::linorder pstate, 'val)
HOMachine

end

```

6.4 Proofs

```

definition majs :: (process set) set where
  majs ≡ {S. card S > (2 * N) div 3}

```

```

lemma card-Compl:
  fixes S :: ('a :: finite) set
  shows card (-S) = card (UNIV :: 'a set) - card S
  ⟨proof⟩

```

```

lemma m-mult-div-Suc-m:
  n > 0 ⟹ m * n div Suc m < n
  ⟨proof⟩

```

```

interpretation majorities: quorum-process majs
  ⟨proof⟩

```

```

lemma card-Un-le:
  [finite A; finite B] ⟹ card (A ∪ B) ≤ card A + card B
  ⟨proof⟩

```

```

lemma qintersect-card:
  assumes Q ∈ majs Q' ∈ majs
  shows card (Q ∩ Q') > card (Q ∩ -Q')
  ⟨proof⟩

```

axiomatization where *val-linorder*:

OFCLASS(*val*, *linorder-class*)

instance *val* :: *linorder* ⟨*proof*⟩

type-synonym *p-TS-state* = (*nat* × (*process* ⇒ (*val pstate*)))

definition *K* **where**

$$K y \equiv \lambda x. y$$

definition *OTR-Alg* **where**

OTR-Alg =

$$\begin{aligned} & (\text{CinitState} = (\lambda p st crd. \text{OTR-initState } p st), \\ & \quad \text{sendMsg} = \text{OTR-sendMsg}, \\ & \quad \text{CnextState} = (\lambda r p st msgs crd st'. \text{OTR-nextState } r p st msgs st')) \\ &) \end{aligned}$$

definition *OTR-TS* ::

$$\begin{aligned} & (\text{round} \Rightarrow \text{process HO}) \\ & \Rightarrow (\text{round} \Rightarrow \text{process HO}) \\ & \Rightarrow (\text{round} \Rightarrow \text{process}) \\ & \Rightarrow \text{p-TS-state TS} \end{aligned}$$

where

OTR-TS HOs SHOs crds = *CHO-to-TS OTR-Alg HOs SHOs (K o crds)*

lemmas *OTR-TS-defs* = *OTR-TS-def CHO-to-TS-def OTR-Alg-def CHOinit-Config-def OTR-initState-def*

definition

$$\begin{aligned} & \text{OTR-trans-step HOs} \equiv \bigcup r \mu. \\ & \{((r, cfg), Suc r, cfg') | cfg \neq cfg'\}. \\ & (\forall p. \mu p \in \text{get-msgs } (\text{OTR-sendMsg } r) \ cfg \ (HOs r) \ (HOs r) \ p) \wedge \\ & (\forall p. \text{OTR-nextState } r p \ (cfg p) \ (\mu p) \ (cfg' p)) \} \end{aligned}$$

definition *CSHOnextConfig* **where**

$$\begin{aligned} & \text{CSHOnextConfig } A r cfg HO SHO coord cfg' \equiv \\ & \forall p. \exists \mu \in \text{SHOmsgVectors } A r p cfg \ (HO p) \ (SHO p). \\ & \quad \text{CnextState } A r p \ (cfg p) \ \mu \ (coord p) \ (cfg' p) \end{aligned}$$

type-synonym $rHO = nat \Rightarrow process HO$

6.4.1 Refinement

definition $otr\text{-ref}\text{-rel} :: (opt\text{-}v\text{-}state \times p\text{-}TS\text{-}state) set$ **where**

```

 $otr\text{-ref}\text{-rel} = \{(sa, (r, sc)) .$ 
 $r = next\text{-}round sa$ 
 $\wedge (\forall p. decisions\ sa\ p = decision\ (sc\ p))$ 
 $\wedge majorities.\text{opt-no-defection}\ sa\ (Some\ o\ last\text{-}vote\ o\ sc)$ 
 $\}$ 
```

lemma $decide\text{-origin}:$

assumes

```

 $send: \mu p \in get\text{-}msgs (OTR\text{-}sendMsg r) sc (HOs r) (HOs r) p$ 
and  $nxt: OTR\text{-}nextState r p (sc\ p) (\mu p) (sc'\ p)$ 
and  $new\text{-}dec: decision (sc'\ p) \neq decision (sc\ p)$ 
```

shows

```

 $\exists v. decision (sc'\ p) = Some\ v \wedge \{q. last\text{-}vote (sc\ q) = v\} \in majs$ 
 $\langle proof \rangle$ 
```

lemma $MFR\text{-in}\text{-msgs}:$

assumes $HO:\text{dom msgs} \neq \{\}$

and $v: MFR\ msgs\ v$

shows $\exists q \in \text{dom msgs}. v = \text{the} (\text{msgs } q)$

$\langle proof \rangle$

lemma $step\text{-ref}:$

```

 $\{otr\text{-ref}\text{-rel}\}$ 
 $(\bigcup r\ v\text{-}f\ d\text{-}f. majorities.\text{flv-round}\ r\ v\text{-}f\ d\text{-}f),$ 
 $OTR\text{-trans-step}\ HOs$ 
 $\{> otr\text{-ref}\text{-rel}\}$ 
 $\langle proof \rangle$ 
```

lemma $OTR\text{-Refines-LV-Voting}:$

$PO\text{-refines} (otr\text{-ref}\text{-rel})$

$majorities.\text{flv-TS} (OTR\text{-TS}\ HOs\ HOs\ crds)$

$\langle proof \rangle$

6.4.2 Termination

The termination proof for the algorithm is already given in the Heard-Of Model AFP entry, and we do not repeat it here.

end

7 The $A_{T,E}$ Algorithm

```
theory Ate-Defs
imports Heard-Of.HOModel .. / Consensus-Types
begin
```

The contents of this file have been taken almost verbatim from the Heard Of Model AFP entry. The only difference is that the types have been changed.

7.1 Model of the algorithm

The following record models the local state of a process.

```
record 'val pstate =
  x :: 'val           — current value held by process
  decide :: 'val option — value the process has decided on, if any
```

The x field of the initial state is unconstrained, but no decision has yet been taken.

```
definition Ate-initState where
  Ate-initState p st ≡ (decide st = None)
```

```
locale ate-parameters =
  fixes α::nat and T::nat and E::nat
  assumes TNαE:T ≥ 2*(N + 2*α - E)
    and TltN:T < N
    and EltN:E < N
```

begin

The following are consequences of the assumptions on the parameters.

```
lemma majE: 2 * (E - α) ≥ N
⟨proof⟩
```

lemma $E \geq \alpha$

$\langle proof \rangle$

lemma $T \geq 2 * \alpha$

$\langle proof \rangle$

At every round, each process sends its current x . If it received more than T messages, it selects the smallest value and store it in x . As in algorithm *OneThirdRule*, we therefore require values to be linearly ordered.

If more than E messages holding the same value are received, the process decides that value.

definition $mostOftenRcvd$ **where**

$mostOftenRcvd (msgs::process \Rightarrow 'val option) \equiv$

$\{v. \forall w. card \{qq. msgs qq = Some w\} \leq card \{qq. msgs qq = Some v\}\}$

definition

$Ate-sendMsg :: nat \Rightarrow process \Rightarrow process \Rightarrow 'val pstate \Rightarrow 'val$

where

$Ate-sendMsg r p q st \equiv x st$

definition

$Ate-nextState :: nat \Rightarrow process \Rightarrow ('val::linorder) pstate \Rightarrow (process \Rightarrow 'val option)$

$\Rightarrow 'val pstate \Rightarrow bool$

where

$Ate-nextState r p st msgs st' \equiv$

$(if card \{q. msgs q \neq None\} > T$

$then x st' = Min (mostOftenRcvd msgs)$

$else x st' = x st)$

$\wedge (\exists v. card \{q. msgs q = Some v\} > E \wedge decide st' = Some v)$

$\vee \neg (\exists v. card \{q. msgs q = Some v\} > E)$

$\wedge decide st' = decide st)$

7.2 Communication predicate for $A_{T,E}$

definition $Ate-commPerRd$ **where**

$Ate-commPerRd HOrs SHOrs \equiv$

$\forall p. card (HOrs p - SHOrs p) \leq \alpha$

The global communication predicate stipulates the three following conditions:

- for every process p there are infinitely many rounds where p receives more than T messages,
- for every process p there are infinitely many rounds where p receives more than E uncorrupted messages,
- and there are infinitely many rounds in which more than $E - \alpha$ processes receive uncorrupted messages from the same set of processes, which contains more than T processes.

definition

```
Ate-commGlobal where
Ate-commGlobal HOs SHOs ≡
  (forall r p. exists r' > r. card (HOs r' p) > T)
  ∧ (forall r p. exists r' > r. card (SHOs r' p ∩ HOs r' p) > E)
  ∧ (forall r. exists r' > r. exists π1 π2.
    card π1 > E - α
    ∧ card π2 > T
    ∧ (forall p ∈ π1. HOs r' p = π2 ∧ SHOs r' p ∩ HOs r' p = π2))
```

7.3 The $A_{T,E}$ Heard-Of machine

We now define the non-coordinated SHO machine for the Ate algorithm by assembling the algorithm definition and its communication-predicate.

definition Ate-SHOMachine where

```
Ate-SHOMachine = ()
CinitState = (λ p st crd. Ate-initState p (st::('val::linorder) pstate)),
sendMsg = Ate-sendMsg,
CnextState = (λ r p st msgs crd st'. Ate-nextState r p st msgs st'),
SHOcommPerRd = (Ate-commPerRd:: process HO ⇒ process HO ⇒ bool),
SHOcommGlobal = Ate-commGlobal
)
```

abbreviation

```
Ate-M ≡ (Ate-SHOMachine::(process, 'val::linorder pstate, 'val) SHOMachine)
```

end — locale *ate-parameters*

end

7.4 Proofs

axiomatization where *val-linorder*:

OFCLASS(*val*, *linorder-class*)

instance *val* :: *linorder* $\langle proof \rangle$

context *ate-parameters*

begin

definition *majs* :: (*process set*) *set* **where**

majs $\equiv \{S. \text{card } S > E\}$

interpretation *majorities*: *quorum-process* *majs*
 $\langle proof \rangle$

type-synonym *p-TS-state* = (*nat* \times (*process* \Rightarrow (*val pstate*)))

definition *K* **where**

K *y* $\equiv \lambda x. y$

definition *Ate-Alg* **where**

Ate-Alg =

$\langle \begin{array}{l} CinitState = (\lambda p st crd. Ate-initState p st), \\ sendMsg = Ate-sendMsg, \\ CnextState = (\lambda r p st msgs crd st'. Ate-nextState r p st msgs st') \end{array} \rangle$

definition *Ate-TS* ::

$\begin{aligned} & (round \Rightarrow process HO) \\ & \Rightarrow (round \Rightarrow process HO) \\ & \Rightarrow (round \Rightarrow process) \\ & \Rightarrow p\text{-TS-state TS} \end{aligned}$

where

Ate-TS HOs SHOs crds = *CHO-to-TS Ate-Alg HOs SHOs (K o crds)*

lemmas *Ate-TS-defs* = *Ate-TS-def CHO-to-TS-def Ate-Alg-def CHOinitConfig-def*
Ate-initState-def

definition

$Ate\text{-}trans\text{-}step HOs \equiv \bigcup r \mu.$
 $\{((r, cfg), Suc r, cfg') | cfg \neq cfg'\}.$
 $(\forall p. \mu p \in get\text{-}msgs (Ate\text{-}sendMsg r) cfg (HOs r) (HOs r) p) \wedge$
 $(\forall p. Ate\text{-}nextState r p (cfg p) (\mu p) (cfg' p))\}$

definition *CSHOnextConfig* **where**
 $CSHOnextConfig A r cfg HO SHO coord cfg' \equiv$
 $\forall p. \exists \mu \in SHOmsgVectors A r p cfg (HO p) (SHO p).$
 $CnextState A r p (cfg p) \mu (coord p) (cfg' p)$

type-synonym $rHO = nat \Rightarrow process HO$

7.4.1 Refinement

definition *ate-ref-rel* :: $(opt\text{-}v\text{-}state \times p\text{-}TS\text{-}state) set$ **where**
 $ate\text{-}ref\text{-}rel = \{(sa, (r, sc)) .$
 $r = next\text{-}round sa$
 $\wedge (\forall p. decisions sa p = Ate\text{-}Defs.decide (sc p))$
 $\wedge majorities.opt\text{-}no\text{-}defection sa (Some o x o sc)$
 $\}$

lemma *decide-origin*:

assumes

$send: \mu p \in get\text{-}msgs (Ate\text{-}sendMsg r) sc (HOs r) (HOs r) p$

and $nxt: Ate\text{-}nextState r p (sc p) (\mu p) (sc' p)$

and $new\text{-}dec: decide (sc' p) \neq decide (sc p)$

shows

$\exists v. decide (sc' p) = Some v \wedge \{q. x (sc q) = v\} \in majs \langle proof \rangle$

lemma *other-values-received*:

assumes $nxt: Ate\text{-}nextState r q (sc q) \mu q ((sc') q)$

and $muq: \mu q \in get\text{-}msgs (Ate\text{-}sendMsg r) sc (HOs r) (HOs r) q$

and $vsent: card \{qq. sendMsg Ate\text{-}M r qq q (sc qq) = v\} > E - \alpha$

(is $card ?vsent > -$)

shows $card (\{qq. \mu q qq \neq Some v\} \cap HOs r q) \leq N + 2*\alpha - E$
 $\langle proof \rangle$

If more than $E - \alpha$ processes send a value v to some process q at some round r , and if q receives more than T messages in r , then v is the most frequently received value by q in r .

```

lemma mostOftenRcvd-v:
  assumes nxt: Ate-nextState r q (sc q) μq ((sc') q)
  and muq: μq ∈ get-msgs (Ate-sendMsg r) sc (HOs r) (HOs r) q
  and threshold-T: card {qq. μq qq ≠ None} > T
  and threshold-E: card {qq. sendMsg Ate-M r qq q (sc qq) = v} > E - α
  shows mostOftenRcvd μq = {v}
  ⟨proof⟩

```

```

lemma step-ref:
  {ate-ref-rel}
  ( $\bigcup r v\text{-}f d\text{-}f. \text{majorities.flv-round } r v\text{-}f d\text{-}f$ ),
   Ate-trans-step HOs
  {> ate-ref-rel}
  ⟨proof⟩

```

```

lemma Ate-Refines-LV-Voting:
  PO-refines (ate-ref-rel)
  majorities.flv-TS (Ate-TS HOs HOs crds)
  ⟨proof⟩

```

end — context *ate-parameters*

7.4.2 Termination

The termination proof for the algorithm is already given in the Heard-Of Model AFP entry, and we do not repeat it here.

end

8 The Same Vote Model

```

theory Same-Vote
imports Voting
begin

```

context quorum-process **begin**

8.1 Model definition

The system state remains the same as in the Voting model, but the voting event is changed.

```
definition safe :: v-state  $\Rightarrow$  round  $\Rightarrow$  val  $\Rightarrow$  bool where
  safe-def': safe s r v  $\equiv$ 
     $\forall r' < r. \forall Q \in Quorum. \forall w. (votes s r') \setminus Q = \{Some w\} \longrightarrow v = w$ 
```

This definition of *safe* is easier to reason about in Isabelle.

