

CIMP

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Abstract

CIMP extends the small imperative language IMP with control non-determinism and constructs for synchronous message passing.

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1 Lifted predicates

Typically we define predicates as functions of a state. The following provide a somewhat comfortable imitation of Isabelle/HOL's operators.

abbreviation (*input*)

$pred\text{-}pair :: ('a \Rightarrow 'b) \Rightarrow ('a \Rightarrow 'c) \Rightarrow 'a \Rightarrow 'b \times 'c$ (**infixr** \otimes 60) **where**
 $a \otimes b \equiv \lambda s. (a\ s, b\ s)$

abbreviation (*input*)

$pred-in :: ('a \Rightarrow 'b) \Rightarrow ('a \Rightarrow 'b\ set) \Rightarrow 'a \Rightarrow bool$ (**infix in 50**) **where**
 $a\ in\ A \equiv \lambda s. a\ s \in A\ s$

abbreviation (*input*)

$pred-subseteq :: ('a \Rightarrow 'b\ set) \Rightarrow ('a \Rightarrow 'b\ set) \Rightarrow 'a \Rightarrow bool$ (**infix subseteq 50**) **where**
 $A\ subseteq\ B \equiv \lambda s. A\ s \subseteq B\ s$

abbreviation (*input*)

$pred-union :: ('a \Rightarrow 'b\ set) \Rightarrow ('a \Rightarrow 'b\ set) \Rightarrow 'a \Rightarrow 'b\ set$ (**infixl union 65**) **where**
 $a\ union\ b \equiv \lambda s. a\ s \cup b\ s$

abbreviation (*input*)

$pred-diff :: ('a \Rightarrow 'b\ set) \Rightarrow ('a \Rightarrow 'b\ set) \Rightarrow 'a \Rightarrow 'b\ set$ (**infixr diff 65**) **where**
 $a\ diff\ b \equiv \lambda s. a\ s - b\ s$

abbreviation (*input*)

$pred-comp :: (('b \Rightarrow 'c) \Rightarrow 'a \Rightarrow 'd) \Rightarrow ('b \Rightarrow 'a \Rightarrow 'c) \Rightarrow 'a \Rightarrow 'd$ (**infixl o 55**) **where**
 $f\ o\ g \equiv \lambda s. f\ (\lambda b. g\ b\ s)\ s$

abbreviation (*input*)

$pred-app :: ('b \Rightarrow 'a \Rightarrow 'c) \Rightarrow ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow 'c$ (**infixl ▷ 100**) **where**
 $f\ ▷\ g \equiv \lambda s. f\ (g\ s)\ s$

abbreviation (*input*)

$pred-eq :: ('a \Rightarrow 'b) \Rightarrow ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow bool$ (**infix eq 40**) **where**
 $a\ eq\ b \equiv \lambda s. a\ s = b\ s$

abbreviation (*input*)

$pred-neq :: ('a \Rightarrow 'b) \Rightarrow ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow bool$ (**infix neq 40**) **where**
 $a\ neq\ b \equiv \lambda s. a\ s \neq b\ s$

abbreviation (*input*)

$pred-lt :: ('a \Rightarrow 'b::ord) \Rightarrow ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow bool$ (**infix lt 40**) **where**
 $a\ lt\ b \equiv \lambda s. a\ s < b\ s$

abbreviation (*input*)

$pred-and :: ('a \Rightarrow bool) \Rightarrow ('a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**infixr and 35**) **where**
 $a\ and\ b \equiv \lambda s. a\ s \wedge b\ s$

abbreviation (*input*)

$pred-or :: ('a \Rightarrow bool) \Rightarrow ('a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**infixr or 30**) **where**
 $a\ or\ b \equiv \lambda s. a\ s \vee b\ s$

abbreviation (*input*)

$pred-not :: ('a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**not - [40] 40**) **where**
 $not\ a \equiv \lambda s. \neg a\ s$

abbreviation (*input*)

$pred\text{-}imp :: ('a \Rightarrow bool) \Rightarrow ('a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**infixr** *imp* 25) **where**
 $a\ imp\ b \equiv \lambda s. a\ s \longrightarrow b\ s$

abbreviation (*input*)

$pred\text{-}iff :: ('a \Rightarrow bool) \Rightarrow ('a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**infixr** *iff* 25) **where**
 $a\ iff\ b \equiv \lambda s. a\ s \longleftrightarrow b\ s$

abbreviation (*input*)

$pred\text{-}K :: 'b \Rightarrow 'a \Rightarrow 'b \langle \langle - \rangle \rangle$ **where**
 $\langle f \rangle \equiv \lambda s. f$

abbreviation (*input*)

$pred\text{-}conjoin :: ('a \Rightarrow bool)\ list \Rightarrow 'a \Rightarrow bool$ **where**
 $pred\text{-}conjoin\ xs \equiv foldr\ (op\ and)\ xs\ \langle True \rangle$

abbreviation (*input*)

$pred\text{-}singleton :: ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow 'b\ set$ **where**
 $pred\text{-}singleton\ x \equiv \lambda s. \{x\ s\}$

abbreviation (*input*)

$pred\text{-}empty :: ('a \Rightarrow 'b\ set) \Rightarrow 'a \Rightarrow bool$ (*empty* - [40] 40) **where**
 $empty\ a \equiv \lambda s. a\ s = \{\}$

abbreviation (*input*)

$pred\text{-}map\text{-}empty :: ('a \Rightarrow ('b \Rightarrow 'c\ option)) \Rightarrow 'a \Rightarrow bool$ (*map'-empty* - [40] 40) **where**
 $map\text{-}empty\ a \equiv \lambda s. a\ s = Map.empty$

abbreviation (*input*)

$pred\text{-}list\text{-}null :: ('a \Rightarrow 'b\ list) \Rightarrow 'a \Rightarrow bool$ (*list'-null* - [40] 40) **where**
 $list\text{-}null\ a \equiv \lambda s. a\ s = []$

abbreviation (*input*)

$pred\text{-}null :: ('a \Rightarrow 'b\ option) \Rightarrow 'a \Rightarrow bool$ (*null* - [40] 40) **where**
 $null\ a \equiv \lambda s. a\ s = None$

abbreviation (*input*)

$pred\text{-}ex :: ('b \Rightarrow 'a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**binder** *EXS* 10) **where**
 $EXS\ x. P\ x \equiv \lambda s. \exists x. P\ x\ s$

abbreviation (*input*)

$pred\text{-}all :: ('b \Rightarrow 'a \Rightarrow bool) \Rightarrow 'a \Rightarrow bool$ (**binder** *ALLS* 10) **where**
 $ALLS\ x. P\ x \equiv \lambda s. \forall x. P\ x\ s$

abbreviation (*input*)

$pred\text{-}If :: ('a \Rightarrow bool) \Rightarrow ('a \Rightarrow 'b) \Rightarrow ('a \Rightarrow 'b) \Rightarrow 'a \Rightarrow 'b$ (*If* (-)/ *Then* (-)/ *Else* (-))

$[0, 0, 10] 10)$

where *If P Then x Else y* $\equiv \lambda s. \text{if } P \text{ s then } x \text{ s else } y \text{ s}$

2 CIMP syntax and semantics

We define a small sequential programming language with synchronous message passing primitives for describing the individual processes. This has the advantage over raw transition systems in that it is programmer-readable, includes sequential composition, supports a program logic and VCG (§2.5), etc. These processes are composed in parallel at the top-level.

CIMP is inspired by IMP, as presented by Winskel (1993) and Nipkow and Klein (2014), and the classical process algebras CCS (Milner 1980, 1989) and CSP (Hoare 1985). Note that the algebraic properties of this language have not been developed.

As we operate in a concurrent setting, we need to provide a small-step semantics (§2.2), which we give in the style of *structural operational semantics* (SOS) as popularised by Plotkin (2004). The semantics of a complete system (§2.3) is presently taken simply to be the states reachable by interleaving the enabled steps of the individual processes, subject to message passing rendezvous. We leave a trace or branching semantics to future work.

2.1 Syntax

Programs are represented using an explicit (deep embedding) of their syntax, as the semantics needs to track the progress of multiple threads of control. Each (atomic) *basic command* (§2.2) is annotated with a *'location*, which we use in our assertions (§2.4.1). These locations need not be unique, though in practice they likely will be.

Processes maintain *local states* of type *'state*. These can be updated with arbitrary relations of *'state* \Rightarrow *'state set* with *LocalOp*, and conditions of type *'s* \Rightarrow *bool* are similarly shallowly embedded. This arrangement allows the end-user to select their own level of atomicity.