```
lemma safe-def:
  safe s r v =
     $(\forall r' < r. \forall Q w. quorum-for Q w (votes s r') \longrightarrow v = w)$ 
   $\langle proof \rangle$ 
```

```
definition sv-round :: round  $\Rightarrow$  process set  $\Rightarrow$  val  $\Rightarrow$  (process, val)map  $\Rightarrow$  (v-state  $\times$  v-state) set where
  sv-round r S v r-decisions = {(s, s')}.
    — guards
    r = next-round s
     $\wedge (S \neq \{\}) \longrightarrow safe s r v$ 
     $\wedge d\text{-guard } r\text{-decisions } (const-map v S)$ 
     $\wedge$  — actions
    s' = s()
      next-round := Suc r
      , votes := (votes s)(r := const-map v S)
      , decisions := (decisions s ++ r-decisions)
    )
  }
```

```
definition sv-trans :: (v-state  $\times$  v-state) set where
  sv-trans = ( $\bigcup r S v D. sv\text{-round } r S v D$ )  $\cup Id$ 
```

```
definition sv-TS :: v-state TS where
  sv-TS = () init = v-init, trans = sv-trans ()
```

```
lemmas sv-TS-defs = sv-TS-def v-init-def sv-trans-def
```

8.2 Refinement

```
lemma safe-imp-no-defection:
```

safe s (next-round s) v \implies no-defection s (const-map v S) (next-round s)
 $\langle proof \rangle$

lemma *const-map-quorum-locked*:
 $S \in Quorum \implies \text{locked-in-vf} (\text{const-map} v S) v$
 $\langle proof \rangle$

lemma *sv-round-refines*:
 $\{Id\} v\text{-round } r (\text{const-map} v S) r\text{-decisions}, sv\text{-round } r S v r\text{-decisions } \{> Id\}$
 $\langle proof \rangle$

lemma *Same-Vote-Refines*:
 $P O\text{-refines } Id v\text{-TS } sv\text{-TS}$
 $\langle proof \rangle$

8.3 Invariants

definition *SV-inv3 where*

$SV\text{-inv3} = \{s. \forall r a b v w.$
 $\quad votes s r a = Some v \wedge votes s r b = Some w \longrightarrow v = w$
 $\}$

lemmas *SV-inv3I* = *SV-inv3-def* [THEN setc-def-to-intro, rule-format]

lemmas *SV-inv3E* [elim] = *SV-inv3-def* [THEN setc-def-to-elim, rule-format]

lemmas *SV-inv3D* = *SV-inv3-def* [THEN setc-def-to-dest, rule-format]

8.3.1 Proof of invariants

lemma *SV-inv3-v-round*:
 $\{SV\text{-inv3}\} sv\text{-round } r S v D \{> SV\text{-inv3}\}$
 $\langle proof \rangle$

lemmas *SV-inv3-event-pres* = *SV-inv3-v-round*

lemma *SV-inv3-inductive*:
 $init sv\text{-TS} \subseteq SV\text{-inv3}$
 $\{SV\text{-inv3}\} trans sv\text{-TS} \{> SV\text{-inv3}\}$
 $\langle proof \rangle$

lemma *SV-inv3-invariant*: $reach sv\text{-TS} \subseteq SV\text{-inv3}$

$\langle proof \rangle$

This is a different characterization of *safe*, due to Lampson [4]: $safe' s r v = (\forall r' < r. \exists Q \in Quorum. \forall a \in Q. \forall w. votes s r' a = Some w \rightarrow w = v)$

It is, however, strictly stronger than our characterization, since we do not at this point assume the "completeness" of our quorum system (for any set S, either S or the complement of S is a quorum), and the following is thus not provable: $s \in majorities.SV\text{-}inv3 \implies safe' s = safe s$.

8.3.2 Transfer of abstract invariants

lemma *SV-inv1-inductive*:

```
init sv-TS ⊆ Vinv1
{Vinv1} trans sv-TS {> Vinv1}
⟨proof⟩
```

lemma *SV-inv1-invariant*:

```
reach sv-TS ⊆ Vinv1
⟨proof⟩
```

lemma *SV-inv2-inductive*:

```
init sv-TS ⊆ Vinv2
{Vinv2 ∩ Vinv1} trans sv-TS {> Vinv2}
⟨proof⟩
```

lemma *SV-inv2-invariant*:

```
reach sv-TS ⊆ Vinv2
⟨proof⟩
```

8.3.3 Additional invariants

With Same Voting, the voted values are safe in the next round.

definition *SV-inv4 :: v-state set where*

$$SV\text{-}inv4 = \{s. \forall v a r. votes s r a = Some v \rightarrow safe s (Suc r) v\}$$

lemmas *SV-inv4I = SV-inv4-def [THEN setc-def-to-intro, rule-format]*

lemmas *SV-inv4E [elim] = SV-inv4-def [THEN setc-def-to-elim, rule-format]*

lemmas *SV-inv4D = SV-inv4-def [THEN setc-def-to-dest, rule-format]*

```

lemma SV-inv4-sv-round:
  {SV-inv4 ∩ (Vinv1 ∩ Vinv2)} sv-round r S v D {> SV-inv4}
  ⟨proof⟩

```

```
lemmas SV-inv4-event-pres = SV-inv4-sv-round
```

```
lemma SV-inv4-inductive:
```

```

  init sv-TS ⊆ SV-inv4
  {SV-inv4 ∩ (Vinv1 ∩ Vinv2)} trans sv-TS {> SV-inv4}
  ⟨proof⟩

```

```

lemma SV-inv4-invariant: reach sv-TS ⊆ SV-inv4
  ⟨proof⟩

```

```
end
```

```
end
```

9 The Observing Quorums Model

```

theory Observing-Quorums
imports Same-Vote
begin

```

9.1 Model definition

The state adds one field to the Voting model state:

```

record obsv-state = v-state +
  obs :: round ⇒ (process, val) map

```

For the observation mechanism to work, we need monotonicity of quorums.

```
context mono-quorum begin
```

```

definition obs-safe
  where
    obs-safe r s v ≡ (forall r' < r. exists p. obs s r' p ∈ {None, Some v})

```

```
definition obsv-round
```

$:: round \Rightarrow process\ set \Rightarrow val \Rightarrow (process, val)map \Rightarrow process\ set \Rightarrow (obsv-state \times obsv-state)\ set$

where

$obsv-round\ r\ S\ v\ r\text{-decisions}\ Os = \{(s, s')\}.$

- guards
- $r = next-round\ s$
- $\wedge (S \neq \{\}) \rightarrow obs-safe\ r\ s\ v)$
- $\wedge d\text{-guard}\ r\text{-decisions}\ (const-map\ v\ S)$
- $\wedge (S \in Quorum \rightarrow Os = UNIV)$
- $\wedge (Os \neq \{\}) \rightarrow S \neq \{\}$
- actions
- $s' = s\langle \rangle$
- $next-round := Suc\ r$
- , $votes := (votes\ s)(r := const-map\ v\ S)$
- , $decisions := decisions\ s\ ++\ r\text{-decisions}$
- , $obs := (obs\ s)(r := const-map\ v\ Os)$

||

}

definition $obsv-trans :: (obsv-state \times obsv-state)\ set$ **where**

$obsv-trans = (\bigcup r\ S\ v\ d\text{-f}\ Os.\ obsv-round\ r\ S\ v\ d\text{-f}\ Os) \cup Id$

definition $obsv-init :: obsv-state\ set$ **where**

$obsv-init = \{ \langle \rangle | next-round = 0, votes = \lambda r. None, decisions = Map.empty, obs = \lambda r. None \rangle \}$

definition $obsv-TS :: obsv-state\ TS$ **where**

$obsv-TS = \langle init = obsv-init, trans = obsv-trans \rangle$

lemmas $obsv-TS-defs = obsv-TS\text{-def}\ obsv-init\text{-def}\ obsv-trans\text{-def}$

9.2 Invariants

definition $OV-inv1$ **where**

$OV-inv1 = \{s. \forall r\ Q\ v. quorum-for\ Q\ v\ (votes\ s\ r) \rightarrow (\forall Q' \in Quorum. quorum-for\ Q'\ v\ (obs\ s\ r))\}$

lemmas $OV-inv1I = OV-inv1\text{-def}$ [THEN setc-def-to-intro, rule-format]

lemmas $OV-inv1E = OV-inv1\text{-def}$ [THEN setc-def-to-elim, rule-format]

lemmas $OV-inv1D = OV-inv1\text{-def}$ [THEN setc-def-to-dest, rule-format]

9.2.1 Proofs of invariants

lemma *OV-inv1-obsv-round*:

$\{OV\text{-}inv1\} \text{ obsv-round } r S v d\text{-}f Ob \{> OV\text{-}inv1\}$
 $\langle proof \rangle$

lemma *OV-inv1-inductive*:

$\text{init obsv-TS} \subseteq OV\text{-}inv1$
 $\{OV\text{-}inv1\} \text{ trans obsv-TS } \{> OV\text{-}inv1\}$
 $\langle proof \rangle$

lemma *quorum-for-const-map*:

$(\text{quorum-for } Q w (\text{const-map } v S)) = (Q \in \text{Quorum} \wedge Q \subseteq S \wedge w = v)$
 $\langle proof \rangle$

9.3 Refinement

definition *obsv-ref-rel* **where**

$\text{obsv-ref-rel} \equiv \{(sa, sc).$
 $sa = v\text{-state}.\text{truncate } sc$
 $\}$

lemma *obsv-round-refines*:

$\{\text{obsv-ref-rel} \cap \text{UNIV} \times OV\text{-}inv1\} \text{ sv-round } r S v \text{ dec-f, obsv-round } r S v \text{ dec-f}$
 $Ob \{> \text{obsv-ref-rel}\}$
 $\langle proof \rangle$

lemma *Observable-Refines*:

$P\text{O-refines } (\text{obsv-ref-rel} \cap \text{UNIV} \times OV\text{-}inv1) \text{ sv-TS obsv-TS}$
 $\langle proof \rangle$

9.4 Additional invariants

definition *OV-inv2* **where**

$OV\text{-}inv2 = \{s. \forall r \geq \text{next-round } s. \text{ obs } s r = \text{Map.empty}\}$

lemmas *OV-inv2I* = *OV-inv2-def* [THEN setc-def-to-intro, rule-format]

lemmas *OV-inv2E* [elim] = *OV-inv2-def* [THEN setc-def-to-elim, rule-format]

lemmas *OV-inv2D* = *OV-inv2-def* [THEN setc-def-to-dest, rule-format]

definition *OV-inv3* **where**

$OV\text{-}inv3 = \{s. \forall r p v. obs s r p = Some v \rightarrow obs\text{-}safe r s v\}$

lemmas $OV\text{-}inv3I = OV\text{-}inv3\text{-}def$ [THEN setc-def-to-intro, rule-format]
lemmas $OV\text{-}inv3E$ [elim] = $OV\text{-}inv3\text{-}def$ [THEN setc-def-to-elim, rule-format]
lemmas $OV\text{-}inv3D = OV\text{-}inv3\text{-}def$ [THEN setc-def-to-dest, rule-format]

definition $OV\text{-}inv4$ **where**

$OV\text{-}inv4 = \{s. \forall r p q v w. obs s r p = Some v \wedge obs s r q = Some w \rightarrow w = v\}$

lemmas $OV\text{-}inv4I = OV\text{-}inv4\text{-}def$ [THEN setc-def-to-intro, rule-format]
lemmas $OV\text{-}inv4E$ [elim] = $OV\text{-}inv4\text{-}def$ [THEN setc-def-to-elim, rule-format]
lemmas $OV\text{-}inv4D = OV\text{-}inv4\text{-}def$ [THEN setc-def-to-dest, rule-format]

9.4.1 Proofs of additional invariants

lemma $OV\text{-}inv2\text{-}inductive$:

init $obsv\text{-}TS \subseteq OV\text{-}inv2$
 $\{OV\text{-}inv2\}$ trans $obsv\text{-}TS \{> OV\text{-}inv2\}$
 $\langle proof \rangle$

lemma $SV\text{-}inv3\text{-}inductive$:

init $obsv\text{-}TS \subseteq SV\text{-}inv3$
 $\{SV\text{-}inv3\}$ trans $obsv\text{-}TS \{> SV\text{-}inv3\}$
 $\langle proof \rangle$

lemma $OV\text{-}inv3\text{-}obsv-round$:

$\{OV\text{-}inv3} \cap {OV\text{-}inv2}\}$ $obsv\text{-}round r S v D Ob \{> OV\text{-}inv3\}$
 $\langle proof \rangle$

lemma $OV\text{-}inv3\text{-}inductive$:

init $obsv\text{-}TS \subseteq OV\text{-}inv3$
 $\{OV\text{-}inv3} \cap {OV\text{-}inv2}\}$ trans $obsv\text{-}TS \{> OV\text{-}inv3\}$
 $\langle proof \rangle$

lemma $OV\text{-}inv4\text{-}inductive$:

init $obsv\text{-}TS \subseteq OV\text{-}inv4$
 $\{OV\text{-}inv4\}$ trans $obsv\text{-}TS \{> OV\text{-}inv4\}$
 $\langle proof \rangle$

```
end
```

```
end
```

10 The Optimized Observing Quorums Model

```
theory Observing-Quorums-Opt
imports Observing-Quorums
begin
```

10.1 Model definition

```
record opt-obsv-state =
  next-round :: round
  decisions :: (process, val)map
  last-obs :: (process, val)map
```

```
context mono-quorum
begin
```

```
definition opt-obs-safe where
  opt-obs-safe obs-f v  $\equiv \exists p. \text{obs-}f p \in \{\text{None}, \text{Some } v\}$ 
```

```
definition olv-round where
  olv-round r S v r-decisions Ob  $\equiv \{(s, s') \mid$ 
    — guards
     $r = \text{next-round } s$ 
     $\wedge (S \neq \{\}) \longrightarrow \text{opt-obs-safe} (\text{last-obs } s) v$ 
     $\wedge (S \in \text{Quorum} \longrightarrow Ob = \text{UNIV})$ 
     $\wedge d\text{-guard } r\text{-decisions} (\text{const-map } v S)$ 
     $\wedge (Ob \neq \{\}) \longrightarrow S \neq \{\}$ 
     $\wedge$  — actions
     $s' = s \parallel$ 
     $\text{next-round} := \text{Suc } r$ 
    , decisions := decisions s ++ r-decisions
    , last-obs := last-obs s ++ const-map v Ob
   $\}$ 
}
```

definition *olv-init* **where**

$$\text{olv-init} = \{ () \mid \text{next-round} = 0, \text{decisions} = \text{Map.empty}, \text{last-obs} = \text{Map.empty} \}$$

definition *olv-trans* :: (*opt-obs-state* × *opt-obs-state*) set **where**

$$\text{olv-trans} = (\bigcup r S v D \text{Ob. } \text{olv-round } r S v D \text{Ob}) \cup \text{Id}$$

definition *olv-TS* :: *opt-obs-state TS* **where**

$$\text{olv-TS} = () \mid \text{init} = \text{olv-init}, \text{trans} = \text{olv-trans} \}$$

lemmas *olv-TS-defs* = *olv-TS-def* *olv-init-def* *olv-trans-def*

10.2 Refinement

definition *olv-ref-rel* **where**

$$\begin{aligned} \text{olv-ref-rel} &\equiv \{ (sa, sc) . \\ &\quad \text{next-round } sc = v\text{-state.next-round } sa \\ &\quad \wedge \text{decisions } sc = v\text{-state.decisions } sa \\ &\quad \wedge \text{last-obs } sc = \text{map-option snd o process-mru (obs-state.obs } sa) \} \end{aligned}$$

lemma *OV-inv2-finite-map-graph*:

$$s \in \text{OV-inv2} \implies \text{finite}(\text{map-graph}(\text{case-prod}(\text{obs-state.obs } s)))$$

(proof)

lemma *OV-inv2-finite-obs-set*:

$$s \in \text{OV-inv2} \implies \text{finite}(\text{vote-set}(\text{obs-state.obs } s) Q)$$

(proof)

lemma *olv-round-refines*:

$$\{ \text{olv-ref-rel} \cap (\text{OV-inv2} \cap \text{OV-inv3} \cap \text{OV-inv4}) \times \text{UNIV} \} \text{ obsv-round } r S v D \text{Ob, } \text{olv-round } r S v D \text{Ob} \{ > \text{olv-ref-rel} \}$$

(proof)

lemma *OLV-Refines*:

$$\text{PO-refines}(\text{olv-ref-rel} \cap (\text{OV-inv2} \cap \text{OV-inv3} \cap \text{OV-inv4}) \times \text{UNIV}) \text{ obsv-TS}$$

(proof)