The sequential composition operator and control constructs are standard. We add the infinite looping construct *Loop* so we can construct single-state reactive systems; this has implications for fairness assertions.

type-synonym *'s bexp* = *'s* \Rightarrow *bool*

datatype (*'answer*, *'location*, *'question*, *'state*) *com*
 = *Request* *'location* *'state* \Rightarrow *'question* *'answer* \Rightarrow *'state* \Rightarrow *'state set* ($\{\}$ -} *Request* -
 - [0, 70, 70] 71)
 | *Response* *'location* *'question* \Rightarrow *'state* \Rightarrow (*'state* \times *'answer*) *set* ($\{\}$ -} *Response*
 - [0, 70] 71)
 | *LocalOp* *'location* *'state* \Rightarrow *'state set* ($\{\}$ -} *LocalOp* - [0, 70]
 71)
 | *Cond1* *'location* *'state* *bexp* (*'answer*, *'location*, *'question*, *'state*) *com* ($\{\}$ -} *IF* - *THEN*
 - *FI* [0, 0] 71)
 | *Cond2* *'location* *'state* *bexp* (*'answer*, *'location*, *'question*, *'state*) *com*
 (*'answer*, *'location*, *'question*, *'state*) *com* ($\{\}$ -} *IF* -/ *THEN*
 -/ *ELSE* -/ *FI* [0, 0, 0] 71)

<i>Loop</i> ('answer, 'location, 'question, 'state) com	(<i>LOOP DO -/ OD</i>
[0] 71)	
<i>While</i> 'location 'state bexp ('answer, 'location, 'question, 'state) com ($\{\!-\!\}$ <i>WHILE -/</i>	
<i>DO -/ OD</i> [0, 0, 0] 71)	
<i>Seq</i> ('answer, 'location, 'question, 'state) com	
('answer, 'location, 'question, 'state) com	(infixr ;; 69)
<i>Choose</i> ('answer, 'location, 'question, 'state) com	
('answer, 'location, 'question, 'state) com	(infixl \sqcup 68)

We provide a one-armed conditional as it is the common form and avoids the need to discover a label for an internal *SKIP* and/or trickier proofs about the VCG.

In contrast to classical process algebras, we have local state and distinct send and receive actions. These provide an interface to Isabelle/HOL's datatypes that avoids the need for binding (ala the π -calculus of Milner (1989)) or large non-deterministic sums (ala CCS (Milner 1980, §2.8)). Intuitively the sender asks a '*question*' with a *Request* command, which upon rendezvous with a receiver's *Response* command receives an '*answer*'. The '*question*' is a deterministic function of the sender's local state, whereas a receiver can respond non-deterministically. Note that CIMP does not provide a notion of channel; these can be modelled by a judicious choice of '*question*'.

We also provide a binary external choice operator. Internal choice can be recovered in combination with local operations (see Milner (1980, §2.3)).

We abbreviate some common commands: *SKIP* is a local operation that does nothing, and the floor brackets simplify deterministic *LocalOps*. We also adopt some syntax magic from Makarius's Hoare and Multiquote theories in the Isabelle/HOL distribution.

abbreviation *SKIP-syn* ($\{\!-\!\}$ / *SKIP* 70) **where**

$$\{\!l\!\} \text{ SKIP} \equiv \{\!l\!\} \text{ LocalOp } (\lambda s. \{s\})$$

abbreviation (*input*) *DetLocalOp* :: 'location \Rightarrow ('state \Rightarrow 'state)

$$\Rightarrow ('answer, 'location, 'question, 'state) \text{ com } (\{\!-\!\} \text{ [-]}) \text{ where}$$

$$\{\!l\!\} [f] \equiv \{\!l\!\} \text{ LocalOp } (\lambda s. \{f s\})$$

syntax

$$\text{-quote} \quad :: 'b \Rightarrow ('a \Rightarrow 'b) (\ll\text{-}\gg [0] 1000)$$

$$\text{-antiquote} \quad :: ('a \Rightarrow 'b) \Rightarrow 'b (\text{'-} [1000] 1000)$$

$$\text{-Assign} \quad :: 'location \Rightarrow \text{idt} \Rightarrow 'b \Rightarrow ('answer, 'location, 'question, 'state) \text{ com } ((\{\!-\!\} \text{'-} :=/ \text{-}) [0, 0, 70] 71)$$

$$\text{-NonDetAssign} \quad :: 'location \Rightarrow \text{idt} \Rightarrow 'b \text{ set} \Rightarrow ('answer, 'location, 'question, 'state) \text{ com } ((\{\!-\!\} \text{'-} :∈/ \text{-}) [0, 0, 70] 71)$$

abbreviation (*input*) *NonDetAssign* :: 'location \Rightarrow (('val \Rightarrow 'val) \Rightarrow 'state \Rightarrow 'state) \Rightarrow ('state \Rightarrow 'val set)

$$\Rightarrow ('answer, 'location, 'question, 'state) \text{ com } \text{where}$$

$$\text{NonDetAssign } l \text{ upd } es \equiv \{\!l\!\} \text{ LocalOp } (\lambda s. \{ \text{upd } \langle e \rangle s \mid e. e \in es \ s \})$$

translations

$$\{\!l\!\} \text{' } x := e \Rightarrow \text{CONST } \text{DetLocalOp } l \ll\text{'(-update-name } x (\lambda\text{-. } e)\gg$$

$\{\!|l|\!\} \text{ 'x :} \in \text{ es} \Rightarrow \text{CONST NonDetAssign l (-update-name x) } \ll \text{es} \gg$

$\langle \text{ML} \rangle$

2.2 Process semantics

Here we define the semantics of a single process's program. We begin by defining the type of externally-visible behaviour:

datatype ('answer, 'question) seq-label
 = sl-Internal (τ)
 | sl-Send 'question 'answer ($\ll-$, $->$)
 | sl-Receive 'question 'answer ($\gg-$, $-<$)

We define a *labelled transition system* (an LTS) using an execution-stack style of semantics that avoids special treatment of the *SKIPs* introduced by a traditional small step semantics (such as Winskel (1993, Chapter 14)) when a basic command is executed. This was suggested by Thomas Sewell; Pitts (2002) gave a semantics to an ML-like language using this approach.

type-synonym ('answer, 'location, 'question, 'state) local-state
 = ('answer, 'location, 'question, 'state) com list \times 'state

inductive

small-step :: ('answer, 'location, 'question, 'state) local-state
 \Rightarrow ('answer, 'question) seq-label
 \Rightarrow ('answer, 'location, 'question, 'state) local-state \Rightarrow bool ($- \rightarrow_- -$ [55, 0, 56]

55)

where

| Request: $\llbracket \alpha = \text{action } s; s' \in \text{val } \beta \text{ } s \rrbracket \Longrightarrow (\{\!|l|\!\} \text{ Request action val } \# \text{ cs, } s) \rightarrow_{\ll\alpha, \beta\gg} (\text{cs, } s')$

| Response: $(s', \beta) \in \text{action } \alpha \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ Response action } \# \text{ cs, } s) \rightarrow_{\gg\alpha, \beta\ll} (\text{cs, } s')$

| LocalOp: $s' \in R \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ LocalOp } R \# \text{ cs, } s) \rightarrow_{\tau} (\text{cs, } s')$

| Cond1True: $b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ IF } b \text{ THEN } c \text{ FI } \# \text{ cs, } s) \rightarrow_{\tau} (c \# \text{ cs, } s)$

| Cond1False: $\neg b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ IF } b \text{ THEN } c \text{ FI } \# \text{ cs, } s) \rightarrow_{\tau} (\text{cs, } s)$

| Cond2True: $b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ IF } b \text{ THEN } c1 \text{ ELSE } c2 \text{ FI } \# \text{ cs, } s) \rightarrow_{\tau} (c1 \# \text{ cs, } s)$

| Cond2False: $\neg b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ IF } b \text{ THEN } c1 \text{ ELSE } c2 \text{ FI } \# \text{ cs, } s) \rightarrow_{\tau} (c2 \# \text{ cs, } s)$

| Loop: $(c \# \text{ LOOP DO } c \text{ OD } \# \text{ cs, } s) \rightarrow_{\alpha} (\text{cs}', s') \Longrightarrow (\text{LOOP DO } c \text{ OD } \# \text{ cs, } s) \rightarrow_{\alpha} (\text{cs}', s')$

| While: $b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ WHILE } b \text{ DO } c \text{ OD } \# \text{ cs, } s) \rightarrow_{\tau} (c \# \{\!|l|\!\} \text{ WHILE } b \text{ DO } c \text{ OD } \# \text{ cs, } s)$

| WhileFalse: $\neg b \text{ } s \Longrightarrow (\{\!|l|\!\} \text{ WHILE } b \text{ DO } c \text{ OD } \# \text{ cs, } s) \rightarrow_{\tau} (\text{cs, } s)$

| Seq: $(c1 \# c2 \# \text{ cs, } s) \rightarrow_{\alpha} (\text{cs}', s') \Longrightarrow (c1;; c2 \# \text{ cs, } s) \rightarrow_{\alpha} (\text{cs}', s')$

| *Choose1*: $(c1 \# cs, s) \rightarrow_{\alpha} (cs', s') \implies (c1 \sqcup c2 \# cs, s) \rightarrow_{\alpha} (cs', s')$
 | *Choose2*: $(c2 \# cs, s) \rightarrow_{\alpha} (cs', s') \implies (c1 \sqcup c2 \# cs, s) \rightarrow_{\alpha} (cs', s')$

The following projections operate on local states. These are internal to CIMP and should not appear to the end-user.

abbreviation *cPGM* :: ('answer, 'location, 'question, 'state) local-state \Rightarrow ('answer, 'location, 'question, 'state) com list **where**
cPGM \equiv *fst*

abbreviation *cLST* :: ('answer, 'location, 'question, 'state) local-state \Rightarrow 'state **where**
cLST *s* \equiv *snd* *s*⟨*proof*⟩⟨*proof*⟩

To reason about system transitions we need to identify which basic statement gets executed next. To that end we factor out the recursive cases of the *small-step* semantics into *contexts*, which identify the *basic-com* commands with immediate externally-visible behaviour. Note that non-determinism means that more than one *basic-com* can be enabled at a time.

The representation of evaluation contexts follows [Berghofer \(2012\)](#). This style of operational semantics was originated by [Felleisen and Hieb \(1992\)](#).

type-synonym ('answer, 'location, 'question, 'state) *ctxt*
 $=$ ('answer, 'location, 'question, 'state) com \Rightarrow ('answer, 'location, 'question, 'state) com

inductive-set

ctxt :: (('answer, 'location, 'question, 'state) *ctxt*
 \times (('answer, 'location, 'question, 'state) com \Rightarrow ('answer, 'location, 'question, 'state) com list)) set

where

C-Hole: $(id, \langle [] \rangle) \in ctxt$
 | *C-Loop*: $(E, fctxt) \in ctxt \implies (\lambda t. LOOP DO E t OD, \lambda t. fctxt t @ [LOOP DO E t OD]) \in ctxt$
 | *C-Seq*: $(E, fctxt) \in ctxt \implies (\lambda t. E t;; u, \lambda t. fctxt t @ [u]) \in ctxt$
 | *C-Choose1*: $(E, fctxt) \in ctxt \implies (\lambda t. E t \sqcup u, fctxt) \in ctxt$
 | *C-Choose2*: $(E, fctxt) \in ctxt \implies (\lambda t. u \sqcup E t, fctxt) \in ctxt$

inductive

basic-com :: ('answer, 'location, 'question, 'state) com \Rightarrow bool

where

basic-com ($\{l\}$ Request action val)
 | *basic-com* ($\{l\}$ Response action)
 | *basic-com* ($\{l\}$ LocalOp R)
 | *basic-com* ($\{l\}$ IF b THEN c FI)
 | *basic-com* ($\{l\}$ IF b THEN c1 ELSE c2 FI)
 | *basic-com* ($\{l\}$ WHILE b DO c OD)

We can decompose a small step into a context and a *basic-com*.

fun

decompose-com :: ('answer, 'location, 'question, 'state) com
 \Rightarrow (('answer, 'location, 'question, 'state) com

$$\begin{aligned} & \times ('answer, 'location, 'question, 'state) \text{ ctxt} \\ & \times (('answer, 'location, 'question, 'state) \text{ com} \Rightarrow ('answer, 'location, \\ & 'question, 'state) \text{ com list}) \text{ set} \end{aligned}$$

where

$$\begin{aligned} & \text{decompose-com } (LOOP DO c1 OD) = \{ (c, \lambda t. LOOP DO \text{ictxt } t OD, \lambda t. \text{fctxt } t @ [LOOP \\ & DO \text{ictxt } t OD]) \mid c \text{ fctxt } \text{ictxt}. (c, \text{ictxt}, \text{fctxt}) \in \text{decompose-com } c1 \} \\ & \mid \text{decompose-com } (c1;; c2) = \{ (c, \lambda t. \text{ictxt } t;; c2, \lambda t. \text{fctxt } t @ [c2]) \mid c \text{ fctxt } \text{ictxt}. (c, \text{ictxt}, \\ & \text{fctxt}) \in \text{decompose-com } c1 \} \\ & \mid \text{decompose-com } (c1 \sqcup c2) = \{ (c, \lambda t. \text{ictxt } t \sqcup c2, \text{fctxt}) \mid c \text{ fctxt } \text{ictxt}. (c, \text{ictxt}, \text{fctxt}) \in \\ & \text{decompose-com } c1 \} \\ & \cup \{ (c, \lambda t. c1 \sqcup \text{ictxt } t, \text{fctxt}) \mid c \text{ fctxt } \text{ictxt}. (c, \text{ictxt}, \text{fctxt}) \in \\ & \text{decompose-com } c2 \} \\ & \mid \text{decompose-com } c = \{(c, id, \langle [] \rangle)\} \end{aligned}$$

definition

$$\begin{aligned} & \text{decomposeLS} :: ('answer, 'location, 'question, 'state) \text{ local-state} \\ & \Rightarrow (('answer, 'location, 'question, 'state) \text{ com} \\ & \quad \times (('answer, 'location, 'question, 'state) \text{ com} \Rightarrow ('answer, 'location, 'question, \\ & 'state) \text{ com}) \\ & \quad \times (('answer, 'location, 'question, 'state) \text{ com} \Rightarrow ('answer, 'location, 'question, \\ & 'state) \text{ com list}) \text{ set} \end{aligned}$$

where

$$\text{decomposeLS } s \equiv \text{case } cPGM \text{ s of } c \# - \Rightarrow \text{decompose-com } c \mid - \Rightarrow \{\}$$

<proof><proof><proof>

theorem context-decompose:

$$\begin{aligned} & s \rightarrow_{\alpha} s' \iff (\exists (c, \text{ictxt}, \text{fctxt}) \in \text{decomposeLS } s. \\ & \quad cPGM \text{ s} = \text{ictxt } c \# \text{tl } (cPGM \text{ s}) \\ & \quad \wedge \text{basic-com } c \\ & \quad \wedge (c \# \text{fctxt } c @ \text{tl } (cPGM \text{ s}), cLST \text{ s}) \rightarrow_{\alpha} s') \text{ <proof>} \end{aligned}$$

While we only use this result left-to-right (to decompose a small step into a basic one), this equivalence shows that we lose no information in doing so.

2.3 System steps

A global state maps process names to process' local states. One might hope to allow processes to have distinct types of local state, but there remains no good solution yet in a simply-typed setting; see [Schirmer and Wenzel \(2009\)](#).

type-synonym $('answer, 'location, 'proc, 'question, 'state) \text{ global-state}$
 $= 'proc \Rightarrow ('answer, 'location, 'question, 'state) \text{ local-state}$

type-synonym $('proc, 'state) \text{ local-states}$
 $= 'proc \Rightarrow 'state$

An execution step of the overall system is either any enabled internal τ step of any process, or a communication rendezvous between two processes. For the latter to occur, a *Request*

action must be enabled in process $p1$, and a *Response* action in (distinct) process $p2$, where the request/response labels α and β (semantically) match.

We also track global communication history here to support assertional reasoning (see §2.4).

type-synonym ('answer, 'question) event = 'question × 'answer

type-synonym ('answer, 'question) history = ('answer, 'question) event list

type-synonym ('answer, 'location, 'proc, 'question, 'state) system-state

= ('answer, 'location, 'proc, 'question, 'state) global-state

× ('answer, 'question) history

inductive-set

system-step :: (('answer, 'ls, 'proc, 'question, 'state) system-state

× ('answer, 'ls, 'proc, 'question, 'state) system-state) set

where

LocalStep: $\llbracket s \ p \rightarrow_{\tau} \ ls' ; s' = s(p := ls') ; h' = h \rrbracket \Longrightarrow ((s, h), (s', h')) \in \text{system-step}$

| CommunicationStep: $\llbracket s \ p1 \rightarrow_{\llcorner\alpha, \beta\gg} \ ls1' ; s \ p2 \rightarrow_{\gg\alpha, \beta\ll} \ ls2' ; p1 \neq p2 ;$

$s' = s(p1 := ls1', p2 := ls2') ; h' = h @ [(\alpha, \beta)] \rrbracket \Longrightarrow ((s, h), (s', h')) \in$

system-step

abbreviation

system-step-syn :: ('answer, 'ls, 'proc, 'question, 'state) system-state

\Rightarrow ('answer, 'ls, 'proc, 'question, 'state) system-state \Rightarrow bool (- $s \Rightarrow$ - [55,

56] 55)

where

sh $s \Rightarrow sh' \equiv (sh, sh') \in \text{system-step}$

abbreviation

system-steps-syn :: ('answer, 'ls, 'proc, 'question, 'state) system-state

\Rightarrow ('answer, 'ls, 'proc, 'question, 'state) system-state \Rightarrow bool (- $s \Rightarrow^*$ - [55,

56] 55)

where

sh $s \Rightarrow^* sh' \equiv (sh, sh') \in \text{system-step}^*$

In classical process algebras matching communication actions yield τ steps, which aids nested parallel composition and the restriction operation (Milner 1980, §2.2). As CIMP does not provide either we do not need to hide communication labels. In CCS/CSP it is not clear how one reasons about the communication history, and it seems that assertional reasoning about these languages is not well developed.

2.4 Assertions

We now develop a technique for showing that a CIMP system satisfies a single global invariant, following Lamport (1980); Lamport and Schneider (1984) (and the later Lamport (2002)) and closely related work by Cousot and Cousot (1980) and Levin and Gries (1981), which suggest the incorporation of a history variable. Cousot and Cousot (1980) apparently contains a completeness proof. Lamport mentions that this technique was well-known in the mid-80s

when he proposed the use of prophecy variables (see his webpage bibliography). See [de Roever, de Boer, Hannemann, Hooman, Lakhnech, Poel, and Zwiers \(2001\)](#) for an extended discussion of some of this.

Achieving the right level of abstraction is a bit fiddly; we want to avoid revealing too much of the program text as it executes. Intuitively we wish to expose the processes's present control locations and local states only. [Lamport](#) avoids these issues by only providing an axiomatic semantics for his language.