```
end
```

```
end
```

11 Two-Step Observing Quorums Model

```
theory Two-Step-Observing
imports ..../Observing-Quorums-Opt ..../Two-Steps
begin
```

To make the coming proofs of concrete algorithms easier, in this model we split the *olv-round* into two steps.

11.1 Model definition

```
record tso-state = opt-obsrv-state +
  r-votes :: process  $\Rightarrow$  val option
```

```
context mono-quorum
begin
```

```
definition tso-round0
  :: round  $\Rightarrow$  process set  $\Rightarrow$  val  $\Rightarrow$  (tso-state  $\times$  tso-state)set
  where
    tso-round0 r S v  $\equiv$  {(s, s') .
      — guards
      r = next-round s
       $\wedge$  two-step r = 0
       $\wedge$  (S  $\neq$  {}  $\longrightarrow$  opt-obs-safe (last-obs s) v)
      — actions
       $\wedge$  s' = s()
      next-round := Suc r
      , r-votes := const-map v S
    }
}
```

```
definition obs-guard :: (process, val)map  $\Rightarrow$  (process, val)map  $\Rightarrow$  bool where
  obs-guard r-obs r-v  $\equiv$   $\forall p.$ 
```

$$(\forall v. r\text{-}obs\ p = Some\ v \longrightarrow (\exists q. r\text{-}v\ q = Some\ v)) \\ \wedge (dom\ r\text{-}v \in Quorum \longrightarrow (\exists q \in dom\ r\text{-}v. r\text{-}obs\ p = r\text{-}v\ q))$$

definition *tso-round1*

:: *round* \Rightarrow (*process, val*)*map* \Rightarrow (*process, val*)*map* \Rightarrow (*tso-state* \times *tso-state*)*set*
where
tso-round1 r r-decisions r-obs \equiv $\{(s, s')\}$.
— guards
r = next-round s
 \wedge *two-step r = 1*
 \wedge *d-guard r-decisions (r-votes s)*
 \wedge *obs-guard r-obs (r-votes s)*
— actions
 \wedge *s' = s[]*
next-round := Suc r
 $, decisions := decisions\ s\ ++\ r\text{-}decisions$
 $, last-obs := last-obs\ s\ ++\ r\text{-}obs$
 $\}$
 $\}$

definition *tso-init* **where**

tso-init = { () *next-round* = 0, *decisions* = *Map.empty*, *last-obs* = *Map.empty*,
r-votes = *Map.empty* () }

definition *tso-trans* :: (*tso-state* \times *tso-state*) *set* **where**

tso-trans = $(\bigcup r S v. tso-round0\ r S v) \cup (\bigcup r d-f o-f. tso-round1\ r d-f o-f) \cup Id$

definition *tso-TS* :: *tso-state TS* **where**

tso-TS = () *init* = *tso-init*, *trans* = *tso-trans* ()

lemmas *tso-TS-defs* = *tso-TS-def tso-init-def tso-trans-def*

11.2 Refinement

definition *basic-rel* :: (*opt-obsrv-state* \times *tso-state*)*set* **where**

basic-rel = {(*sa, sc*).
next-round sa = two-phase (next-round sc)
 \wedge *last-obs sc = last-obs sa*
 \wedge *decisions sc = decisions sa*
 $\}$

definition $step0\text{-rel} :: (opt\text{-}obsv\text{-}state} \times tso\text{-}state)\text{set}$ **where**
 $step0\text{-rel} = basic\text{-rel}$

definition $step1\text{-add}\text{-rel} :: (opt\text{-}obsv\text{-}state} \times tso\text{-}state)\text{set}$ **where**
 $step1\text{-add}\text{-rel} = \{(sa, sc). \exists S v.$
 $r\text{-votes } sc = const\text{-map } v S$
 $\wedge (S \neq \{\} \longrightarrow opt\text{-obs-safe } (last\text{-obs } sc) v)$
 $\}$

definition $step1\text{-rel} :: (opt\text{-}obsv\text{-}state} \times tso\text{-}state)\text{set}$ **where**
 $step1\text{-rel} = basic\text{-rel} \cap step1\text{-add}\text{-rel}$

definition $tso\text{-ref}\text{-rel} :: (opt\text{-}obsv\text{-}state} \times tso\text{-}state)\text{set}$ **where**
 $tso\text{-ref}\text{-rel} \equiv \{(sa, sc).$
 $(two\text{-step } (next\text{-round } sc) = 0 \longrightarrow (sa, sc) \in step0\text{-rel})$
 $\wedge (two\text{-step } (next\text{-round } sc) = 1 \longrightarrow$
 $(sa, sc) \in step1\text{-rel}$
 $\wedge (\exists sc' r S v. (sc', sc) \in tso\text{-round0 } r S v \wedge (sa, sc') \in step0\text{-rel}))$
 $\}$

lemma *const-map-equality:*
 $(const\text{-map } v S = const\text{-map } v' S') = (S = S' \wedge (S = \{\} \vee v = v'))$
 $\langle proof \rangle$

lemma *rhoare-skipI:*
 $\llbracket \wedge sa sc sc'. \llbracket (sa, sc) \in Pre; (sc, sc') \in Tc \rrbracket \implies (sa, sc') \in Post \rrbracket \implies \{Pre\}$
 $Id, Tc \{>Post\}$
 $\langle proof \rangle$

lemma *tso-round0-refines:*
 $\{tso\text{-ref}\text{-rel}\} Id, tso\text{-round0 } r S v \{>tso\text{-ref}\text{-rel}\}$
 $\langle proof \rangle$

lemma *tso-round1-refines:*
 $\{tso\text{-ref}\text{-rel}\} \bigcup r S v dec\text{-}f Ob. olv\text{-}round r S v dec\text{-}f Ob, tso\text{-round1 } r dec\text{-}f o\text{-}f$
 $\{>tso\text{-ref}\text{-rel}\}$
 $\langle proof \rangle$

lemma *TS-Observing-Refines:*

PO-refines tso-ref-rel olv-TS tso-TS
(proof)

11.3 Invariants

definition TSO-inv1 where

$TSO\text{-}inv1 = \{s. \text{two-step (next-round } s) = \text{Suc } 0 \longrightarrow (\exists v. \forall p w. r\text{-votes } s p = \text{Some } w \longrightarrow w = v)\}$

lemmas TSO-inv1I = TSO-inv1-def [THEN setc-def-to-intro, rule-format]

lemmas TSO-inv1E [elim] = TSO-inv1-def [THEN setc-def-to-elim, rule-format]

lemmas TSO-inv1D = TSO-inv1-def [THEN setc-def-to-dest, rule-format]

definition TSO-inv2 where

$TSO\text{-}inv2 = \{s. \text{two-step (next-round } s) = \text{Suc } 0 \longrightarrow (\forall p v. (r\text{-votes } s p = \text{Some } v \longrightarrow (\exists q. \text{last-obs } s q \in \{\text{None}, \text{Some } v\})))\}$

lemmas TSO-inv2I = TSO-inv2-def [THEN setc-def-to-intro, rule-format]

lemmas TSO-inv2E [elim] = TSO-inv2-def [THEN setc-def-to-elim, rule-format]

lemmas TSO-inv2D = TSO-inv2-def [THEN setc-def-to-dest, rule-format]

11.3.1 Proofs of invariants

lemma TSO-inv1-inductive:

init tso-TS \subseteq TSO-inv1
 $\{TSO\text{-}inv1\} TS.\text{trans tso-TS} \{> TSO\text{-}inv1\}$
(proof)

lemma TSO-inv1-invariant:

reach tso-TS \subseteq TSO-inv1
(proof)

lemma TSO-inv2-inductive:

init tso-TS \subseteq TSO-inv2
 $\{TSO\text{-}inv2\} TS.\text{trans tso-TS} \{> TSO\text{-}inv2\}$
(proof)

lemma TSO-inv2-invariant:

reach tso-TS \subseteq TSO-inv2
(proof)

```
end
```

```
end
```

12 The UniformVoting Algorithm

```
theory Uv-Defs
imports Heard-Of.HOModel .. / Consensus-Types .. / Quorums
begin
```

The contents of this file have been taken almost verbatim from the Heard Of Model AFP entry. The only difference is that the types have been changed.

12.1 Model of the algorithm

```
abbreviation nSteps ≡ 2
```

```
definition phase where phase (r::nat) ≡ r div nSteps
```

```
definition step where step (r::nat) ≡ r mod nSteps
```

The following record models the local state of a process.

```
record 'val pstate =
  last-obs :: 'val           — current value held by process
  agreed-vote :: 'val option   — value the process voted for, if any
  decide :: 'val option     — value the process has decided on, if any
```

Possible messages sent during the execution of the algorithm, and characteristic predicates to distinguish types of messages.

```
datatype 'val msg =
  Val 'val
  | ValVote 'val 'val option
  | Null   — dummy message in case nothing needs to be sent
```

```
definition isValVote where isValVote m ≡ ∃z v. m = ValVote z v
```

```
definition isVal where isVal m ≡ ∃v. m = Val v
```

Selector functions to retrieve components of messages. These functions have a meaningful result only when the message is of appropriate kind.

```
fun getvote where
  getvote (ValVote z v) = v
```

```
fun getval where
  getval (ValVote z v) = z
  | getval (Val z) = z
```

definition *UV-initState where*

$$UV\text{-}initState p st \equiv (agreed\text{-}vote st = None) \wedge (decide st = None)$$

We separately define the transition predicates and the send functions for each step and later combine them to define the overall next-state relation.

definition *msgRcvd where* — processes from which some message was received

$$msgRcvd (msgs:: process \rightarrow 'val msg) = \{q . msgs q \neq None\}$$

definition *smallestValRcvd where*

$$\begin{aligned} smallestValRcvd (msgs::process \rightarrow ('val::linorder) msg) &\equiv \\ Min \{v. \exists q. msgs q = Some (Val v)\} \end{aligned}$$

In step 0, each process sends its current *last-obs* value.

It updates its *last-obs* field to the smallest value it has received. If the process has received the same value *v* from all processes from which it has heard, it updates its *agreed-vote* field to *v*.

```
definition send0 where
  send0 r p q st  $\equiv$  Val (last-obs st)
```

definition *next0 where*

$$\begin{aligned} next0 r p st (msgs::process \rightarrow ('val::linorder) msg) st' &\equiv \\ (\exists v. (\forall q \in msgRcvd msgs. msgs q = Some (Val v)) \wedge st' = st \wedge agreed\text{-}vote := Some v, last\text{-}obs := smallestValRcvd msgs) \\ \vee \neg(\exists v. \forall q \in msgRcvd msgs. msgs q = Some (Val v)) \wedge st' = st \wedge last\text{-}obs := smallestValRcvd msgs \end{aligned}$$

In step 1, each process sends its current *last-obs* and *agreed-vote* values.

```
definition send1 where
  send1 r p q st  $\equiv$  ValVote (last-obs st) (agreed-vote st)
```

definition *valVoteRcvd* **where**

— processes from which values and votes were received

$$\text{valVoteRcvd} (\text{msgs} :: \text{process} \rightarrow \text{'val msg}) \equiv \\ \{q . \exists z v. \text{msgs } q = \text{Some} (\text{ValVote } z v)\}$$

definition *smallestValNoVoteRcvd* **where**

$$\text{smallestValNoVoteRcvd} (\text{msgs} :: \text{process} \rightarrow (\text{'val} :: \text{linorder}) \text{ msg}) \equiv \\ \text{Min} \{v. \exists q. \text{msgs } q = \text{Some} (\text{ValVote } v \text{ None})\}$$

definition *someVoteRcvd* **where**

— set of processes from which some vote was received

$$\text{someVoteRcvd} (\text{msgs} :: \text{process} \rightarrow \text{'val msg}) \equiv \\ \{q . q \in \text{msgRcvd msgs} \wedge \text{isValVote} (\text{the} (\text{msgs } q)) \wedge \text{getvote} (\text{the} (\text{msgs } q)) \neq \text{None}\}$$

definition *identicalVoteRcvd* **where**

$$\text{identicalVoteRcvd} (\text{msgs} :: \text{process} \rightarrow \text{'val msg}) v \equiv \\ \forall q \in \text{msgRcvd msgs}. \text{isValVote} (\text{the} (\text{msgs } q)) \wedge \text{getvote} (\text{the} (\text{msgs } q)) = \text{Some} \\ v$$

definition *x-update* **where**

$$x\text{-update } st \text{ msgs } st' \equiv$$

$$(\exists q \in \text{someVoteRcvd msgs} . \text{last-obs } st' = \text{the} (\text{getvote} (\text{the} (\text{msgs } q)))) \\ \vee \text{someVoteRcvd msgs} = \{\} \wedge \text{last-obs } st' = \text{smallestValNoVoteRcvd msgs}$$

definition *dec-update* **where**

$$\text{dec-update } st \text{ msgs } st' \equiv$$

$$(\exists v. \text{identicalVoteRcvd msgs } v \wedge \text{decide } st' = \text{Some } v)$$

$$\vee \neg(\exists v. \text{identicalVoteRcvd msgs } v) \wedge \text{decide } st' = \text{decide } st$$

definition *next1* **where**

$$\text{next1 } r p st \text{ msgs } st' \equiv$$

$$x\text{-update } st \text{ msgs } st'$$

$$\wedge \text{dec-update } st \text{ msgs } st'$$

$$\wedge \text{agreed-vote } st' = \text{None}$$

The overall send function and next-state relation are simply obtained as the composition of the individual relations defined above.

definition *UV-sendMsg* **where**

$UV\text{-}sendMsg (r::nat) \equiv \text{if } step\ r = 0 \text{ then } send0\ r \text{ else } send1\ r$

definition $UV\text{-}nextState$ **where**

$UV\text{-}nextState\ r \equiv \text{if } step\ r = 0 \text{ then } next0\ r \text{ else } next1\ r$

definition (in quorum-process) $UV\text{-}commPerRd$ **where**

$UV\text{-}commPerRd\ HOrs \equiv \forall p. HOrs\ p \in Quorum$

definition $UV\text{-}commGlobal$ **where**

$UV\text{-}commGlobal\ HOs \equiv \exists r. \forall p\ q. HOs\ r\ p = HOs\ r\ q$

12.2 The *Uniform Voting* Heard-Of machine

We now define the HO machine for *Uniform Voting* by assembling the algorithm definition and its communication predicate. Notice that the coordinator arguments for the initialization and transition functions are unused since *Uniform Voting* is not a coordinated algorithm.

definition (in quorum-process) $UV\text{-}HOMachine$ **where**

$UV\text{-}HOMachine = \emptyset$

$CinitState = (\lambda p\ st\ crd. UV\text{-}initState\ p\ st),$

$sendMsg = UV\text{-}sendMsg,$

$CnextState = (\lambda r\ p\ st\ msgs\ crd\ st'. UV\text{-}nextState\ r\ p\ st\ msgs\ st'),$

$HOcommPerRd = UV\text{-}commPerRd,$

$HOcommGlobal = UV\text{-}commGlobal$

\emptyset

abbreviation (in quorum-process)

$UV\text{-}M \equiv (UV\text{-}HOMachine::(process, 'val::linorder\ pstate, 'val\ msg))\ HOMachine)$

end

12.3 Proofs

type-synonym $uv\text{-}TS\text{-}state} = (nat \times (process \Rightarrow (val\ pstate)))$

axiomatization where $val\text{-}linorder:$

$OFCLASS(val, linorder-class)$