2.4.1 Control predicates

Following [Lamport \(1980\)](#)¹, we define the *at* predicate, which holds of a process when control resides at that location. Due to non-determinism processes can be *at* a set of locations; it is more like “a statement with this location is enabled”, which incidentally handles non-unique locations. Lamport's language is deterministic, so he doesn't have this problem. This also allows him to develop a stronger theory about his control predicates.

primrec

$atC :: ('answer, 'location, 'question, 'state) com \Rightarrow 'location \Rightarrow bool$

where

$atC (\{l\} Request\ action\ val) = (\lambda l. l = l')$
 $| atC (\{l\} Response\ action) = (\lambda l. l = l')$
 $| atC (\{l\} LocalOp\ f) = (\lambda l. l = l')$
 $| atC (\{l\} IF - THEN - FI) = (\lambda l. l = l')$
 $| atC (\{l\} IF - THEN - ELSE - FI) = (\lambda l. l = l')$
 $| atC (\{l\} WHILE - DO - OD) = (\lambda l. l = l')$
 $| atC (LOOP\ DO\ c\ OD) = atC\ c$
 $| atC (c1;; c2) = atC\ c1$
 $| atC (c1 \sqcup c2) = (atC\ c1\ or\ atC\ c2)$

primrec $atL :: ('answer, 'location, 'question, 'state) com\ list \Rightarrow 'location \Rightarrow bool$ **where**

$atL [] = \langle False \rangle$
 $| atL (c \# -) = atC\ c$

abbreviation $atLS :: ('answer, 'location, 'question, 'state) local-state \Rightarrow 'location \Rightarrow bool$

where

$atLS \equiv \lambda s. atL (cPGM\ s)\langle proof \rangle\langle proof \rangle$

We define predicates over communication histories and a projection of global states. These are uncurried to ease composition.

type-synonym $('location, 'proc, 'state) pred-local-state$

$= 'proc \Rightarrow (('location \Rightarrow bool) \times 'state)$

record $('answer, 'location, 'proc, 'question, 'state) pred-state =$

$local-states :: ('location, 'proc, 'state) pred-local-state$

¹[Manna and Pnueli \(1995\)](#) also develop a theory of locations. I think Lamport attributes control predicates to Owicki in her PhD thesis (under Gries). I did not find a treatment of procedures. [Manna and Pnueli \(1991\)](#) observe that a set notation for spreading assertions over sets of locations reduces clutter significantly.

$hist :: ('answer, 'question) history$

type-synonym $('answer, 'location, 'proc, 'question, 'state) pred$
 $= ('answer, 'location, 'proc, 'question, 'state) pred-state \Rightarrow bool$

definition $mkP :: ('answer, 'location, 'proc, 'question, 'state) system-state \Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred-state$ **where**
 $mkP \equiv \lambda(s, h). (\downarrow local-states = \lambda p. case s p of (cs, ps) \Rightarrow (atL cs, ps), hist = h) \langle proof \rangle$

We provide the following definitions to the end-user.

AT maps process names to a predicate that is true of locations where control for that process resides. The abbreviation at shuffles its parameters; the former is simplifier-friendly and eta-reduced, while the latter is convenient for writing assertions.

definition $AT :: ('answer, 'location, 'proc, 'question, 'state) pred-state \Rightarrow 'proc \Rightarrow 'location \Rightarrow bool$ **where**
 $AT \equiv \lambda s p l. fst (local-states s p) l$

abbreviation $at :: 'proc \Rightarrow 'location \Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred$ **where**
 $at p l s \equiv AT s p l$

Often we wish to talk about control residing at one of a set of locations. This stands in for, and generalises, the in predicate of [Lampert \(1980\)](#).

definition $atS :: 'proc \Rightarrow 'location set \Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred$ **where**
 $atS \equiv \lambda p ls s. \exists l \in ls. at p l s$

A process is terminated if it not at any control location.

abbreviation $terminated :: 'proc \Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred$ **where**
 $terminated p s \equiv \forall l. \neg at p l s$

The LST operator (written as a postfix \downarrow) projects the local states of the processes from a $pred-state$, i.e. it discards control location information.

Conversely the $LSTP$ operator lifts predicates over local states into predicates over $pred-state$. [Levin and Gries \(1981, §3.6\)](#) call such predicates *universal assertions*.

type-synonym $('proc, 'state) state-pred$
 $= ('proc, 'state) local-states \Rightarrow bool$

definition $LST :: ('answer, 'location, 'proc, 'question, 'state) pred-state$
 $\Rightarrow ('proc, 'state) local-states (-\downarrow [1000] 1000)$ **where**
 $s \downarrow \equiv snd \circ local-states s$

abbreviation (*input*) $LSTP :: ('proc, 'state) state-pred$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred$ **where**
 $LSTP P \equiv \lambda s. P (LST s)$

By default we ask the simplifier to rewrite atS using ambient AT information.

lemma *atS-state-cong*[*cong*]:

$\llbracket AT\ s\ p = AT\ s'\ p \rrbracket \implies atS\ p\ ls\ s \longleftrightarrow atS\ p\ ls\ s'$
 $\langle proof \rangle$

We provide an incomplete set of basic rules for label sets.

lemma *atS-simps*:

$\neg atS\ p\ \{\} s$
 $atS\ p\ \{l\} s \longleftrightarrow at\ p\ l\ s$
 $\llbracket at\ p\ l\ s; l \in ls \rrbracket \implies atS\ p\ ls\ s \longleftrightarrow True$
 $(\forall l. at\ p\ l\ s \longrightarrow l \notin ls) \implies atS\ p\ ls\ s \longleftrightarrow False$
 $\langle proof \rangle$

lemma *atS-mono*:

$\llbracket atS\ p\ ls\ s; ls \subseteq ls' \rrbracket \implies atS\ p\ ls'\ s$
 $\langle proof \rangle$

lemma *atS-un*:

$atS\ p\ (l \cup l')\ s \longleftrightarrow atS\ p\ l\ s \vee atS\ p\ l'\ s$
 $\langle proof \rangle$

2.4.2 Invariants

A complete system consists of one program per process, and a (global) constraint on their initial local states. From these we can construct the set of initial global states and all those reachable by system steps (§2.3).

type-synonym (*'answer, 'location, 'proc, 'question, 'state*) *programs*
 $= 'proc \Rightarrow ('answer, 'location, 'question, 'state)\ com$

type-synonym (*'answer, 'location, 'proc, 'question, 'state*) *system*
 $= ('answer, 'location, 'proc, 'question, 'state)\ programs$
 $\times ('proc, 'state)\ state-pred$

definition

initial-states $:: ('answer, 'location, 'proc, 'question, 'state)\ system$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state)\ global-state\ set$

where

initial-states $sys \equiv$
 $\{ f \cdot (\forall p. cPGM\ (f\ p) = [fst\ sys\ p]) \wedge snd\ sys\ (cLST \circ f) \}$

definition

reachable-states $:: ('answer, 'location, 'proc, 'question, 'state)\ system$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state)\ system-state\ set$

where

reachable-states $sys \equiv system-step^* \text{ “ } (initial-states\ sys \times \{\}\}$

The following is a slightly more convenient induction rule for the set of reachable states.

lemma *reachable-states-system-step-induct*[*consumes 1*,

case-names init LocalStep CommunicationStep]:

assumes r : $(s, h) \in \text{reachable-states } \text{sys}$
assumes i : $\bigwedge s. s \in \text{initial-states } \text{sys} \implies P s []$
assumes l : $\bigwedge s h ls' p. \llbracket (s, h) \in \text{reachable-states } \text{sys}; P s h; s p \rightarrow_{\tau} ls' \rrbracket$
 $\implies P (s(p := ls')) h$
assumes c : $\bigwedge s h ls1' ls2' p1 p2 \alpha \beta.$
 $\llbracket (s, h) \in \text{reachable-states } \text{sys}; P s h;$
 $s p1 \rightarrow_{\ll \alpha, \beta} ls1'; s p2 \rightarrow_{\gg \alpha, \beta} ls2'; p1 \neq p2 \rrbracket$
 $\implies P (s(p1 := ls1', p2 := ls2')) (h @ [(\alpha, \beta)])$
shows $P s h \langle \text{proof} \rangle \langle \text{proof} \rangle \langle \text{proof} \rangle$

2.4.3 Relating reachable states to the initial programs

To usefully reason about the control locations presumably embedded in the single global invariant, we need to link the programs we have in reachable state s to the programs in the initial states. The *fragments* function decomposes the program into statements that can be directly executed (§2.2). We also compute the locations we could be at after executing that statement as a function of the process's local state.