```

instance val :: linorder ⟨proof⟩

lemma two-step-step:
  step = two-step
  phase = two-phase
  ⟨proof⟩

context mono-quorum
begin

definition UV-Alg :: (process, val pstate, val msg)CHOAlgorithm where
  UV-Alg = CHOAlgorithm.truncate UV-M

definition UV-TS :: 
  (round ⇒ process HO) ⇒ (round ⇒ process HO) ⇒ (round ⇒ process) ⇒
  uv-TS-state TS
where
  UV-TS HOs SHOs crds = CHO-to-TS UV-Alg HOs SHOs (K o crds)

lemmas UV-TS-defs = UV-TS-def CHO-to-TS-def UV-Alg-def CHOinitConfig-def
  UV-initState-def

type-synonym rHO = nat ⇒ process HO

definition UV-trans-step
where
  UV-trans-step HOs SHOs nxt-f snd-f stp ≡ ∪ r μ.
  {((r, cfg), (Suc r, cfg')) | cfg cfg'. step r = stp ∧ (∀ p.
    μ p ∈ get-msgs (snd-f r) cfg (HOs r) (SHOs r) p
    ∧ nxt-f r p (cfg p) (μ p) (cfg' p)
  )}

lemma step-less-D:
  0 < step r ==> step r = Suc 0
  ⟨proof⟩

lemma UV-trans:
  CSHO-trans-alt UV-sendMsg (λr p st msgs crd st'. UV-nextState r p st msgs st')
  HOs SHOs crds =
  UV-trans-step HOs SHOs next0 send0 0

```

\cup UV-trans-step HOs SHOs next1 send1 1

$\langle proof \rangle$

12.3.1 Invariants

definition *UV-inv1*

:: uv-TS-state set

where

UV-inv1 = $\{(r, s).$

two-step r = 0 $\longrightarrow (\forall p. agreed\text{-vote}(s p) = None)$

}

lemmas *UV-inv1I* = *UV-inv1-def* [THEN setc-def-to-intro, rule-format]

lemmas *UV-inv1E* [elim] = *UV-inv1-def* [THEN setc-def-to-elim, rule-format]

lemmas *UV-inv1D* = *UV-inv1-def* [THEN setc-def-to-dest, rule-format]

lemma *UV-inv1-inductive*:

init (UV-TS HOs SHOs crds) \subseteq *UV-inv1*

{*UV-inv1*} TS.trans (UV-TS HOs SHOs crds) {> *UV-inv1*}

$\langle proof \rangle$

lemma *UV-inv1-invariant*:

reach (UV-TS HOs SHOs crds) \subseteq *UV-inv1*

$\langle proof \rangle$

12.3.2 Refinement

definition *ref-rel* :: (*tso-state* \times *uv-TS-state*)set **where**

ref-rel $\equiv \{(sa, (r, sc)).$

r = *next-round sa*

$\wedge (step\ r = 1 \longrightarrow r\text{-votes}\ sa = agreed\text{-vote}\ o\ sc)$

$\wedge (\forall p\ v. last\text{-obs}\ (sc\ p) = v \longrightarrow (\exists q. opt\text{-obsrv-state}.last\text{-obs}\ sa\ q \in \{None, Some\ v\}))$

$\wedge decisions\ sa = decide\ o\ sc$

}

Agreement for UV only holds if the communication predicates hold

context

fixes

HOs :: nat \Rightarrow process \Rightarrow process set

```

and rho :: nat  $\Rightarrow$  process  $\Rightarrow$  'val pstate
assumes global: UV-commGlobal HOs
and per-rd:  $\forall r.$  UV-commPerRd (HOs r)
and run: HORun fA rho HOs
begin

lemma HOs-intersect:
HOs r p  $\cap$  HOs r' q  $\neq \{\}$   $\langle proof \rangle$ 

lemma HOs-nonempty:
HOs r p  $\neq \{\}$ 
 $\langle proof \rangle$ 

lemma vote-origin:
assumes
send:  $\forall p.$   $\mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$ 
and step:  $\forall p.$  next0 r p (cfg p) ( $\mu p$ ) (cfg' p)
and inv: (r, cfg)  $\in$  UV-inv1
and step-r: two-step r = 0
shows
agreed-vote (cfg' p) = Some v  $\longleftrightarrow$  ( $\forall q \in HOs r p.$  last-obs (cfg q) = v)
 $\langle proof \rangle$ 

lemma same-new-vote:
assumes
send:  $\forall p.$   $\mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$ 
and step:  $\forall p.$  next0 r p (cfg p) ( $\mu p$ ) (cfg' p)
and inv: (r, cfg)  $\in$  UV-inv1
and step-r: two-step r = 0
obtains v where  $\forall p w.$  agreed-vote (cfg' p) = Some w  $\longrightarrow$  w = v
 $\langle proof \rangle$ 

lemma x-origin1:
assumes
send:  $\forall p.$   $\mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$ 
and step:  $\forall p.$  next0 r p (cfg p) ( $\mu p$ ) (cfg' p)
and step-r: two-step r = 0
and last-obs: last-obs (cfg' p) = v
shows

```

$\exists q. \text{last-obs}(\text{cfg } q) = v$
 $\langle \text{proof} \rangle$

lemma *step0-ref*:
 $\{\text{ref-rel} \cap \text{UNIV} \times \text{UV-inv1}\} \cup r S v. \text{tso-round0 } r S v,$
 $\text{UV-trans-step } \text{HOs HOs next0 send0 0 } \{> \text{ref-rel}\}$
 $\langle \text{proof} \rangle$

lemma *x-origin2*:
assumes
 $\text{send}: \forall p. \mu p \in \text{get-msgs}(\text{send1 } r) \text{ cfg } (\text{HOs } r) (\text{HOs } r) p$
and $\text{step}: \forall p. \text{next1 } r p (\text{cfg } p) (\mu p) (\text{cfg}' p)$
and $\text{step-r: two-step } r = \text{Suc } 0$
and $\text{last-obs: last-obs } (\text{cfg}' p) = v$
shows
 $(\exists q. \text{last-obs } (\text{cfg } q) = v) \vee (\exists q. \text{agreed-vote } (\text{cfg } q) = \text{Some } v)$
 $\langle \text{proof} \rangle$

definition *D* **where**
 $D \text{ cfg cfg}' \equiv \{p. \text{decide } (\text{cfg}' p) \neq \text{decide } (\text{cfg } p)\}$

lemma *decide-origin*:
assumes
 $\text{send}: \forall p. \mu p \in \text{get-msgs}(\text{send1 } r) \text{ cfg } (\text{HOs } r) (\text{HOs } r) p$
and $\text{step}: \forall p. \text{next1 } r p (\text{cfg } p) (\mu p) (\text{cfg}' p)$
and $\text{step-r: two-step } r = \text{Suc } 0$
shows
 $D \text{ cfg cfg}' \subseteq \{p. \exists v. \text{decide } (\text{cfg}' p) = \text{Some } v \wedge (\forall q \in \text{HOs } r p. \text{agreed-vote } (\text{cfg } q) = \text{Some } v)\}$
 $\langle \text{proof} \rangle$

lemma *step1-ref*:
 $\{\text{ref-rel} \cap (\text{TSO-inv1} \cap \text{TSO-inv2}) \times \text{UNIV}\} \cup r d-f o-f. \text{tso-round1 } r d-f o-f,$
 $\text{UV-trans-step } \text{HOs HOs next1 send1 } (\text{Suc } 0) \{> \text{ref-rel}\}$
 $\langle \text{proof} \rangle$

lemma *UV-Refines-votes*:
 $P\text{O-refines } (\text{ref-rel} \cap (\text{TSO-inv1} \cap \text{TSO-inv2}) \times \text{UV-inv1})$
 $\text{tso-TS } (\text{UV-TS } \text{HOs HOs crds})$

$\langle proof \rangle$

end

end

12.3.3 Termination

As the model of the algorithm is taken verbatim from the HO Model AFP, we do not repeat the termination proof here and refer to that AFP entry.

end

13 The Ben-Or Algorithm

```
theory BenOr-Defs
imports Heard-Of.HOModel .. / Consensus-Types .. / Quorums .. / Two-Steps
begin

consts coin :: round ⇒ process ⇒ val

record 'val pstate =
  x :: 'val          — current value held by process
  vote :: 'val option — value the process voted for, if any
  decide :: 'val option — value the process has decided on, if any

datatype 'val msg =
  Val 'val
  | Vote 'val option
  | Null — dummy message in case nothing needs to be sent

definition isVote where isVote m ≡ ∃ v. m = Vote v

definition isVal where isVal m ≡ ∃ v. m = Val v

fun getvote where
  getvote (Vote v) = v

fun getval where
  getval (Val z) = z
```

definition *BenOr-initState* **where**

$$\text{BenOr-initState } p \text{ st} \equiv (\text{vote st} = \text{None}) \wedge (\text{decide st} = \text{None})$$

definition *msgRcvd* **where** — processes from which some message was received
 $\text{msgRcvd } (\text{msgs} :: \text{process} \multimap \text{'val msg}) = \{q . \text{msgs } q \neq \text{None}\}$

definition *send0* **where**

$$\text{send0 } r \text{ p } q \text{ st} \equiv \text{Val } (x \text{ st})$$

definition *next0* **where**

$$\begin{aligned} \text{next0 } r \text{ p } st \text{ (msgs::process} \multimap \text{'val msg) } st' \equiv \\ (\exists v. (\forall q \in \text{msgRcvd msgs}. \text{msgs } q = \text{Some } (\text{Val } v)) \\ \wedge st' = st \mid \text{vote} := \text{Some } v \mid) \\ \vee \neg(\exists v. \forall q \in \text{msgRcvd msgs}. \text{msgs } q = \text{Some } (\text{Val } v)) \\ \wedge st' = st \mid \text{vote} := \text{None} \mid) \end{aligned}$$

definition *send1* **where**

$$\text{send1 } r \text{ p } q \text{ st} \equiv \text{Vote } (\text{vote st})$$

definition *someVoteRcvd* **where**

— set of processes from which some vote was received

$$\begin{aligned} \text{someVoteRcvd } (\text{msgs} :: \text{process} \multimap \text{'val msg}) \equiv \\ \{ q . q \in \text{msgRcvd msgs} \wedge \text{isVote } (\text{the } (\text{msgs } q)) \wedge \text{getvote } (\text{the } (\text{msgs } q)) \neq \\ \text{None} \} \end{aligned}$$

definition *identicalVoteRcvd* **where**

$$\begin{aligned} \text{identicalVoteRcvd } (\text{msgs} :: \text{process} \multimap \text{'val msg}) v \equiv \\ \forall q \in \text{msgRcvd msgs}. \text{isVote } (\text{the } (\text{msgs } q)) \wedge \text{getvote } (\text{the } (\text{msgs } q)) = \text{Some } v \end{aligned}$$

definition *x-update* **where**

$$\begin{aligned} \text{x-update } r \text{ p } msgs \text{ st}' \equiv \\ (\exists q \in \text{someVoteRcvd msgs} . x \text{ st}' = \text{the } (\text{getvote } (\text{the } (\text{msgs } q)))) \\ \vee \text{someVoteRcvd msgs} = \{\} \wedge x \text{ st}' = \text{coin } r \text{ p} \end{aligned}$$

definition *dec-update* **where**

$$\begin{aligned} \text{dec-update } st \text{ msgs } st' \equiv \\ (\exists v. \text{identicalVoteRcvd msgs } v \wedge \text{decide st}' = \text{Some } v) \\ \vee \neg(\exists v. \text{identicalVoteRcvd msgs } v) \wedge \text{decide st}' = \text{decide st} \end{aligned}$$

```

definition next1 where
  next1 r p st msgs st' ≡
    x-update r p msgs st'
    ∧ dec-update st msgs st'
    ∧ vote st' = None

definition BenOr-sendMsg where
  BenOr-sendMsg (r::nat) ≡ if two-step r = 0 then send0 r else send1 r

definition BenOr-nextState where
  BenOr-nextState r ≡ if two-step r = 0 then next0 r else next1 r

```

13.1 The *Ben-Or* Heard-Of machine

```

definition (in quorum-process) BenOr-commPerRd where
  BenOr-commPerRd HOrs ≡ ∀ p. HOrs p ∈ Quorum

```

```

definition BenOr-commGlobal where
  BenOr-commGlobal HOs ≡ ∃ r. two-step r = 1
  ∧ (∀ p q. HOs r p = HOs r q ∧ (coin r p :: val) = coin r q)

```

```

definition (in quorum-process) BenOr-HOMachine where
  BenOr-HOMachine = ⟨
    CinitState = (λp st crd. BenOr-initState p st),
    sendMsg = BenOr-sendMsg,
    CnextState = (λr p st msgs crd st'. BenOr-nextState r p st msgs st'),
    HOcommPerRd = BenOr-commPerRd,
    HOcommGlobal = BenOr-commGlobal
  ⟩

```