We could support Lamport's *after* control predicate with more syntactic analysis of this kind.

fun

extract-cond :: $(\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{com} \Rightarrow \text{'state } \text{bexp}$

where

extract-cond ($\{\!|l|\!\}$ IF b THEN c FI) = b
 \mid *extract-cond* ($\{\!|l|\!\}$ IF b THEN $c1$ ELSE $c2$ FI) = b
 \mid *extract-cond* ($\{\!|l|\!\}$ WHILE b DO c OD) = b
 \mid *extract-cond* c = $\langle \text{False} \rangle$

type-synonym $(\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{loc-comp}$

= $(\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{com}$
 $\Rightarrow \text{'state} \Rightarrow \text{'location} \Rightarrow \text{bool}$

fun *lconst* :: $(\text{'location} \Rightarrow \text{bool}) \Rightarrow (\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{loc-comp}$ **where**

lconst $lp b s = lp$

definition *lcond* :: $(\text{'location} \Rightarrow \text{bool}) \Rightarrow (\text{'location} \Rightarrow \text{bool})$

$\Rightarrow (\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{loc-comp}$ **where**

lcond $lp lp' c s \equiv \text{if } \text{extract-cond } c s \text{ then } lp \text{ else } lp' \langle \text{proof} \rangle \langle \text{proof} \rangle$

fun

fragments :: $(\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{com}$
 $\Rightarrow (\text{'location} \Rightarrow \text{bool})$
 $\Rightarrow ((\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{com}$
 $\times (\text{'answer}, \text{'location}, \text{'question}, \text{'state}) \text{loc-comp}) \text{set}$

where

fragments ($\{\!|l|\!\}$ IF b THEN c FI) ls
= $\{ (\{\!|l|\!\}$ IF b THEN c' FI, *lcond* (*atC* c) ls) $\mid c'. \text{True} \}$
 $\cup \text{fragments } c \text{ } ls$

$| \text{fragments } (\{l\} \text{ IF } b \text{ THEN } c1 \text{ ELSE } c2 \text{ FI}) \text{ } ls$
 $= \{ (\{l\} \text{ IF } b \text{ THEN } c1' \text{ ELSE } c2' \text{ FI}, \text{lcond } (atC \ c1) \ (atC \ c2)) \mid c1' \ c2'. \text{ True} \}$
 $\cup \text{fragments } c1 \text{ } ls \cup \text{fragments } c2 \text{ } ls$
 $| \text{fragments } (\text{LOOP DO } c \text{ OD}) \text{ } ls = \text{fragments } c \text{ } (atC \ c)$
 $| \text{fragments } (\{l'\} \text{ WHILE } b \text{ DO } c \text{ OD}) \text{ } ls$
 $= \{ (\{l'\} \text{ WHILE } b \text{ DO } c' \text{ OD}, \text{lcond } (atC \ c) \ ls) \mid c'. \text{ True} \} \cup \text{fragments } c \text{ } (\lambda l. l = l')$
 $| \text{fragments } (c1 ;; c2) \text{ } ls = \text{fragments } c1 \text{ } (atC \ c2) \cup \text{fragments } c2 \text{ } ls$
 $| \text{fragments } (c1 \sqcup c2) \text{ } ls = \text{fragments } c1 \text{ } ls \cup \text{fragments } c2 \text{ } ls$
 $| \text{fragments } c \text{ } ls = \{ (c, \text{lconst } ls) \}$

fun

$\text{fragmentsL} :: ('answer, 'location, 'question, 'state) \text{ com list}$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{ com}$
 $\times ('answer, 'location, 'question, 'state) \text{ loc-comp }) \text{ set}$

where

$\text{fragmentsL } [] = \{ \}$
 $| \text{fragmentsL } [c] = \text{fragments } c \ \langle \text{False} \rangle$
 $| \text{fragmentsL } (c \# c' \# cs) = \text{fragments } c \text{ } (atC \ c') \cup \text{fragmentsL } (c' \# cs)$

abbreviation

$\text{fragmentsLS} :: ('answer, 'location, 'question, 'state) \text{ local-state}$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{ com}$
 $\times ('answer, 'location, 'question, 'state) \text{ loc-comp }) \text{ set}$

where

$\text{fragmentsLS } s \equiv \text{fragmentsL } (cPGM \ s) \langle \text{proof} \rangle \langle \text{proof} \rangle$

Eliding the bodies of *IF* and *WHILE* statements yields smaller (but equivalent) proof obligations.

We show that taking system steps preserves fragments.

lemma *reachable-states-fragmentsLS*:

assumes $(s, h) \in \text{reachable-states } \text{sys}$
shows $\text{fragmentsLS } (s \ p) \subseteq \text{fragments } (\text{fst } \text{sys } \ p) \ \langle \text{False} \rangle \langle \text{proof} \rangle$

Decomposing a compound command preserves fragments too.

fun

$\text{extract-inner-locations} :: ('answer, 'location, 'question, 'state) \text{ com}$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{ com list}$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{ loc-comp}$

where

$\text{extract-inner-locations } (\{l\} \text{ IF } b \text{ THEN } c \text{ FI}) \text{ } cs = \text{lcond } (atC \ c) \ (atL \ cs)$
 $| \text{extract-inner-locations } (\{l\} \text{ IF } b \text{ THEN } c1 \text{ ELSE } c2 \text{ FI}) \text{ } cs = \text{lcond } (atC \ c1) \ (atC \ c2)$
 $| \text{extract-inner-locations } (\text{LOOP DO } c \text{ OD}) \text{ } cs = \text{lconst } (atC \ c)$
 $| \text{extract-inner-locations } (\{l\} \text{ WHILE } b \text{ DO } c \text{ OD}) \text{ } cs = \text{lcond } (atC \ c) \ (atL \ cs)$
 $| \text{extract-inner-locations } c \text{ } cs = \text{lconst } (atL \ cs)$
 $\langle \text{proof} \rangle \langle \text{proof} \rangle$

lemma *small-step-extract-inner-locations*:

assumes $\text{basic-com } c$

assumes $(c \# cs, ls) \rightarrow_\alpha ls'$
shows *extract-inner-locations* $c \ cs \ c \ ls = atLS \ ls'$
 $\langle proof \rangle$

The headline lemma allows us to constrain the initial and final states of a given small step in terms of the original programs, provided the initial state is reachable.

theorem *decompose-small-step*:

assumes $s \ p \rightarrow_\alpha \ ps'$
assumes $(s, h) \in \text{reachable-states } sys$
obtains $c \ cs \ ls'$
where $(c, ls') \in \text{fragments } (fst \ sys \ p) \ \langle False \rangle$
and *basic-com* c
and $\forall l. atC \ c \ l \longrightarrow atLS \ (s \ p) \ l$
and $ls' \ c \ (cLST \ (s \ p)) = atLS \ ps'$
and $(c \ # \ cs, cLST \ (s \ p)) \rightarrow_\alpha \ ps' \langle proof \rangle$

Reasoning with *reachable-states-system-step-induct* and *decompose-small-step* is quite tedious. We provide a very simple VCG that generates friendlier local proof obligations.

2.5 Simple-minded Hoare Logic/VCG for CIMP

We do not develop a proper Hoare logic or full VCG for CIMP: this machinery merely packages up the subgoals that arise from induction over the reachable states (§2.4.2). This is somewhat in the spirit of ?.

Note that this approach is not compositional: it consults the original system to find matching communicating pairs, and *aft* tracks the labels of possible successor statements. More serious Hoare logics are provided by Cousot and Cousot (1989); Lamport (1980); Lamport and Schneider (1984).

Intuitively we need to discharge a proof obligation for either *Requests* or *Responses* but not both. Here we choose to focus on *Requests* as we expect to have more local information available about these.

inductive

$vcg :: ('answer, 'location, 'proc, 'question, 'state) \text{programs}$
 $\Rightarrow 'proc$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{loc-comp}$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state) \text{pred}$
 $\Rightarrow ('answer, 'location, 'question, 'state) \text{com}$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state) \text{pred}$
 $\Rightarrow \text{bool } (-, -, - \models / \{\!-\!\} / - / \{\!-\!\})$

where

Request: $\llbracket \bigwedge aft' \ action' \ s \ ps' \ p's' \ l' \ \beta \ s' \ p'.$
 $\llbracket \text{pre } s; (\{\!l'\!\} \ Response \ action', aft') \in \text{fragments } (pgms \ p') \ \langle False \rangle; p \neq p';$
 $\text{ps}' \in \text{val } \beta \ (LST \ s \ p); (p's', \beta) \in \text{action}' \ (\text{action} \ (LST \ s \ p)) \ (LST \ s \ p);$
 $\text{at } p \ l \ s; \text{at } p' \ l' \ s;$
 $AT \ s' = (AT \ s)(p := aft \ (\{\!l'\!\} \ Request \ action \ \text{val}) \ (LST \ s \ p),$
 $p' := aft' \ (\{\!l'\!\} \ Response \ action') \ (LST \ s \ p));$