```

abbreviation (in quorum-process)
  BenOr-M ≡ (BenOr-HOMachine::(process, val pstate, val msg) HOMachine)

```

end

13.2 Proofs

type-synonym ben-or-TS-state = (nat × (process ⇒ (val pstate)))

consts

val0 :: val
val1 :: val

Ben-Or works only on binary values.

axiomatization where

val-exhaust: v = val0 ∨ v = val1
and *val-diff: val0 ≠ val1*

context *mono-quorum*

begin

definition *BenOr-Alg* :: (*process, val pstate, val msg*) *CHOAlgorithm* **where**
BenOr-Alg = CHOAlgorithm.truncate BenOr-M

definition *BenOr-TS* ::

(round ⇒ process HO) ⇒ (round ⇒ process HO) ⇒ (round ⇒ process) ⇒ ben-or-TS-state TS

where

BenOr-TS HOs SHOs crds = CHO-to-TS BenOr-Alg HOs SHOs (K o crds)

lemmas *BenOr-TS-defs = BenOr-TS-def CHO-to-TS-def BenOr-Alg-def CHOinit-Config-def BenOr-initState-def*

type-synonym *rHO = nat ⇒ process HO*

definition *BenOr-trans-step*

where

BenOr-trans-step HOs SHOs nxt-f snd-f stp ≡ ∪ r μ.
{((r, cfg), (Suc r, cfg'))|cfg cfg'. two-step r = stp ∧ (∀ p.
μ p ∈ get-msgs (snd-f r) cfg (HOs r) (SHOs r) p
∧ nxt-f r p (cfg p) (μ p) (cfg' p)}
)}

lemma *two-step-less-D:*

0 < two-step r ⇒ two-step r = Suc 0
{proof}

lemma *BenOr-trans*:

CSHO-trans-alt BenOr-sendMsg ($\lambda r\ p\ st\ msgs\ crd\ st'. BenOr-nextState\ r\ p\ st\ msgs\ st')$ *HOs SHOs crds* =

BenOr-trans-step HOs SHOs next0 send0 0
 \cup *BenOr-trans-step HOs SHOs next1 send1 1*

$\langle proof \rangle$

definition *BenOr-A* = *CHOAlgorithm.truncate BenOr-M*

13.2.1 Refinement

Agreement for BenOr only holds if the communication predicates hold

context

fixes

HOs :: nat \Rightarrow *process* \Rightarrow *process set*
and *rho :: nat* \Rightarrow *process* \Rightarrow *val pstate*
assumes *comm-global: BenOr-commGlobal HOs*
and *per-rd: $\forall r. BenOr-commPerRd (HOs r)$*
and *run: HORun BenOr-A rho HOs*

begin

definition *no-vote-diff where*

no-vote-diff sc p \equiv *vote (sc p) = None* \longrightarrow
 $(\exists q\ q'. x (sc\ q) \neq x (sc\ q'))$

definition *ref-rel :: (tso-state \times ben-or-TS-state) set where*

ref-rel \equiv $\{(sa, (r, sc))\}$.

r = next-round sa

\wedge *(two-step r = 1 \longrightarrow r-votes sa = vote o sc)*
 \wedge *(two-step r = 1 \longrightarrow ($\forall p. no-vote-diff sc p$))*
 \wedge *($\forall p\ v. x (sc\ p) = v \longrightarrow (\exists q. last-obs\ sa\ q \in \{None, Some\ v\})$)*
 \wedge *decisions sa = decide o sc*
 $\}$

lemma *HOs-intersect*:

HOs r p \cap HOs r' q $\neq \{\}$ $\langle proof \rangle$

lemma *HOs-nonempty*:

$HOs\ r\ p \neq \{\}$
 $\langle proof \rangle$

lemma *vote-origin*:

assumes

send: $\forall p. \mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$

and step: $\forall p. next0 r p (cfg p) (\mu p) (cfg' p)$

and step-r: *two-step r = 0*

shows

$vote (cfg' p) = Some v \longleftrightarrow (\forall q \in HOs r p. x (cfg q) = v)$
 $\langle proof \rangle$

lemma *same-new-vote*:

assumes

send: $\forall p. \mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$

and step: $\forall p. next0 r p (cfg p) (\mu p) (cfg' p)$

and step-r: *two-step r = 0*

obtains v **where** $\forall p w. vote (cfg' p) = Some w \longrightarrow w = v$

$\langle proof \rangle$

lemma *no-x-change*:

assumes

send: $\forall p. \mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$

and step: $\forall p. next0 r p (cfg p) (\mu p) (cfg' p)$

and step-r: *two-step r = 0*

shows

$x (cfg' p) = x (cfg p)$

$\langle proof \rangle$

lemma *no-vote*:

assumes

send: $\forall p. \mu p \in get-msgs (send0 r) cfg (HOs r) (HOs r) p$

and step: $\forall p. next0 r p (cfg p) (\mu p) (cfg' p)$

and step-r: *two-step r = 0*

shows

no-vote-diff $cfg' p$

$\langle proof \rangle$

lemma *step0-ref*:

$\{ref\text{-}rel\} \bigcup r S v. tso\text{-}round0 r S v,$
BenOr-trans-step HOs HOs next0 send0 0 {> ref-rel}
 $\langle proof \rangle$

definition D where

$D cfg cfg' \equiv \{p. decide(cfg' p) \neq decide(cfg p)\}$

lemma decide-origin:

assumes

$send: \forall p. \mu p \in get\text{-}msgs(send1 r) cfg(HOs r) (HOs r) p$

and $step: \forall p. next1 r p (cfg p) (\mu p) (cfg' p)$

and $step\text{-}r: two\text{-}step r = Suc 0$

shows

$D cfg cfg' \subseteq \{p. \exists v. decide(cfg' p) = Some v \wedge (\forall q \in HOs r p. vote(cfg q) = Some v)\}$

$\langle proof \rangle$

lemma step1-ref:

$\{ref\text{-}rel} \cap (TSO\text{-}inv1 \cap TSO\text{-}inv2) \times UNIV\} \bigcup r d\text{-}f o\text{-}f. tso\text{-}round1 r d\text{-}f o\text{-}f,$

BenOr-trans-step HOs HOs next1 send1 (Suc 0) {> ref-rel}

$\langle proof \rangle$

lemma BenOr-Refines-Two-Step-Obs:

$PO\text{-}refines(\{ref\text{-}rel} \cap (TSO\text{-}inv1 \cap TSO\text{-}inv2) \times UNIV)$

$tso\text{-}TS(BenOr\text{-}TS HOs HOs crds)$

$\langle proof \rangle$

13.2.2 Termination

The full termination proof for Ben-Or is probabilistic, and depends on the state of the processes, and a "favorable" coin toss, where "favorable" is relative to this state. As this termination pre-condition is state-dependent, we cannot capture it in an HO predicate.

Instead, we prove a variant of the argument, where we assume that there exists a round where all the processes hear from the same set of other processes, and all toss the same coin.

theorem BenOr-termination:

shows $\exists r v. decide(rho r p) = Some v$

$\langle proof \rangle$

```

end

end

end
```

14 The MRU Vote Model

```

theory MRU-Vote
imports Same-Vote
begin

context quorum-process
begin
```

This model is identical to Same Vote, except that it replaces the *safe* guard with the following one, which says that v is the most recently used (MRU) vote of a quorum:

```

definition mru-guard ::  $v\text{-state} \Rightarrow \text{process set} \Rightarrow \text{val} \Rightarrow \text{bool}$  where
  mru-guard  $s Q v \equiv Q \in \text{Quorum} \wedge (\text{let } mru = \text{mru-of-set}(\text{votes } s) \text{ } Q \text{ in}$ 
     $mru = \text{None} \vee (\exists r. mru = \text{Some}(r, v))$ 
```

The concrete algorithms will not refine the MRU Voting model directly, but its optimized version instead. For simplicity, we thus do not create the model explicitly, but just prove guard strengthening. We will show later that the optimized model refines the Same Vote model.

```

lemma mru-vote-implies-safe:
  assumes
    inv4:  $s \in \text{SV-inv4}$ 
    and inv1:  $s \in V\text{inv1}$ 
    and mru-vote: mru-guard  $s Q v$ 
    and is-Quorum:  $Q \in \text{Quorum}$ 
    shows safe  $s (v\text{-state}.next-round } s) v \langle proof \rangle$ 

end

end
```

15 Optimized MRU Vote Model

```
theory MRU-Vote-Opt
imports MRU-Vote
begin

 15.1 Model definition

record opt-mru-state =
  next-round :: round
  mru-vote :: (process, round × val) map
  decisions :: (process, val) map

definition opt-mru-init where
  opt-mru-init = { () next-round = 0, mru-vote = Map.empty, decisions = Map.empty
  () }

context quorum-process begin

definition opt-mru-vote :: (process, round × val) map ⇒ (process set, round × val) map where
  opt-mru-vote lvs Q = option-Max-by fst (ran (lvs |` Q))

definition opt-mru-guard :: (process, round × val) map ⇒ process set ⇒ val ⇒ bool where
  opt-mru-guard mru-votes Q v ≡ Q ∈ Quorum ∧
  (let mru = opt-mru-vote mru-votes Q in mru = None ∨ (exists r. mru = Some (r, v)))

definition opt-mru-round
  :: round ⇒ process set ⇒ process set ⇒ val ⇒ (process, val) map ⇒ (opt-mru-state × opt-mru-state) set
  where
    opt-mru-round r Q S v r-decisions = {(s, s') .
      — guards
      r = next-round s
      ∧ (S ≠ {}) → opt-mru-guard (mru-vote s) Q v
      ∧ d-guard r-decisions (const-map v S)
      ∧ — actions
      s' = s ()}
```

```

mru-vote := mru-vote s ++ const-map (r, v) S
, next-round := Suc r
, decisions := decisions s ++ r-decisions
|
}

```

lemmas *lv-evt-defs* = *opt-mru-round-def* *opt-mru-guard-def*

definition *mru-opt-trans* :: (*opt-mru-state* × *opt-mru-state*) set **where**
 $mru-opt-trans = (\bigcup r Q S v D. opt-mru-round r Q S v D) \cup Id$

definition *mru-opt-TS* :: *opt-mru-state* *TS* **where**
 $mru-opt-TS = () init = opt-mru-init, trans = mru-opt-trans ()$

lemmas *mru-opt-TS-defs* = *mru-opt-TS-def* *opt-mru-init-def* *mru-opt-trans-def*

15.2 Refinement

definition *lv-ref-rel* :: (*v-state* × *opt-mru-state*) set **where**
 $lv-ref-rel = \{(sa, sc).$
 $sc = ()$
 $next-round = v-state.next-round sa$
 $, mru-vote = process-mru (votes sa)$
 $, decisions = v-state.decisions sa$
 $\}$
 $\}$

15.2.1 The concrete guard implies the abstract guard

definition *voters* :: (*round* ⇒ (*process*, *val*) map) ⇒ *process* set **where**
 $voters vs = \{a | a \in r. ((r, a), v) \in map-graph (case-prod vs)\}$

lemma *vote-set-as-Union*:

$vote-set vs Q = (\bigcup a \in (Q \cap voters vs). vote-set vs \{a\})$
 $\langle proof \rangle$

lemma *empty-ran*:

$(ran f = \{\}) = (\forall x. f x = None)$
 $\langle proof \rangle$

lemma *empty-ran-restrict*:

$$(\text{ran } (f \mid' A) = \{\}) = (\forall x \in A. f x = \text{None})$$

$\langle \text{proof} \rangle$

lemma *option-Max-by-eqI*:

$$\begin{aligned} & [\![(S = \{\}) \longleftrightarrow (S' = \{\}); S \neq \{ \} \wedge S' \neq \{ \} \implies \text{Max-by } f S = \text{Max-by } g S']\!] \\ & \implies \text{option-Max-by } f S = \text{option-Max-by } g S' \end{aligned}$$

$\langle \text{proof} \rangle$

lemma *ran-process-mru-only-voters*:

$$\text{ran } (\text{process-mru } vs \mid' Q) = \text{ran } (\text{process-mru } vs \mid' (Q \cap \text{voters } vs))$$

$\langle \text{proof} \rangle$

lemma *SV-inv3-inj-on-fst-vote-set*:

$$s \in \text{SV-inv3} \implies \text{inj-on } \text{fst } (\text{vote-set } (\text{votes } s) Q)$$

$\langle \text{proof} \rangle$

lemma *opt-mru-vote-mru-of-set*:

assumes

- inv1: $s \in V_{\text{inv1}}$*
- and** *inv3: $s \in \text{SV-inv3}$*

defines *vs $\equiv \text{votes } s$*

shows

$$\text{opt-mru-vote } (\text{process-mru } vs) Q = \text{mru-of-set } vs Q$$

$\langle \text{proof} \rangle$

lemma *opt-mru-guard-imp-mru-guard*:

assumes *invs:*

- s $\in V_{\text{inv1}}$ s $\in \text{SV-inv3}$*
- and** *c-guard: opt-mru-guard $(\text{process-mru } (\text{votes } s)) Q v$*

shows *mru-guard s Q v* $\langle \text{proof} \rangle$

15.2.2 The concrete action refines the abstract action

lemma *act-ref*:

assumes

- s $\in V_{\text{inv1}}$*

shows

$$\begin{aligned} & \text{process-mru } (\text{votes } s) ++ \text{const-map } (v\text{-state.next-round } s, v) S \\ & = \text{process-mru } ((\text{votes } s)(v\text{-state.next-round } s := \text{const-map } v S)) \end{aligned}$$

$\langle proof \rangle$

15.2.3 The complete refinement

lemma *opt-mru-guard-imp-Quorum*:

opt-mru-guard vs Q v $\implies Q \in Quorum$
 $\langle proof \rangle$

lemma *opt-mru-round-refines*:

$\{lv\text{-ref-rel} \cap (Vinv1 \cap SV\text{-inv3} \cap SV\text{-inv4}) \times UNIV\}$
 $sv\text{-round } r S v d\text{-f}, opt\text{-mru-round } r Q S v d\text{-f}$
 $\{> lv\text{-ref-rel}\}$
 $\langle proof \rangle$

lemma *Opt-MRU-Vote-Refines*:

PO-refines $(lv\text{-ref-rel} \cap (Vinv1 \cap Vinv2 \cap SV\text{-inv3} \cap SV\text{-inv4}) \times UNIV)$ *sv-TS*
mru-opt-TS
 $\langle proof \rangle$

15.3 Invariants

definition *OMRU-inv1* :: *opt-mru-state set* **where**

OMRU-inv1 = {*s*. $\forall p.$ (*case mru-vote s p of*
 $Some (r, -) \Rightarrow r < next\text{-round } s$
 $| None \Rightarrow True$)
 $\}$

lemma *OMRU-inv1-inductive*:

init mru-opt-TS $\subseteq OMRU\text{-inv1}$
 $\{OMRU\text{-inv1}\}$ *trans mru-opt-TS* $\{> OMRU\text{-inv1}\}$
 $\langle proof \rangle$

lemmas *OMRU-inv1I* = *OMRU-inv1-def* [THEN *setc-def-to-intro, rule-format*]

lemmas *OMRU-inv1E* [elim] = *OMRU-inv1-def* [THEN *setc-def-to-elim, rule-format*]

lemmas *OMRU-inv1D* = *OMRU-inv1-def* [THEN *setc-def-to-dest, rule-format*]

end

end

16 Three-step Optimized MRU Model

```
theory Three-Step-MRU
imports ..../MRU-Vote-Opt Three-Steps
begin
```

To make the coming proofs of concrete algorithms easier, in this model we split the *opt-mru-round* into three steps

16.1 Model definition

```
record three-step-mru-state = opt-mru-state +
  candidates :: val set
```

```
context mono-quorum
begin
```

```
definition opt-mru-step0 :: round  $\Rightarrow$  val set  $\Rightarrow$  (three-step-mru-state  $\times$  three-step-mru-state)
set where
```

```
opt-mru-step0 r C = {(s, s')}.
  — guards
  r = next-round s  $\wedge$  three-step r = 0
   $\wedge$  ( $\forall$  cand  $\in$  C.  $\exists$  Q. opt-mru-guard (mru-vote s) Q cand)
   $\wedge$  — actions
  s' = s()
  candidates := C
  , next-round := Suc r
}
}
```

```
definition opt-mru-step1 :: round  $\Rightarrow$  process set  $\Rightarrow$  val  $\Rightarrow$ 
(three-step-mru-state  $\times$  three-step-mru-state) set where
opt-mru-step1 r S v = {(s, s')}.
  — guards
```