$$\begin{aligned}
& LST\ s' = (LST\ s)(p := ps', p' := p's'); \\
& hist\ s' = hist\ s @ [(action\ (LST\ s\ p), \beta)] \\
& \quad] \implies post\ s' \\
| \quad] \implies pgms, p, aft \models \{pre\} \{l\} \text{ Request action val } \{post\} \\
| \quad LocalOp: [\bigwedge s\ ps'\ s'. [pre\ s; ps' \in f\ (LST\ s\ p); \\
& \quad at\ p\ l\ s; \\
& \quad AT\ s' = (AT\ s)(p := aft\ (\{l\}\ LocalOp\ f)\ (LST\ s\ p)); \\
& \quad LST\ s' = (LST\ s)(p := ps'); \\
& \quad hist\ s' = hist\ s \\
& \quad] \implies post\ s' \\
& \quad] \implies pgms, p, aft \models \{pre\} \{l\} \text{ LocalOp } f\ \{post\} \\
| \quad Cond1: [\bigwedge s\ s'. [pre\ s; \\
& \quad at\ p\ l\ s; \\
& \quad AT\ s' = (AT\ s)(p := aft\ (\{l\}\ IF\ b\ THEN\ t\ FI)\ (LST\ s\ p)); \\
& \quad LST\ s' = LST\ s; \\
& \quad hist\ s' = hist\ s \\
& \quad] \implies post\ s' \\
& \quad] \implies pgms, p, aft \models \{pre\} \{l\} \text{ IF } b\ THEN\ t\ FI\ \{post\} \\
| \quad Cond2: [\bigwedge s\ s'. [pre\ s; \\
& \quad at\ p\ l\ s; \\
& \quad AT\ s' = (AT\ s)(p := aft\ (\{l\}\ IF\ b\ THEN\ t\ ELSE\ e\ FI)\ (LST\ s\ p)); \\
& \quad LST\ s' = LST\ s; \\
& \quad hist\ s' = hist\ s \\
& \quad] \implies post\ s' \\
& \quad] \implies pgms, p, aft \models \{pre\} \{l\} \text{ IF } b\ THEN\ t\ ELSE\ e\ FI\ \{post\} \\
| \quad While: [\bigwedge s\ s'. [pre\ s; \\
& \quad at\ p\ l\ s; \\
& \quad AT\ s' = (AT\ s)(p := aft\ (\{l\}\ WHILE\ b\ DO\ c\ OD)\ (LST\ s\ p)); \\
& \quad LST\ s' = LST\ s; \\
& \quad hist\ s' = hist\ s \\
& \quad] \implies post\ s' \\
& \quad] \implies pgms, p, aft \models \{pre\} \{l\} \text{ WHILE } b\ DO\ c\ OD\ \{post\}
\end{aligned}$$

— There are no proof obligations for the following commands.

$$\begin{aligned}
| \quad Response: pgms, p, aft \models \{pre\} \{l\} \text{ Response action } \{post\} \\
| \quad Seq: pgms, p, aft \models \{pre\} c1 ;; c2 \{post\} \\
| \quad Loop: pgms, p, aft \models \{pre\} LOOP DO c OD \{post\} \\
| \quad Choose: pgms, p, aft \models \{pre\} c1 \sqcup c2 \{post\}
\end{aligned}$$

We abbreviate invariance with one-sided validity syntax.

abbreviation *valid-inv* $(-, -, - \models / \{-\} / -)$ **where**

$$pgms, p, aft \models \{I\} c \equiv pgms, p, aft \models \{I\} c \{I\} \langle proof \rangle \langle proof \rangle$$

We tweak *fragments* by omitting *Responses*, yielding fewer obligations.

fun

$$\begin{aligned}
vcg\text{-}fragments' & :: ('answer, 'location, 'question, 'state) com \\
& \Rightarrow ('location \Rightarrow bool) \\
& \Rightarrow (('answer, 'location, 'question, 'state) com
\end{aligned}$$

$\times ('answer, 'location, 'question, 'state) loc-comp) set$

where

$vcg_fragments' (\{l\} Response\ action) ls = \{ \}$
 $| vcg_fragments' (\{l\} IF\ b\ THEN\ c\ FI) ls$
 $\quad = vcg_fragments' c\ ls$
 $\quad \cup \{ (\{l\} IF\ b\ THEN\ c'\ FI, lcond\ (atC\ c)\ ls) | c'.\ True \}$
 $| vcg_fragments' (\{l\} IF\ b\ THEN\ c1\ ELSE\ c2\ FI) ls$
 $\quad = vcg_fragments' c2\ ls \cup vcg_fragments' c1\ ls$
 $\quad \cup \{ (\{l\} IF\ b\ THEN\ c1'\ ELSE\ c2'\ FI, lcond\ (atC\ c1)\ (atC\ c2)) | c1'\ c2'.\ True \}$
 $| vcg_fragments' (LOOP\ DO\ c\ OD) ls = vcg_fragments' c\ (atC\ c)$
 $| vcg_fragments' (\{l'\} WHILE\ b\ DO\ c\ OD) ls$
 $\quad = vcg_fragments' c\ (\lambda l. l = l') \cup \{ (\{l'\} WHILE\ b\ DO\ c'\ OD, lcond\ (atC\ c)\ ls) | c'.\ True \}$
 $| vcg_fragments' (c1\ ;;\ c2) ls = vcg_fragments' c2\ ls \cup vcg_fragments' c1\ (atC\ c2)$
 $| vcg_fragments' (c1\ \sqcup\ c2) ls = vcg_fragments' c1\ ls \cup vcg_fragments' c2\ ls$
 $| vcg_fragments' c\ ls = \{(c, lconst\ ls)\}$

abbreviation

$vcg_fragments :: ('answer, 'location, 'question, 'state) com$
 $\Rightarrow ('answer, 'location, 'question, 'state) com$
 $\times ('answer, 'location, 'question, 'state) loc-comp) set$

where

$vcg_fragments\ c \equiv vcg_fragments' c \langle False \rangle \langle proof \rangle \langle proof \rangle$

The user sees the conclusion of V for each element of $vcg_fragments$.

lemma VCG:

assumes $R: s \in reachable_states\ sys$
assumes $I: \forall s \in initial_states\ sys. I\ (mkP\ (s, []))$
assumes $V: \bigwedge p. \forall (c, afts) \in vcg_fragments\ (fst\ sys\ p). ((fst\ sys), p, afts \models \{I\}\ c)$
shows $I\ (mkP\ s) \langle proof \rangle$

2.5.1 VCG rules

We can develop some (but not all) of the familiar Hoare rules; see [Lamport \(1980\)](#) and the `seL4/l4.verified` lemma buckets for inspiration. We avoid many of the issues Lamport mentions as we only treat basic (atomic) commands.

context

fixes $pgms :: ('answer, 'location, 'proc, 'question, 'state) programs$
fixes $p :: 'proc$
fixes $afts :: ('answer, 'location, 'question, 'state) loc-comp$

begin

abbreviation

$valid_syn :: ('answer, 'location, 'proc, 'question, 'state) pred$
 $\Rightarrow ('answer, 'location, 'question, 'state) com$
 $\Rightarrow ('answer, 'location, 'proc, 'question, 'state) pred \Rightarrow bool$ **where**
 $valid_syn\ P\ c\ Q \equiv pgms, p, afts \models \{P\}\ c\ \{Q\}$

notation *valid-syn* ($\{\{-\}/ -/ \{-\}$)

abbreviation

valid-inv-syn :: ('answer, 'location, 'proc, 'question, 'state) pred
 \Rightarrow ('answer, 'location, 'question, 'state) com \Rightarrow bool **where**

valid-inv-syn P c \equiv $\{P\}$ c $\{P\}$

notation *valid-inv-syn* ($\{\{-\}/ -$)

lemma *vcg-True*:

$\{P\}$ c $\{\langle True \rangle\}$
 $\langle proof \rangle$

lemma *vcg-conj*:

$\llbracket \{I\}$ c $\{Q\}$; $\{I\}$ c $\{R\} \rrbracket \Longrightarrow \{I\}$ c $\{Q$ and $R\}$
 $\langle proof \rangle$

lemma *vcg-pre-imp*:

$\llbracket \bigwedge s. P s \Longrightarrow Q s$; $\{Q\}$ c $\{R\} \rrbracket \Longrightarrow \{P\}$ c $\{R\}$
 $\langle proof \rangle$

lemmas *vcg-pre* = *vcg-pre-imp*[rotated]

lemma *vcg-post-imp*:

$\llbracket \bigwedge s. Q s \Longrightarrow R s$; $\{P\}$ c $\{Q\} \rrbracket \Longrightarrow \{P\}$ c $\{R\}$
 $\langle proof \rangle$

lemma *vcg-prop*[intro]:

$\{\langle P \rangle\}$ c
 $\langle proof \rangle$

lemma *vcg-drop-imp*:

assumes $\{P\}$ c $\{Q\}$
shows $\{P\}$ c $\{R$ imp $Q\}$
 $\langle proof \rangle$

lemma *vcg-conj-lift*:

assumes x: $\{P\}$ c $\{Q\}$
assumes y: $\{P'\}$ c $\{Q'\}$
shows $\{P$ and $P'\}$ c $\{Q$ and $Q'\}$
 $\langle proof \rangle$

lemma *vcg-disj-lift*:

assumes x: $\{P\}$ c $\{Q\}$
assumes y: $\{P'\}$ c $\{Q'\}$
shows $\{P$ or $P'\}$ c $\{Q$ or $Q'\}$
 $\langle proof \rangle$

lemma *vcg-imp-lift*:
assumes $\{P'\} c \{not P\}$
assumes $\{Q'\} c \{Q\}$
shows $\{P' \text{ or } Q'\} c \{P \text{ imp } Q\}$
 $\langle proof \rangle$

lemma *vcg-ex-lift*:
assumes $\bigwedge x. \{P x\} c \{Q x\}$
shows $\{\lambda s. \exists x. P x s\} c \{\lambda s. \exists x. Q x s\}$
 $\langle proof \rangle$

lemma *vcg-all-lift*:
assumes $\bigwedge x. \{P x\} c \{Q x\}$
shows $\{\lambda s. \forall x. P x s\} c \{\lambda s. \forall x. Q x s\}$
 $\langle proof \rangle$

lemma *vcg-name-pre-state*:
assumes $\bigwedge s. P s \implies \{op = s\} c \{Q\}$
shows $\{P\} c \{Q\}$
 $\langle proof \rangle$

lemma *vcg-lift-comp*:
assumes $f: \bigwedge P. \{\lambda s. P (f s :: 'a :: type)\} c$
assumes $P: \bigwedge x. \{Q x\} c \{P x\}$
shows $\{\lambda s. Q (f s) s\} c \{\lambda s. P (f s) s\}$
 $\langle proof \rangle$

2.5.2 Cheap non-interference rules

These rules magically construct VCG lifting rules from the easier to prove *eq-imp* facts. We don't actually use these in the GC, but we do derive *fun-upd* equations using the same mechanism. Thanks to Thomas Sewell for the requisite syntax magic.