```
r = next-round s  $\wedge$  three-step r = 1
 $\wedge$  (S  $\neq$  {}  $\longrightarrow$  v  $\in$  candidates s)
 $\wedge$  — actions
s' = s()
mru-vote := mru-vote s ++ const-map (three-phase r, v) S
, next-round := Suc r
```

}

definition *step2-d-guard* :: $(process, val)map \Rightarrow (process, val)map \Rightarrow bool$ **where**
 $step2-d-guard r\text{-decisions } r\text{-votes} \equiv \forall p v. r\text{-decisions } p = Some v \rightarrow v \in ran r\text{-votes} \wedge dom r\text{-votes} \in Quorum$

definition *r-votes* :: $three\text{-step}\text{-mru}\text{-state} \Rightarrow round \Rightarrow (process, val)map$ **where**
 $r\text{-votes } s r \equiv \lambda p. if (\exists v. mru\text{-vote } s p = Some (three\text{-phase } r, v))$
 $then map\text{-option } snd (mru\text{-vote } s p)$
 $else None$

definition *opt-mru-step2* :: $round \Rightarrow (process, val)map \Rightarrow (three\text{-step}\text{-mru}\text{-state} \times three\text{-step}\text{-mru}\text{-state}) set$ **where**
 $opt\text{-mru}\text{-step2 } r r\text{-decisions} = \{(s, s')\}$.
— guards
 $r = next\text{-round } s \wedge three\text{-step } r = 2$
 $\wedge step2\text{-d-guard } r\text{-decisions } (r\text{-votes } s r)$
 \wedge — actions
 $s' = s \emptyset$
 $next\text{-round} := Suc r$
 $, decisions := decisions s ++ r\text{-decisions}$
 \emptyset
{}

lemmas *ts-mru-evt-defs* = *opt-mru-step0-def* *opt-mru-step1-def* *opt-mru-guard-def*

definition *ts-mru-trans* :: $(three\text{-step}\text{-mru}\text{-state} \times three\text{-step}\text{-mru}\text{-state}) set$ **where**
 $ts\text{-mru}\text{-trans} = (\bigcup r C. opt\text{-mru}\text{-step0 } r C)$
 $\cup (\bigcup r S v. opt\text{-mru}\text{-step1 } r S v)$
 $\cup (\bigcup r dec-f. opt\text{-mru}\text{-step2 } r dec-f) \cup Id$

definition *ts-mru-init* **where**
 $ts\text{-mru}\text{-init} = \{ \emptyset | next\text{-round} = 0, mru\text{-vote} = Map.empty, decisions = Map.empty, candidates = \{\} \}$

definition *ts-mru-TS* :: $three\text{-step}\text{-mru}\text{-state} TS$ **where**
 $ts\text{-mru}\text{-TS} = \emptyset | init = ts\text{-mru}\text{-init}, trans = ts\text{-mru}\text{-trans} \emptyset$

lemmas *ts-mru-TS-defs* = *ts-mru-TS-def* *ts-mru-init-def* *ts-mru-trans-def*

16.2 Refinement

```

definition basic-rel where
  basic-rel ≡ {(sa, sc)}.
  decisions sc = decisions sa
  ∧ next-round sa = three-phase (next-round sc)
}

definition three-step0-rel :: (opt-mru-state × three-step-mru-state)set where
  three-step0-rel ≡ basic-rel ∩ {(sa, sc)}.
  three-step (next-round sc) = 0
  ∧ mru-vote sc = mru-vote sa
}

definition three-step1-rel :: (opt-mru-state × three-step-mru-state)set where
  three-step1-rel ≡ basic-rel ∩ {(sa, sc)}.
  (exists sc' r C. (sa, sc') ∈ three-step0-rel ∧ (sc', sc) ∈ opt-mru-step0 r C)
  ∧ mru-vote sc = mru-vote sa
}

definition three-step2-rel :: (opt-mru-state × three-step-mru-state)set where
  three-step2-rel ≡ basic-rel ∩ {(sa, sc)}.
  (exists sc' r S v. (sa, sc') ∈ three-step1-rel ∧ (sc', sc) ∈ opt-mru-step1 r S v)
}

definition ts-ref-rel where
  ts-ref-rel = {(sa, sc)}.
  (three-step (next-round sc) = 0 → (sa, sc) ∈ three-step0-rel)
  ∧ (three-step (next-round sc) = 1 → (sa, sc) ∈ three-step1-rel)
  ∧ (three-step (next-round sc) = 2 → (sa, sc) ∈ three-step2-rel)
}

lemmas ts-ref-rel-defs =
  basic-rel-def
  ts-ref-rel-def
  three-step0-rel-def
  three-step1-rel-def
  three-step2-rel-def

```

```

lemma step0-ref:
  {ts-ref-rel} Id, opt-mru-step0 r C {> ts-ref-rel}
  ⟨proof⟩

lemma step1-ref:
  {ts-ref-rel} Id, opt-mru-step1 r S v {> ts-ref-rel}
  ⟨proof⟩

lemma step2-ref:
  {ts-ref-rel ∩ OMRU-inv1 × UNIV}
  ∪ r' Q S' v dec-f'. opt-mru-round r' Q S' v dec-f',
  opt-mru-step2 r dec-f {> ts-ref-rel}
  ⟨proof⟩

lemma ThreeStep-Coordinated-Refines:
  PO-refines (ts-ref-rel ∩ OMRU-inv1 × UNIV)
  mru-opt-TS ts-mru-TS
  ⟨proof⟩

end

end

```

17 The New Algorithm

```

theory New-Algorithm-Defs
imports Heard-Of.HOModel .. / Consensus-Types .. / Consensus-Misc Three-Steps
begin

```

17.1 Model of the algorithm

We assume that the values are linearly ordered, to be able to have each process select the smallest value.

```

axiomatization where val-linorder:
  OFCLASS(val, linorder-class)

```

```

instance val :: linorder ⟨proof⟩

```

```

record pstate =

```

$x :: val$ — current value held by process
 $prop\text{-}vote :: val\ option$
 $mru\text{-}vote :: (nat \times val)\ option$
 $decide :: val\ option$ — value the process has decided on, if any

```

datatype msg =
  MruVote (nat × val) option val
| PreVote val
| Vote val
| Null — dummy message in case nothing needs to be sent
  
```

Characteristic predicates on messages.

```
definition isLV where isLV m ≡ ∃ rv. m = Vote rv
```

```
definition isPreVote where isPreVote m ≡ ∃ px. m = PreVote px
```

```

definition NA-initState where
  NA-initState p st - ≡
    mru-vote st = None
    ∧ prop-vote st = None
    ∧ decide st = None
  
```

```

definition send0 where
  send0 r p q st ≡ MruVote (mru-vote st) (x st)
  
```

```

fun msg-to-val-stamp :: msg ⇒ (round × val)option where
  msg-to-val-stamp (MruVote rv -) = rv
  
```

```

definition msgs-to-lvs :: 
  (process → msg)
  ⇒ (process, round × val) map
where
  msgs-to-lvs msgs ≡ msg-to-val-stamp ∘m msgs
  
```

```

definition smallest-proposal where
  smallest-proposal (msgs::process → msg) ≡
  Min {v. ∃ q mv. msgs q = Some (MruVote mv v)}
  
```

```
definition next0
```

```

 $\begin{array}{l}
 :: \text{nat} \\
 \Rightarrow \text{process} \\
 \Rightarrow \text{pstate} \\
 \Rightarrow (\text{process} \multimap \text{msg}) \\
 \Rightarrow \text{process} \\
 \Rightarrow \text{pstate} \\
 \Rightarrow \text{bool}
\end{array}$ 
where

$$\begin{aligned}
 \text{next0 } r \ p \ st \ msgs \ crd \ st' &\equiv \text{let} \\
 Q &= \text{dom } msgs; \\
 lvs &= \text{msgs-to-lvs } msgs; \\
 \text{smallest} &= \text{if } Q = \{\} \text{ then } x \ st \text{ else smallest-proposal } msgs \\
 \text{in} \\
 st' &= st \ \emptyset \\
 \text{prop-vote} &:= \text{if } \text{card } Q > N \text{ div } 2 \\
 &\quad \text{then Some (case-option smallest snd (option-Max-by fst (ran (lvs |` Q))))} \\
 &\quad \text{else None} \\
 \end{aligned}$$

 $\}$ 
definition  $\text{send1}$  where

$$\begin{aligned}
 \text{send1 } r \ p \ q \ st &\equiv \text{case prop-vote } st \text{ of} \\
 \text{None} &\Rightarrow \text{Null} \\
 |\text{ Some } v &\Rightarrow \text{PreVote } v
\end{aligned}$$

definition  $\text{Q-prevotes-}v$  where

$$\begin{aligned}
 \text{Q-prevotes-}v \ msgs \ Q \ v &\equiv \text{let } D = \text{dom } msgs \text{ in} \\
 Q \subseteq D \wedge \text{card } Q > N \text{ div } 2 \wedge (\forall q \in Q. \ msgs \ q = \text{Some (PreVote } v))
\end{aligned}$$

definition  $\text{next1}$ 
 $\begin{array}{l}
 :: \text{nat} \\
 \Rightarrow \text{process} \\
 \Rightarrow \text{pstate} \\
 \Rightarrow (\text{process} \multimap \text{msg}) \\
 \Rightarrow \text{process} \\
 \Rightarrow \text{pstate} \\
 \Rightarrow \text{bool}
\end{array}$ 
where

$$\begin{aligned}
 \text{next1 } r \ p \ st \ msgs \ crd \ st' &\equiv \\
 \text{decide } st' &= \text{decide } st \\
 \wedge x \ st' &= x \ st
\end{aligned}$$


```

$$\begin{aligned}
& \wedge (\forall Q v. Q\text{-prevotes-}v \text{ msgs } Q v \\
& \quad \longrightarrow \text{mru-vote } st' = \text{Some (three-phase } r, v)) \\
& \wedge (\neg (\exists Q v. Q\text{-prevotes-}v \text{ msgs } Q v) \\
& \quad \longrightarrow \text{mru-vote } st' = \text{mru-vote } st)
\end{aligned}$$

definition *send2* **where**

$$\begin{aligned}
\text{send2 } r p q st & \equiv \text{case mru-vote } st \text{ of} \\
& \text{None} \Rightarrow \text{Null} \\
& |\text{ Some } (\Phi, v) \Rightarrow \text{if } \Phi = \text{three-phase } r \text{ then } \text{Vote } v \text{ else Null}
\end{aligned}$$

definition *Q'-votes-v* **where**

$$\begin{aligned}
\text{Q'-votes-v } r \text{ msgs } Q Q' v & \equiv \\
Q' \subseteq Q \wedge \text{card } Q' > N \text{ div } 2 \wedge (\forall q \in Q'. \text{msgs } q = \text{Some (Vote } v))
\end{aligned}$$

definition *next2*

$$\begin{aligned}
& :: \text{nat} \\
& \Rightarrow \text{process} \\
& \Rightarrow \text{pstate} \\
& \Rightarrow (\text{process} \rightarrow \text{msg}) \\
& \Rightarrow \text{process} \\
& \Rightarrow \text{pstate} \\
& \Rightarrow \text{bool}
\end{aligned}$$

where

$$\begin{aligned}
\text{next2 } r p st \text{ msgs crd } st' & \equiv \text{let } Q = \text{dom msgs}; lvs = \text{msgs-to-lvs msgs} \text{ in} \\
x st' & = x st \\
& \wedge \text{mru-vote } st' = \text{mru-vote } st \\
& \wedge (\forall Q' v. Q'\text{-votes-}v \text{ r msgs } Q Q' v \longrightarrow \text{decide } st' = \text{Some } v) \\
& \wedge (\neg (\exists Q' v. Q'\text{-votes-}v \text{ r msgs } Q Q' v \longrightarrow \text{decide } st' = \text{decide } st))
\end{aligned}$$

definition *NA-sendMsg* :: nat \Rightarrow process \Rightarrow process \Rightarrow pstate \Rightarrow msg **where**

$$\begin{aligned}
\text{NA-sendMsg } (r::\text{nat}) & \equiv \\
& \text{if three-step } r = 0 \text{ then send0 } r \\
& \text{else if three-step } r = 1 \text{ then send1 } r \\
& \text{else send2 } r
\end{aligned}$$

definition

$$\begin{aligned}
\text{NA-nextState } :: \text{nat} & \Rightarrow \text{process} \Rightarrow \text{pstate} \Rightarrow (\text{process} \rightarrow \text{msg}) \\
& \Rightarrow \text{process} \Rightarrow \text{pstate} \Rightarrow \text{bool}
\end{aligned}$$

where
 $NA\text{-}nextState\ r \equiv$
 $\quad if\ three\text{-}step\ r = 0\ then\ next0\ r$
 $\quad else\ if\ three\text{-}step\ r = 1\ then\ next1\ r$
 $\quad else\ next2\ r$

17.2 The Heard-Of machine

definition

$NA\text{-}commPerRd$ **where**
 $NA\text{-}commPerRd\ (HOs\text{:}:process\ HO) \equiv True$

definition

$NA\text{-}commGlobal$ **where**
 $NA\text{-}commGlobal\ HOs \equiv$
 $\exists ph\text{:}nat.\ \forall i \in \{0..2\}.$
 $(\forall p.\ card\ (HOs\ (nr\text{-}steps}*ph+i)\ p) > N\ div\ 2)$
 $\wedge (\forall p\ q.\ HOs\ (nr\text{-}steps}*ph+i)\ p = HOs\ (nr\text{-}steps}*ph)\ q)$

definition *New-Algo-Alg* **where**

$New\text{-}Algo\text{-}Alg \equiv$
 $\langle CinitState = NA\text{-}initState,$
 $sendMsg = NA\text{-}sendMsg,$
 $C nextState = NA\text{-}nextState \rangle$

definition *New-Algo-HOMachine* **where**

$New\text{-}Algo\text{-}HOMachine \equiv$
 $\langle CinitState = NA\text{-}initState,$
 $sendMsg = NA\text{-}sendMsg,$
 $C nextState = NA\text{-}nextState,$
 $HOcommPerRd = NA\text{-}commPerRd,$
 $HOcommGlobal = NA\text{-}commGlobal \rangle$

abbreviation

$New\text{-}Algo\text{-}M \equiv (New\text{-}Algo\text{-}HOMachine\text{:}(process,\ pstate,\ msg)\ HOMachine)$

end

17.3 Proofs

type-synonym $p\text{-}TS\text{-state} = (\text{nat} \times (\text{process} \Rightarrow p\text{state}))$

definition $New\text{-Algo}\text{-}TS ::$

$(\text{round} \Rightarrow \text{process HO}) \Rightarrow (\text{round} \Rightarrow \text{process HO}) \Rightarrow (\text{round} \Rightarrow \text{process}) \Rightarrow p\text{-}TS\text{-state TS}$

where

$New\text{-Algo}\text{-}TS \text{ HOs SHOs crds} = \text{CHO-to-TS New-Algo-Alg HOs SHOs (K o crds)}$

lemmas $New\text{-Algo}\text{-}TS\text{-defs} = New\text{-Algo}\text{-}TS\text{-def CHO-to-TS-def New-Algo-Alg-def CHOinitConfig-def NA-initState-def}$

definition $New\text{-Algo-trans-step where}$

$New\text{-Algo-trans-step HOs SHOs crds nxt-f snd-f stp} \equiv \bigcup r \mu.$
 $\{(r, cfg), (Suc r, cfg') | cfg \neq cfg'. \text{three-step } r = stp \wedge (\forall p. \mu p \in \text{get-msgs (snd-f r) cfg (HOs r) (SHOs r) p} \wedge \text{nxt-f r p} (cfg p) (\mu p) (\text{crds r}) (cfg' p))\}$

lemma $\text{three-step-less-D}:$

$0 < \text{three-step } r \implies \text{three-step } r = 1 \vee \text{three-step } r = 2$
 $\langle proof \rangle$

lemma $New\text{-Algo-trans}:$

$CSHO\text{-trans-alt NA-sendMsg NA-nextState HOs SHOs (K o crds)} =$
 $\text{New-Algo-trans-step HOs SHOs crds next0 send0 0} \cup$
 $\text{New-Algo-trans-step HOs SHOs crds next1 send1 1} \cup$
 $\text{New-Algo-trans-step HOs SHOs crds next2 send2 2}$

$\langle proof \rangle$

type-synonym $rHO = \text{nat} \Rightarrow \text{process HO}$

17.3.1 Refinement

definition $new\text{-algo-ref-rel} :: (\text{three-step-mru-state} \times p\text{-}TS\text{-state})\text{set where}$

$new\text{-algo-ref-rel} = \{(sa, (r, sc)).$
 $opt\text{-mru-state.next-round } sa = r$