As these *eq-imp* facts do not usefully compose, we make the definition asymmetric (i.e., g does not get a bundle of parameters).

definition *eq-imp* :: $('a \Rightarrow 'b \Rightarrow 'c) \Rightarrow ('b \Rightarrow 'e) \Rightarrow bool$ **where**
 $eq-imp f g \equiv (\forall s s'. (\forall x. f x s = f x s') \longrightarrow (g s = g s'))$

lemma *eq-impD*:
 $\llbracket eq-imp f g; \forall x. f x s = f x s' \rrbracket \implies g s = g s'$
 $\langle proof \rangle$

lemma *eq-imp-vcg*:
assumes $g: eq-imp f g$
assumes $f: \forall x P. \{P \circ (f x)\} c$
shows $\{P \circ g\} c$
 $\langle proof \rangle$

lemma *eq-imp-vcg-LST*:
assumes $g: \text{eq-imp } f \ g$
assumes $f: \forall x \ P. \{P \circ (f \ x) \circ \text{LST}\} \ c$
shows $\{P \circ g \circ \text{LST}\} \ c$
 $\langle \text{proof} \rangle$

lemma *eq-imp-fun-upd*:
assumes $g: \text{eq-imp } f \ g$
assumes $f: \forall x. f \ x \ (s(\text{fld} := \text{val})) = f \ x \ s$
shows $g \ (s(\text{fld} := \text{val})) = g \ s$
 $\langle \text{proof} \rangle$

lemma *curry-forall-eq*:
 $(\forall f. P \ f) = (\forall f. P \ (\text{case-prod } f))$
 $\langle \text{proof} \rangle$

lemma *pres-tuple-vcg*:
 $(\forall P. \{P \circ (\lambda s. (f \ s, g \ s))\} \ c)$
 $\longleftrightarrow ((\forall P. \{P \circ f\} \ c) \wedge (\forall P. \{P \circ g\} \ c))$
 $\langle \text{proof} \rangle$

lemma *pres-tuple-vcg-LST*:
 $(\forall P. \{P \circ (\lambda s. (f \ s, g \ s)) \circ \text{LST}\} \ c)$
 $\longleftrightarrow ((\forall P. \{P \circ f \circ \text{LST}\} \ c) \wedge (\forall P. \{P \circ g \circ \text{LST}\} \ c))$
 $\langle \text{proof} \rangle$

lemmas *conj-explode = conj-imp-eq-imp-imp*

end
 $\langle \text{ML} \rangle$

3 One-place buffer example

To demonstrate the CIMP reasoning infrastructure, we treat the trivial one-place buffer example of Lamport and Schneider (1984, §3.3). Note that the semantics for our language is different to Lamport and Schneider's, who treated a historical variant of CSP (i.e., not the one in Hoare (1985)).

We introduce some syntax for fixed-topology (static channel-based) scenarios.

abbreviation

Receive $:: 'location \Rightarrow 'channel \Rightarrow ('val \Rightarrow 'state \Rightarrow 'state)$
 $\Rightarrow (\text{unit}, 'location, 'channel \times 'val, 'state) \text{ com } (\{-\} / \rightarrow)$

where

$\{l\} \text{ ch} \triangleright f \equiv \{l\} \text{ Response } (\lambda \text{quest } s. \text{if } \text{fst } \text{quest} = \text{ch} \text{ then } \{(f \ (\text{snd } \text{quest}) \ s, ())\} \text{ else } \{\})$

abbreviation

$Send :: 'location \Rightarrow 'channel \Rightarrow ('state \Rightarrow 'val)$
 $\Rightarrow (unit, 'location, 'channel \times 'val, 'state) com (\{\{-\}\} / \triangleleft)$

where

$\{\{l\}\} ch \triangleleft f \equiv \{\{l\}\} Request (\lambda s. (ch, f s)) (\lambda ans s. \{s\})$

We further specialise these for our particular example.

abbreviation

$Receive' :: 'location \Rightarrow 'channel \Rightarrow (unit, 'location, 'channel \times 'state, 'state) com (\{\{-\}\} / \triangleright)$

where

$\{\{l\}\} ch \triangleright \equiv \{\{l\}\} ch \triangleright (\lambda v -. v)$

abbreviation

$Send' :: 'location \Rightarrow 'channel \Rightarrow (unit, 'location, 'channel \times 'state, 'state) com (\{\{-\}\} / \triangleleft)$

where

$\{\{l\}\} ch \triangleleft \equiv \{\{l\}\} ch \triangleleft id$

These definitions largely follow [Lamport and Schneider \(1984\)](#). We have three processes communicating over two channels. We enumerate program locations.

datatype $ex-chname = \xi 12 \mid \xi 23$

type-synonym $ex-val = nat$

type-synonym $ex-ch = ex-chname \times ex-val$

datatype $ex-loc = r12 \mid r23 \mid s23 \mid s12$

datatype $ex-proc = p1 \mid p2 \mid p3$

type-synonym $ex-pgm = (unit, ex-loc, ex-ch, ex-val) com$

type-synonym $ex-pred = (unit, ex-loc, ex-proc, ex-ch, ex-val) pred$

type-synonym $ex-state = (unit, ex-loc, ex-proc, ex-ch, ex-val) global-state$

type-synonym $ex-system = (unit, ex-loc, ex-proc, ex-ch, ex-val) system$

type-synonym $ex-history = (ex-ch \times unit) list$

primrec

$ex-pgms :: ex-proc \Rightarrow ex-pgm$

where

$ex-pgms p1 = \{\{s12\}\} \xi 12 \triangleleft$

$\mid ex-pgms p2 = LOOP DO \{\{r12\}\} \xi 12 \triangleright;; \{\{s23\}\} \xi 23 \triangleleft OD$

$\mid ex-pgms p3 = \{\{r23\}\} \xi 23 \triangleright$

Each process starts with an arbitrary initial local state.

abbreviation $ex-init :: (ex-proc \Rightarrow ex-val) \Rightarrow bool$ **where**

$ex-init \equiv \langle True \rangle$

abbreviation $ex-system :: ex-system$ **where**

$ex-system \equiv (ex-pgms, ex-init)$

PeteG: I don't understand how [Lamport and Schneider](#) justify their invariants.

The following adapts Kai Engelhardt's, from his notes titled *Proving an Asynchronous Message Passing Program Correct*, 2011. The history variable tracks the causality of the system,

which I feel is missing in Lamport's treatment. We tack on Lamport's invariant so we can establish *Etern-pred*.

abbreviation

$filter\text{-}on\text{-}channel :: ex\text{-}chname \Rightarrow ex\text{-}history \Rightarrow ex\text{-}val\ list$

where

$filter\text{-}on\text{-}channel\ ch \equiv map\ (snd \circ fst) \circ filter\ (op = ch \circ fst \circ fst)$

definition $Ip1\text{-}0 :: ex\text{-}pred$ **where**

$Ip1\text{-}0 \equiv at\ p1\ s12\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi12\ (hist\ s) = [])$

definition $Ip1\text{-}1 :: ex\text{-}pred$ **where**

$Ip1\text{-}1 \equiv terminated\ p1\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi12\ (hist\ s) = [LST\ s\ p1])$

definition $Ip2\text{-}0 :: ex\text{-}pred$ **where**

$Ip2\text{-}0 \equiv at\ p2\ r12\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi12\ (hist\ s) = filter\text{-}on\text{-}channel\ \xi23\ (hist\ s))$

definition $Ip2\text{-}1 :: ex\text{-}pred$ **where**

$Ip2\text{-}1 \equiv at\ p2\ s23\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi12\ (hist\ s) = filter\text{-}on\text{-}channel\ \xi23\ (hist\ s))$
 $@ [LST\ s\ p2]$

$\wedge LST\ s\ p1 = LST\ s\ p2)$

definition $Ip3\text{-}0 :: ex\text{-}pred$ **where**

$Ip3\text{-}0 \equiv at\ p3\ r23\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi23\ (hist\ s) = [])$

definition $Ip3\text{-}1 :: ex\text{-}pred$ **where**

$Ip3\text{-}1 \equiv terminated\ p3\ imp\ (\lambda s. filter\text{-}on\text{-}channel\ \xi23\ (hist\ s) = [LST\ s\ p2])$
 $\wedge LST\ s\ p1 = LST\ s\ p3)$

definition $I\text{-}pred :: ex\text{-}pred$ **where**

$I\text{-}pred \equiv pred\text{-}conjoin\ [Ip1\text{-}0, Ip1\text{-}1, Ip2\text{-}0, Ip2\text{-}1, Ip3\text{-}0, Ip3\text{-}1]$

lemmas $I\text{-}defs = Ip1\text{-}0\text{-}def\ Ip1\text{-}1\text{-}def\ Ip2\text{-}0\text{-}def\ Ip2\text{-}1\text{-}def\ Ip3\text{-}0\text{-}def\ Ip3\text{-}1\text{-}def$

If process three terminates, then it has process one's value. This is stronger than [Lamport and Schneider](#)'s as we don't ask that the first process has also terminated.

definition $Etern\text{-}pred :: ex\text{-}pred$ **where**

$Etern\text{-}pred \equiv terminated\ p3\ imp\ (\lambda s. LST\ s\ p1 = LST\ s\ p3)$

Proofs from here down.

lemma *correct-system*:

$I\text{-}pred\ sh \implies Etern\text{-}pred\ sh$

$\langle proof \rangle$

lemma $p1$: $ex\text{-}pgms, p1, lconst\ \langle False \rangle \models \{I\text{-}pred\} \{s12\} \xi12 \triangleleft \lambda s. s$

$\langle proof \rangle$

lemma $p2\text{-}1$: $ex\text{-}pgms, p2, lconst\ (\lambda l. l = r12) \models \{I\text{-}pred\} \{s23\} \xi23 \triangleleft \lambda s. s$

$\langle proof \rangle$

lemma $(s, h) \in \text{reachable-states } \text{ex-system} \implies I\text{-pred } (\text{mkP } (s, h))$
 ⟨proof⟩

⟨proof⟩

4 Unbounded buffer example

This is more literally Kai's example from his notes titled *Proving an Asynchronous Message Passing Program Correct*, 2011.

datatype $\text{ex-chname} = \xi 12 \mid \xi 23$

type-synonym $\text{ex-val} = \text{nat}$

type-synonym $\text{ex-ls} = \text{ex-val list}$

type-synonym $\text{ex-ch} = \text{ex-chname} \times \text{ex-val}$

datatype $\text{ex-loc} = \pi 4 \mid \pi 5 \mid c1 \mid r12 \mid r23 \mid s23 \mid s12$

datatype $\text{ex-proc} = p1 \mid p2 \mid p3$

type-synonym $\text{ex-pgm} = (\text{unit}, \text{ex-loc}, \text{ex-ch}, \text{ex-ls}) \text{ com}$

type-synonym $\text{ex-pred} = (\text{unit}, \text{ex-loc}, \text{ex-proc}, \text{ex-ch}, \text{ex-ls}) \text{ pred}$

type-synonym $\text{ex-state} = (\text{unit}, \text{ex-loc}, \text{ex-proc}, \text{ex-ch}, \text{ex-ls}) \text{ global-state}$

type-synonym $\text{ex-system} = (\text{unit}, \text{ex-loc}, \text{ex-proc}, \text{ex-ch}, \text{ex-ls}) \text{ system}$

type-synonym $\text{ex-history} = (\text{ex-ch} \times \text{unit}) \text{ list}$

FIXME a bit fake: the local state for the producer process contains all values produced.

primrec $\text{ex-pgms} :: \text{ex-proc} \Rightarrow \text{ex-pgm} \text{ where}$

$\text{ex-pgms } p1 = \text{LOOP DO } \{\{c1\}\} \text{ LocalOp } (\lambda xs. \{ xs @ [x] \mid x. \text{True} \}) ;; \{\{s12\}\} \xi 12 \triangleleft \text{last OD}$
 $\mid \text{ex-pgms } p2 = \text{LOOP DO } \{\{r12\}\} \xi 12 \triangleright (\lambda x xs. xs @ [x])$

$\sqcup \{\{\pi 4\}\} \text{ IF } (\lambda s. \text{length } s > 0) \text{ THEN } \{\{s23\}\} \text{ Request } (\lambda s. (\xi 23, \text{hd } s))$
 $(\lambda ans s. \{\text{tl } s\}) \text{ FI}$

OD

$\mid \text{ex-pgms } p3 = \text{LOOP DO } \{\{r23\}\} \xi 23 \triangleright (\lambda x xs. xs @ [x]) \text{ OD}$

abbreviation $\text{ex-init} :: (\text{ex-proc} \Rightarrow \text{ex-ls}) \Rightarrow \text{bool} \text{ where}$

$\text{ex-init } f \equiv \forall p. f p = []$

abbreviation $\text{ex-system} :: \text{ex-system} \text{ where}$

$\text{ex-system} \equiv (\text{ex-pgms}, \text{ex-init})$

definition $\text{filter-on-channel} :: \text{ex-chname} \Rightarrow \text{ex-history} \Rightarrow \text{ex-val list} \text{ where}$

$\text{filter-on-channel } ch \equiv \text{map } (\text{snd} \circ \text{fst}) \circ \text{filter } (\text{op} = ch \circ \text{fst} \circ \text{fst})$

lemma $\text{filter-on-channel-simps} [\text{simp}]$:

$\text{filter-on-channel } ch [] = []$

$\text{filter-on-channel } ch (xs @ ys) = \text{filter-on-channel } ch xs @ \text{filter-on-channel } ch ys$

$\text{filter-on-channel } ch (((ch', v), \text{resp}) \# \text{vals}) = (\text{if } ch' = ch \text{ then } [v] \text{ else } []) @ \text{filter-on-channel } ch \text{ vals}$

⟨proof⟩

definition $Ip1-0$:: *ex-pred* **where**

$Ip1-0 \equiv \lambda s. \text{at } p1 \ c1 \ s \longrightarrow \text{filter-on-channel } \xi12 \ (\text{hist } s) = s \downarrow p1$

definition $Ip1-1$:: *ex-pred* **where**

$Ip1-1 \equiv \lambda s. \text{at } p1 \ s12 \ s \longrightarrow \text{length } (s \downarrow p1) > 0 \wedge \text{butlast } (s \downarrow p1) = \text{filter-on-channel } \xi12 \ (\text{hist } s)$

definition $Ip1-2$:: *ex-pred* **where**

$Ip1-2 \equiv \lambda s. \text{filter-on-channel } \xi12 \ (\text{hist } s) \leq s \downarrow p1$

definition $Ip2-0$:: *ex-pred* **where**

$Ip2-0 \equiv \lambda s. \text{filter-on-channel } \xi12 \ (\text{hist } s) = \text{filter-on-channel } \xi23 \ (\text{hist } s) @ s \downarrow p2$

definition $Ip2-1$:: *ex-pred* **where**

$Ip2-1 \equiv \lambda s. \text{at } p2 \ s23 \ s \longrightarrow \text{length } (s \downarrow p2) > 0$

definition $Ip3-0$:: *ex-pred* **where**

$Ip3-0 \equiv \lambda s. s \downarrow p3 = \text{filter-on-channel } \xi23 \ (\text{hist } s)$

definition $I\text{-pred}$:: *ex-pred* **where**

$I\text{-pred} \equiv \text{pred-conjoin } [Ip1-0, Ip1-1, Ip1-2, Ip2-0, Ip2-1, Ip3-0]$

lemmas $I\text{-defs} = I\text{-pred-def } Ip1-0\text{-def } Ip1-1\text{-def } Ip1-2\text{-def } Ip2-0\text{-def } Ip2-1\text{-def } Ip3-0\text{-def}$

The local state of $p3$ is some prefix of the local state of $p1$.

definition $Etern\text{-pred}$:: *ex-pred* **where**

$Etern\text{-pred} \equiv \lambda s. s \downarrow p3 \leq s \downarrow p1$

lemma *correct-system*:

$I\text{-pred } s \Longrightarrow Etern\text{-pred } s \langle \text{proof} \rangle \langle \text{proof} \rangle \langle \text{proof} \rangle \langle \text{proof} \rangle \langle \text{proof} \rangle$

lemma $s \in \text{reachable-states } \text{ex-system} \Longrightarrow I\text{-pred } (\text{mkP } s) \langle \text{proof} \rangle$

5 Concluding remarks

Previously Nipkow and Prensa Nieto (1999); Prensa Nieto (2002, 2003)² have developed the classical Owicki/Gries and Rely-Guarantee paradigms for the verification of shared-variable concurrent programs in Isabelle/HOL. These have been used to show the correctness of a garbage collector (Prensa Nieto and Esparza 2000).

We instead use synchronous message passing, which is significantly less explored. de Boer, de Roever, and Hannemann (1999); de Roever et al. (2001) provide compositional systems for *terminating* systems. We have instead adopted Lamport's paradigm of a single global invariant and local proof obligations as the systems we have in mind are tightly coupled and it is not obvious that the proofs would be easier on a decomposed system; see de Roever et al. (2001, §1.6.6) for a concurring opinion.

²The theories are in `$ISABELLE/src/HOL/Hoare_Parallel`.

Unlike the generic sequential program verification framework Simpl (Schirmer 2004), we do not support function calls, or a sophisticated account of state spaces. Moreover we do no meta-theory beyond showing the simple VCG is sound (§2.5).

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