```

 $\wedge \text{opt-mru-state}.decisions sa = pstate.decide o sc$ 
 $\wedge \text{opt-mru-state}.mru-vote sa = pstate.mru-vote o sc$ 
 $\wedge (\text{three-step } r = \text{Suc } 0 \longrightarrow \text{three-step-mru-state}.candidates sa = \text{ran}(\text{prop-vote } o sc))$ 
}

```

Different types seem to be derived for the two *mru-vote-evolution* lemmas, so we state them separately.

lemma *mru-vote-evolution0*:

```

 $\forall p. \text{next0 } r p (s p) (\text{msgs } p) (\text{crd } p) (s' p) \implies \text{mru-vote } o s' = \text{mru-vote } o s$ 
⟨proof⟩

```

lemma *mru-vote-evolution2*:

```

 $\forall p. \text{next2 } r p (s p) (\text{msgs } p) (\text{crd } p) (s' p) \implies \text{mru-vote } o s' = \text{mru-vote } o s$ 
⟨proof⟩

```

lemma *decide-evolution*:

```

 $\forall p. \text{next0 } r p (s p) (\text{msgs } p) (\text{crd } p) (s' p) \implies \text{decide } o s = \text{decide } o s'$ 
 $\forall p. \text{next1 } r p (s p) (\text{msgs } p) (\text{crd } p) (s' p) \implies \text{decide } o s = \text{decide } o s'$ 
⟨proof⟩

```

lemma *msgs-mru-vote*:

assumes

```

 $\mu p \in \text{get-msgs}(\text{send0 } r) \text{ cfg } (\text{HOs } r) (\text{HOs } r) p$ 
shows (( $\text{msgs-to-lvs}(\mu p)$ ) |‘  $\text{HOs } r p$ ) = ( $\text{mru-vote } o \text{ cfg}$ ) |‘  $\text{HOs } r p$  ⟨proof⟩

```

lemma *step0-ref*:

```

{new-algo-ref-rel}
( $\bigcup r C. \text{majorities}.opt-mru-step0 r C$ ),
New-Algo-trans-step  $\text{HOs } HOs \text{ crds next0 send0 } 0 \{> \text{new-algo-ref-rel}\}$ 
⟨proof⟩

```

lemma *step1-ref*:

```

{new-algo-ref-rel}
( $\bigcup r S v. \text{majorities}.opt-mru-step1 r S v$ ),
New-Algo-trans-step  $\text{HOs } HOs \text{ crds next1 send1 } (\text{Suc } 0) \{> \text{new-algo-ref-rel}\}$ 
⟨proof⟩

```

lemma *step2-ref*:

```

{new-algo-ref-rel}

```

```

( $\bigcup r \text{ dec-f. majorities.opt-mru-step2 } r \text{ dec-f}),$ 
  New-Algo-trans-step HOs HOs crds next2 send2 2 {> new-algo-ref-rel}
⟨proof⟩

```

lemma *New-Algo-Refines-votes:*

```

PO-refines new-algo-ref-rel
  majorities.ts-mru-TS (New-Algo-TS HOs HOs crds)
⟨proof⟩

```

17.3.2 Termination

theorem *New-Algo-termination:*

```

assumes run: HORun New-Algo-Alg rho HOs
  and commR:  $\forall r. HOcommPerRd$  New-Algo-M (HOs r)
  and commG: HOcommGlobal New-Algo-M HOs
shows  $\exists r v. decide (\rho r p) = Some v$ 
⟨proof⟩

```

end

18 The Paxos Algorithm

```

theory Paxos-Defs
imports Heard-Of.HOModel .. / Consensus-Types .. / Consensus-Misc Three-Steps
begin

```

This is a modified version (closer to the original Paxos) of PaxosDefs from the Heard Of entry in the AFP.

18.1 Model of the algorithm

The following record models the local state of a process.

```

record 'val pstate =
  x :: 'val           — current value held by process
  mru-vote :: (nat × 'val) option
  commt :: 'val option — for coordinators: the value processes are asked to commit
                        to
  decide :: 'val option — value the process has decided on, if any

```

The algorithm relies on a coordinator for each phase of the algorithm. A phase lasts three rounds. The HO model formalization already provides the infrastructure for this, but unfortunately the coordinator is not passed to the *sendMsg* function. Using the infrastructure would thus require additional invariants and proofs; for simplicity, we use a global constant instead.

```
consts coord :: nat  $\Rightarrow$  process
specification (coord)
  coord-phase[rule-format]:  $\forall r r'. \text{three-phase } r = \text{three-phase } r' \longrightarrow \text{coord } r = \text{coord } r'$ 
  ⟨proof⟩
```

Possible messages sent during the execution of the algorithm.

```
datatype 'val msg =
  ValStamp 'val nat
| NeverVoted
| Vote 'val
| Null — dummy message in case nothing needs to be sent
```

Characteristic predicates on messages.

```
definition isValStamp where isValStamp m  $\equiv \exists v ts. m = \text{ValStamp } v ts$ 
```

```
definition isVote where isVote m  $\equiv \exists v. m = \text{Vote } v$ 
```

Selector functions to retrieve components of messages. These functions have a meaningful result only when the message is of an appropriate kind.

```
fun val where
  val (ValStamp v ts) = v
| val (Vote v) = v
```

The *x* field of the initial state is unconstrained, all other fields are initialized appropriately.

```
definition Paxos-initState where
  Paxos-initState p st crd  $\equiv$ 
    mru-vote st = None
   $\wedge$  commt st = None
   $\wedge$  decide st = None
```

```
definition mru-vote-to-msg :: 'val pstate  $\Rightarrow$  'val msg where
```

```

mru-vote-to-msg st ≡ case mru-vote st of
  Some (ts, v) ⇒ ValStamp v ts
  | None ⇒ NeverVoted

fun msg-to-val-stamp :: 'val msg ⇒ (round × 'val)option where
  msg-to-val-stamp (ValStamp v ts) = Some (ts, v)
  | msg-to-val-stamp - = None

definition msgs-to-lvs :: 
  (process → 'val msg)
  ⇒ (process, round × 'val) map
where
  msgs-to-lvs msgs ≡ msg-to-val-stamp ∘m msgs

definition send0 where
  send0 r p q st ≡
  if q = coord r then mru-vote-to-msg st else Null

definition next0
  :: nat
  ⇒ process
  ⇒ 'val pstate
  ⇒ (process → 'val msg)
  ⇒ process
  ⇒ 'val pstate
  ⇒ bool
where
  next0 r p st msgs crd st' ≡ let Q = dom msgs; lvs = msgs-to-lvs msgs in
    if p = coord r ∧ card Q > N div 2
    then (st' = st ∥ commt := Some (case-option (x st) snd (option-Max-by fst
      (ran (lvs ∣‘ Q))))) ∥ )
    else st' = st ∥ commt := None ∥

definition send1 where
  send1 r p q st ≡
  if p = coord r ∧ commt st ≠ None then Vote (the (commt st)) else Null

definition next1
  :: nat
  ⇒ process

```

```

 $\Rightarrow 'val pstate$ 
 $\Rightarrow (process \rightarrow 'val msg)$ 
 $\Rightarrow process$ 
 $\Rightarrow 'val pstate$ 
 $\Rightarrow bool$ 

```

where

```

 $next1 r p st msgs crd st' \equiv$ 
 $if msgs (coord r) \neq None \wedge isVote (the (msgs (coord r)))$ 
 $then st' = st \parallel mru-vote := Some (three-phase r, val (the (msgs (coord r)))) \parallel$ 
 $else st' = st$ 

```

definition *send2 where*

```

 $send2 r p q st \equiv (case mru-vote st of$ 
 $Some (phs, v) \Rightarrow (if phs = three-phase r then Vote v else Null)$ 
 $| - \Rightarrow Null$ 
 $)$ 

```

— processes from which a vote was received

definition *votes-rcvd where*

```

 $votes-rcvd (msgs :: process \rightarrow 'val msg) \equiv$ 
 $\{ (q, v) . msgs q = Some (Vote v) \}$ 

```

definition *the-rcvd-vote where*

```

 $the-rcvd-vote (msgs :: process \rightarrow 'val msg) \equiv SOME v. v \in snd ` votes-rcvd msgs$ 

```

definition *next2 where*

```

 $next2 r p st msgs crd st' \equiv$ 
 $if card (votes-rcvd msgs) > N \text{ div } 2$ 
 $then st' = st \parallel decide := Some (the-rcvd-vote msgs) \parallel$ 
 $else st' = st$ 

```

The overall send function and next-state relation are simply obtained as the composition of the individual relations defined above.

definition *Paxos-sendMsg :: nat \Rightarrow process \Rightarrow process \Rightarrow 'val pstate \Rightarrow 'val msg*
where

```

 $Paxos-sendMsg (r::nat) \equiv$ 
 $if three-step r = 0 \text{ then } send0 r$ 
 $else if three-step r = 1 \text{ then } send1 r$ 
 $else send2 r$ 

```

definition

$$\begin{aligned} Paxos\text{-}nextState :: nat \Rightarrow process \Rightarrow 'val pstate \Rightarrow & (process \rightarrow 'val msg) \\ \Rightarrow process \Rightarrow 'val pstate \Rightarrow bool \end{aligned}$$

where

$$\begin{aligned} Paxos\text{-}nextState r \equiv & \text{if three-step } r = 0 \text{ then next0 } r \\ & \text{else if three-step } r = 1 \text{ then next1 } r \\ & \text{else next2 } r \end{aligned}$$

definition

Paxos-commPerRd **where**

$$Paxos\text{-}commPerRd r (HO::process HO) (crd::process coord) \equiv True$$

definition

Paxos-commGlobal **where**

$$Paxos\text{-}commGlobal HOs coords \equiv$$

$$\begin{aligned} \exists ph::nat. \exists c::process. & \\ coord (nr-steps*ph) = c & \\ \wedge card (HOs (nr-steps*ph) c) > N \text{ div } 2 & \\ \wedge (\forall p. c \in HOs (nr-steps*ph+1) p) & \\ \wedge (\forall p. card (HOs (nr-steps*ph+2) p) > N \text{ div } 2) & \end{aligned}$$

18.2 The *Paxos* Heard-Of machine

We now define the coordinated HO machine for the *Paxos* algorithm by assembling the algorithm definition and its communication-predicate.

definition *Paxos-Alg* **where**

$$\begin{aligned} Paxos\text{-}Alg \equiv & \\ (\& CinitState = Paxos\text{-}initState, \\ & sendMsg = Paxos\text{-}sendMsg, \\ & CnextState = Paxos\text{-}nextState \&) \end{aligned}$$

definition *Paxos-CHOMachine* **where**

$$\begin{aligned} Paxos\text{-}CHOMachine \equiv & \\ (\& CinitState = Paxos\text{-}initState, \\ & sendMsg = Paxos\text{-}sendMsg, \\ & CnextState = Paxos\text{-}nextState, \\ & CHOcommPerRd = Paxos\text{-}commPerRd, \end{aligned}$$

CHOcommGlobal = Paxos-commGlobal ()

abbreviation

Paxos-M ≡ (Paxos-CHOMachine::(process, 'val pstate, 'val msg) CHOMachine)

end

18.3 Proofs

type-synonym *p-TS-state = (nat × (process ⇒ (val pstate)))*

definition *Paxos-TS ::*

$$\begin{aligned} & (\text{round} \Rightarrow \text{process HO}) \\ & \Rightarrow (\text{round} \Rightarrow \text{process HO}) \\ & \Rightarrow (\text{round} \Rightarrow \text{process}) \\ & \Rightarrow \text{p-TS-state TS} \end{aligned}$$

where

Paxos-TS HOs SHOs crds = CHO-to-TS Paxos-Alg HOs SHOs (K o crds)

lemmas *Paxos-TS-defs = Paxos-TS-def CHO-to-TS-def Paxos-Alg-def CHOinit-Config-def*

Paxos-initState-def

definition *Paxos-trans-step where*

$$\begin{aligned} & \text{Paxos-trans-step HOs SHOs crds nxt-f snd-f stp} \equiv \bigcup r \mu. \\ & \{(r, cfg), (Suc r, cfg') | cfg \neq cfg'. \text{three-step } r = stp \wedge (\forall p. \\ & \mu p \in \text{get-msgs (snd-f } r \text{)} \ cfg \ (HOs \ r) \ (SHOs \ r) \ p \\ & \wedge \text{nxt-f } r \ p \ (cfg \ p) \ (\mu p) \ (crds \ r) \ (cfg' \ p) \\ &)\} \end{aligned}$$

lemma *three-step-less-D:*

$$0 < \text{three-step } r \implies \text{three-step } r = 1 \vee \text{three-step } r = 2$$

{proof}

lemma *Paxos-trans:*

$$\begin{aligned} & \text{CSHO-trans-alt Paxos-sendMsg Paxos-nextState HOs SHOs (K o crds)} = \\ & \text{Paxos-trans-step HOs SHOs crds next0 send0 0} \\ & \cup \text{Paxos-trans-step HOs SHOs crds next1 send1 1} \\ & \cup \text{Paxos-trans-step HOs SHOs crds next2 send2 2} \end{aligned}$$

$\langle proof \rangle$

type-synonym $rHO = nat \Rightarrow process HO$

18.3.1 Refinement

definition $coord\text{-vote}\text{-to}\text{-set} :: nat \Rightarrow (process \Rightarrow (val pstate)) \Rightarrow val set$ **where**

```
coord-vote-to-set r sc ≡ (let v = pstate.commit (sc (coord r)) in
    if v = None
    then {}
    else {the v})
```

definition $paxos\text{-ref}\text{-rel} :: (three\text{-step}\text{-mru}\text{-state} \times p\text{-TS-state})set$ **where**

```
paxos-ref-rel = {(sa, (r, sc)).
    opt-mru-state.next-round sa = r
    ∧ opt-mru-state.decisions sa = pstate.decide o sc
    ∧ opt-mru-state.mru-vote sa = pstate.mru-vote o sc
    ∧ (three-step r = Suc 0 → three-step-mru-state.candidates sa = coord-vote-to-set
        r sc)
}
```

lemma $mru\text{-vote}\text{-evolution0}:$

```
∀ p. next0 r p (s p) (msgs p) (crd p) (s' p) ⇒ mru-vote o s' = mru-vote o s
⟨proof⟩
```

lemma $mru\text{-vote}\text{-evolution2}:$

```
∀ p. next2 r p (s p) (msgs p) (crd p) (s' p) ⇒ mru-vote o s' = mru-vote o s
⟨proof⟩
```

lemma $decide\text{-evolution}:$

```
∀ p. next0 r p (s p) (msgs p) (crd p) (s' p) ⇒ decide o s = decide o s'
∀ p. next1 r p (s p) (msgs p) (crd p) (s' p) ⇒ decide o s = decide o s'
⟨proof⟩
```

lemma $msgs\text{-mru}\text{-vote}:$

assumes
 $\mu (coord r) \in get\text{-msgs} (send0 r) cfg (HOs r) (HOs r) (coord r)$ (**is** $\mu ?p \in -$)
shows $((msgs\text{-to}\text{-lvs} (\mu ?p)) |` HOs r ?p) = (mru\text{-vote} o cfg) |` HOs r ?p$ ⟨proof⟩

lemma $step0\text{-ref}:$

```

{paxos-ref-rel}
(Union r C. majorities.opt-mru-step0 r C),
Paxos-trans-step HOs HOs crds next0 send0 0 {> paxos-ref-rel}
⟨proof⟩

lemma step1-ref:
{paxos-ref-rel}
(Union r S v. majorities.opt-mru-step1 r S v),
Paxos-trans-step HOs HOs crds next1 send1 (Suc 0) {> paxos-ref-rel}
⟨proof⟩

lemma step2-ref:
{paxos-ref-rel}
(Union r dec-f. majorities.opt-mru-step2 r dec-f),
Paxos-trans-step HOs HOs crds next2 send2 2 {> paxos-ref-rel}
⟨proof⟩

lemma Paxos-Refines-ThreeStep-MRU:
PO-refines paxos-ref-rel
majorities.ts-mru-TS (Paxos-TS HOs HOs crds)
⟨proof⟩

```

18.3.2 Termination

theorem Paxos-termination:

```

assumes run: CHORun Paxos-Alg rho HOs crds
and commR: ∀ r. CHOcommPerRd Paxos-M r (HOs r) (crds r)
and commG: CHOcommGlobal Paxos-M HOs crds
shows ∃ r v. decide (rho r p) = Some v
⟨proof⟩

```

end

19 Chandra-Toueg $\diamond S$ Algorithm

```

theory CT-Defs
imports Heard-Of.HOModel .. / Consensus-Types .. / Consensus-Misc Three-Steps
begin

```

The following record models the local state of a process.

```

record 'val pstate =
  x :: 'val           — current value held by process
  mru-vote :: (nat × 'val) option
  commt :: 'val      — for coordinators: the value processes are asked to commit to
  decide :: 'val option — value the process has decided on, if any

```

The algorithm relies on a coordinator for each phase of the algorithm. A phase lasts three rounds. The HO model formalization already provides the infrastructure for this, but unfortunately the coordinator is not passed to the *sendMsg* function. Using the infrastructure would thus require additional invariants and proofs; for simplicity, we use a global constant instead.

```

consts coord :: nat ⇒ process
specification (coord)
  coord-phase[rule-format]: ∀ r r'. three-phase r = three-phase r' → coord r = coord r'
  ⟨proof⟩

```

Possible messages sent during the execution of the algorithm.

```

datatype 'val msg =
  ValStamp 'val nat
  | NeverVoted
  | Vote 'val
  | Null — dummy message in case nothing needs to be sent

```

Characteristic predicates on messages.

```

definition isValStamp where isValStamp m ≡ ∃ v ts. m = ValStamp v ts

```

```

definition isVote where isVote m ≡ ∃ v. m = Vote v

```

Selector functions to retrieve components of messages. These functions have a meaningful result only when the message is of an appropriate kind.

```

fun val where
  val (ValStamp v ts) = v
  | val (Vote v) = v

```

The *x* and *commt* fields of the initial state is unconstrained, all other fields are initialized appropriately.

```

definition CT-initState where
  CT-initState p st crd ≡

```

mru-vote st = None
^ decide st = None

definition *mru-vote-to-msg :: 'val pstate \Rightarrow 'val msg where*
mru-vote-to-msg st \equiv case mru-vote st of
Some (ts, v) \Rightarrow ValStamp v ts
| None \Rightarrow NeverVoted

fun *msg-to-val-stamp :: 'val msg \Rightarrow (round \times 'val)option where*
msg-to-val-stamp (ValStamp v ts) = Some (ts, v)
| msg-to-val-stamp - = None

definition *msgs-to-lvs ::*
(process \rightarrow 'val msg)
\Rightarrow (process, round \times 'val) map
where
msgs-to-lvs msgs \equiv msg-to-val-stamp \circ_m msgs

definition *send0 where*
send0 r p q st \equiv
if q = coord r then mru-vote-to-msg st else Null

definition *next0*
:: nat
\Rightarrow process
\Rightarrow 'val pstate
\Rightarrow (process \rightarrow 'val msg)
\Rightarrow process
\Rightarrow 'val pstate
\Rightarrow bool
where
next0 r p st msgs crd st' \equiv let Q = dom msgs; lvs = msgs-to-lvs msgs in
if p = coord r
then (st' = st () commt := (case-option (x st) snd (option-Max-by fst (ran
(lvs | 'Q)))) ())
else st' = st

definition *send1 where*
send1 r p q st \equiv

if $p = \text{coord } r$ *then* $\text{Vote} (\text{commt } st)$ *else* Null

definition next1

```
:: nat
⇒ process
⇒ 'val pstate
⇒ (process → 'val msg)
⇒ process
⇒ 'val pstate
⇒ bool
```

where

```
 $\text{next1 } r \ p \ st \ msgs \ crd \ st' \equiv$ 
  if  $\text{msgs} (\text{coord } r) \neq \text{None}$ 
  then  $st' = st \ (\text{mru-vote} := \text{Some} (\text{three-phase } r, \text{val} (\text{the} (\text{msgs} (\text{coord } r)))) \ )$ 
  else  $st' = st$ 
```

definition send2 **where**

```
 $\text{send2 } r \ p \ q \ st \equiv (\text{case mru-vote } st \ \text{of}$ 
   $\text{Some} (\text{phs}, v) \Rightarrow (\text{if } \text{phs} = \text{three-phase } r \ \text{then } \text{Vote } v \ \text{else } \text{Null})$ 
  | -  $\Rightarrow \text{Null}$ 
)
```

— processes from which a vote was received

definition votes-rcvd **where**

```
 $\text{votes-rcvd } (\text{msgs} :: \text{process} \rightarrow 'val msg) \equiv$ 
  { $(q, v) . \text{msgs } q = \text{Some} (\text{Vote } v)$ }
```

definition the-rcvd-vote **where**

```
 $\text{the-rcvd-vote } (\text{msgs} :: \text{process} \rightarrow 'val msg) \equiv \text{SOME } v. v \in \text{snd} \ ' \text{votes-rcvd } \text{msgs}$ 
```

definition next2 **where**

```
 $\text{next2 } r \ p \ st \ msgs \ crd \ st' \equiv$ 
  if  $\text{card} (\text{votes-rcvd } \text{msgs}) > N \ \text{div } 2$ 
  then  $st' = st \ (\text{decide} := \text{Some} (\text{the-rcvd-vote } \text{msgs}))$ 
  else  $st' = st$ 
```

The overall send function and next-state relation are simply obtained as the composition of the individual relations defined above.

definition $\text{CT-sendMsg} :: \text{nat} \Rightarrow \text{process} \Rightarrow \text{process} \Rightarrow 'val pstate \Rightarrow 'val msg$

where

$$\begin{aligned} CT\text{-}sendMsg(r::nat) \equiv \\ \text{if three-step } r = 0 \text{ then } send0 r \\ \text{else if three-step } r = 1 \text{ then } send1 r \\ \text{else } send2 r \end{aligned}$$

definition

$$\begin{aligned} CT\text{-}nextState :: nat \Rightarrow process \Rightarrow 'val pstate \Rightarrow (process \multimap 'val msg) \\ \Rightarrow process \Rightarrow 'val pstate \Rightarrow bool \end{aligned}$$

where

$$\begin{aligned} CT\text{-}nextState r \equiv \\ \text{if three-step } r = 0 \text{ then } next0 r \\ \text{else if three-step } r = 1 \text{ then } next1 r \\ \text{else } next2 r \end{aligned}$$

19.1 The *CT* Heard-Of machine

We now define the coordinated HO machine for the *CT* algorithm by assembling the algorithm definition and its communication-predicate.

definition *CT-Alg* **where**

$$\begin{aligned} CT\text{-}Alg \equiv \\ (\| CinitState = CT\text{-}initState, \\ sendMsg = CT\text{-}sendMsg, \\ CnextState = CT\text{-}nextState \|) \end{aligned}$$

The CT algorithm relies on *waiting*: in each round, the coordinator waits until it hears from $\frac{N}{2}$ processes. This is reflected in the following per-round predicate.

definition

$$CT\text{-}commPerRd :: nat \Rightarrow process HO \Rightarrow process coord \Rightarrow bool$$

where

$$\begin{aligned} CT\text{-}commPerRd r HOs crds \equiv \\ \text{three-step } r = 0 \longrightarrow \text{card}(HOs(\text{coord } r)) > N \text{ div } 2 \end{aligned}$$

definition

$$CT\text{-}commGlobal \text{ where}$$
$$\begin{aligned} CT\text{-}commGlobal HOs coords \equiv \\ \exists ph::nat. \exists c::process. \\ \text{coord}(nr\text{-}steps}*ph) = c \end{aligned}$$

$$\begin{aligned} & \wedge (\forall p. c \in HOs (nr\text{-}steps*ph+1) p) \\ & \wedge (\forall p. card (HOs (nr\text{-}steps*ph+2) p) > N \text{ div } 2) \end{aligned}$$

definition *CT-CHOMachine* **where**

$$\begin{aligned} CT\text{-}CHOMachine &\equiv \\ & \langle CinitState = CT\text{-}initState, \\ & sendMsg = CT\text{-}sendMsg, \\ & CnextState = CT\text{-}nextState, \\ & CHOcommPerRd = CT\text{-}commPerRd, \\ & CHOcommGlobal = CT\text{-}commGlobal \rangle \end{aligned}$$

abbreviation

$$CT\text{-}M \equiv (CT\text{-}CHOMachine::(process, 'val pstate, 'val msg) CHOMachine)$$

end

19.2 Proofs

type-synonym *ct-TS-state* = $(nat \times (process \Rightarrow (val pstate)))$

definition *CT-TS* ::

$$\begin{aligned} & (round \Rightarrow process HO) \\ & \Rightarrow (round \Rightarrow process HO) \\ & \Rightarrow (round \Rightarrow process \Rightarrow process) \\ & \Rightarrow ct\text{-}TS-state TS \end{aligned}$$

where

$$CT\text{-}TS HOs SHOs crds = CHO\text{-}to\text{-}TS CT\text{-}Alg HOs SHOs crds$$

lemmas *CT-TS-defs* = *CT-TS-def* *CHO-to-TS-def* *CT-Alg-def* *CHOinitConfig-def*
CT-initState-def

definition *CT-trans-step* **where**

$$\begin{aligned} CT\text{-}trans\text{-}step HOs SHOs crds nxt-f snd-f stp &\equiv \bigcup r \mu. \\ & \{((r, cfg), (Suc r, cfg')) | cfg \neq cfg'. three\text{-}step r = stp \wedge (\forall p. \\ & \mu p \in get\text{-}msgs (snd-f r) cfg (HOs r) (SHOs r) p \\ & \wedge nxt-f r p (cfg p) (\mu p) (crds r p) (cfg' p) \\ &)\} \end{aligned}$$

lemma *three-step-less-D*:

$$0 < three\text{-}step r \implies three\text{-}step r = 1 \vee three\text{-}step r = 2$$

$\langle proof \rangle$

lemma *CT-trans*:

$$\begin{aligned} & CSHO\text{-trans-}alt\ CT\text{-sendMsg}\ CT\text{-nextState}\ HOs\ SHOs\ crds = \\ & \quad CT\text{-trans-step}\ HOs\ SHOs\ crds\ next0\ send0\ 0 \\ & \quad \cup\ CT\text{-trans-step}\ HOs\ SHOs\ crds\ next1\ send1\ 1 \\ & \quad \cup\ CT\text{-trans-step}\ HOs\ SHOs\ crds\ next2\ send2\ 2 \end{aligned}$$

$\langle proof \rangle$

type-synonym $rHO = nat \Rightarrow process HO$

19.2.1 Refinement

definition $ct\text{-ref-rel} :: (three\text{-step\text{-}mru\text{-}state} \times ct\text{-TS-state})set$ **where**

$$\begin{aligned} ct\text{-ref-rel} = & \{(sa, (r, sc)) . \\ & opt\text{-mru\text{-}state}.next\text{-}round\ sa = r \\ & \wedge\ opt\text{-mru\text{-}state}.decisions\ sa = pstate.decide\ o\ sc \\ & \wedge\ opt\text{-mru\text{-}state}.mru\text{-}vote\ sa = pstate.mru\text{-}vote\ o\ sc \\ & \wedge\ (three\text{-}step\ r = Suc\ 0 \longrightarrow three\text{-}step\text{-}mru\text{-}state.candidates\ sa = \{commr\ (sc\ (coord\ r))\}) \\ & \} \end{aligned}$$

Now we need to use the fact that $SHOs = HOs$ (i.e. the setting is non-Byzantine), and also the fact that the coordinator receives enough messages in each round

lemma *mru-vote-evolution0*:

$$\forall p. next0\ r\ p\ (s\ p)\ (msgs\ p)\ (crd\ p)\ (s'\ p) \implies mru\text{-}vote\ o\ s' = mru\text{-}vote\ o\ s$$

$\langle proof \rangle$

lemma *mru-vote-evolution2*:

$$\forall p. next2\ r\ p\ (s\ p)\ (msgs\ p)\ (crd\ p)\ (s'\ p) \implies mru\text{-}vote\ o\ s' = mru\text{-}vote\ o\ s$$

$\langle proof \rangle$

lemma *decide-evolution*:

$$\begin{aligned} \forall p. next0\ r\ p\ (s\ p)\ (msgs\ p)\ (crd\ p)\ (s'\ p) \implies decide\ o\ s = decide\ o\ s' \\ \forall p. next1\ r\ p\ (s\ p)\ (msgs\ p)\ (crd\ p)\ (s'\ p) \implies decide\ o\ s = decide\ o\ s' \end{aligned}$$

$\langle proof \rangle$

lemma *msgs-mru-vote*:

```

assumes
 $\mu (coord\ r) \in get-msgs\ (send0\ r)\ cfg\ (HOs\ r)\ (HOs\ r)\ (coord\ r)$  (is  $\mu\ ?p \in -$ )
shows ((msgs-to-lvs ( $\mu\ ?p$ )) |‘ HOs r ?p) = (mru-vote o cfg) |‘ HOs r ?p ⟨proof⟩

context
fixes
 $HOs :: nat \Rightarrow process \Rightarrow process\ set$ 
and  $crds :: nat \Rightarrow process \Rightarrow process$ 
assumes
per-rd:  $\forall r. CT-commPerRd\ r\ (HOs\ r)\ (crds\ r)$ 
begin

lemma step0-ref:
{ct-ref-rel}
( $\bigcup r C. majorities.opt-mru-step0\ r\ C$ ),
CT-trans-step HOs HOs crds next0 send0 0 {> ct-ref-rel}
⟨proof⟩

lemma step1-ref:
{ct-ref-rel}
( $\bigcup r S v. majorities.opt-mru-step1\ r\ S\ v$ ),
CT-trans-step HOs HOs crds next1 send1 (Suc 0) {> ct-ref-rel}
⟨proof⟩

lemma step2-ref:
{ct-ref-rel}
( $\bigcup r dec-f. majorities.opt-mru-step2\ r\ dec-f$ ),
CT-trans-step HOs HOs crds next2 send2 2 {> ct-ref-rel}
⟨proof⟩

lemma CT-Refines-ThreeStep-MRU:
PO-refines ct-ref-rel majorities.ts-mru-TS (CT-TS HOs HOs crds)
⟨proof⟩

end

```

19.2.2 Termination

theorem CT-termination:
assumes run: CHORun CT-Alg rho HOs crds

```

and commR:  $\forall r. \text{CHOcommPerRd } CT\text{-}M r (\text{HOs } r) (\text{crds } r)$ 
and commG:  $\text{CHOcommGlobal } CT\text{-}M \text{HOs crds}$ 
shows  $\exists r v. \text{decide } (\rho r p) = \text{Some } v$ 
<proof>

```

end

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