Verified Approximation Algorithms

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Abstract

We present the first formal verifications of approximation algorithms for NP-complete optimization problems: vertex cover, set cover, independent set, center selection, load balancing, and bin packing. The proofs correct incompletnesses in existing proofs and improve the approximation ratio in one case. A detailed description of our work (excluding center selection) has been published in the proceedings of $IJCAR\ 2020\ [3]$.

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1 Vertex Cover

theory Approx-VC-Hoare imports HOL-Hoare.Hoare-Logic begin

The algorithm is classical, the proof is based on and augments the one by Berghammer and Müller-Olm [1].

1.1 Graph

A graph is simply a set of edges, where an edge is a 2-element set.

```
definition vertex-cover :: 'a set set \Rightarrow 'a set \Rightarrow bool where vertex-cover E C = (\forall e \in E. e \cap C \neq \{\})
```

abbreviation $matching :: 'a \ set \ set \Rightarrow bool \ \mathbf{where}$ $matching \ M \equiv pairwise \ disjnt \ M$

 $\mathbf{lemma}\ \mathit{card-matching-vertex-cover} :$

 $\llbracket \text{ finite } C; \text{ matching } M; M \subseteq E; \text{ vertex-cover } E \ C \ \rrbracket \Longrightarrow \operatorname{card} M \leq \operatorname{card} C \langle \operatorname{proof} \rangle$

1.2 The Approximation Algorithm

Formulated using a simple(!) predefined Hoare-logic. This leads to a stream-lined proof based on standard invariant reasoning.

The nondeterministic selection of an element from a set F is simulated by $SOME\ x.\ x\in F$. The SOME operator is built into HOL: $SOME\ x.\ P\ x$ denotes some x that satisfies P if such an x exists; otherwise it denotes an arbitrary element. Note that there is no actual nondeterminism involved: $SOME\ x.\ P\ x$ is some fixed element but in general we don't know which one. Proofs about SOME are notoriously tedious. Typically it involves showing first that $\exists\ x.\ P\ x.$ Then $\exists\ x.\ ?P\ x\implies ?P\ (SOME\ x.\ ?P\ x)$ implies $P\ (SOME\ x.\ P\ x)$. There are a number of (more) useful related theorems: just click on $\exists\ x.\ ?P\ x\implies ?P\ (SOME\ x.\ ?P\ x)$ to be taken there.

Convenient notation for choosing an arbitrary element from a set:

```
abbreviation some A \equiv SOME x. x \in A
locale Edges =
 fixes E :: 'a \ set \ set
 assumes finE: finite E
  assumes edges2: e \in E \Longrightarrow card \ e = 2
begin
    The invariant:
definition inv-matching C F M =
  (matching M \land M \subseteq E \land card \ C \leq 2 * card \ M \land (\forall e \in M. \ \forall f \in F. \ e \cap f =
{}))
definition invar :: 'a set \Rightarrow 'a set set \Rightarrow bool where
invar C F = (F \subseteq E \land vertex\text{-}cover (E-F) \ C \land finite \ C \land (\exists M. inv\text{-}matching \ C))
F(M)
    Preservation of the invariant by the loop body:
lemma invar-step:
  assumes F \neq \{\} invar C F
  shows invar (C \cup some\ F)\ (F - \{e' \in F.\ some\ F \cap e' \neq \{\}\})
\langle proof \rangle
lemma approx-vertex-cover:
VARS \ C \ F
  \{True\}
  C := \{\};
  F := E;
  WHILE F \neq \{\}
  INV \{invar \ C \ F\}
  DO \ C := C \cup some \ F;
     F := F - \{e' \in F. \text{ some } F \cap e' \neq \{\}\}
  \{vertex\text{-}cover\ E\ C\ \land\ (\forall\ C'.\ finite\ C'\ \land\ vertex\text{-}cover\ E\ C'\longrightarrow card\ C\leq 2*card
C')
\langle proof \rangle
end
1.3
        Version for Hypergraphs
```

Almost the same. We assume that the degree of every edge is bounded.

```
locale Bounded-Hypergraph =
  fixes E :: 'a \ set \ set
 fixes k :: nat
 assumes finE: finite E
 assumes edge-bnd: e \in E \Longrightarrow finite \ e \land card \ e \le k
  assumes E1: \{\} \notin E
```

```
begin
```

```
{\bf definition}\ inv\text{-}matching\ C\ F\ M\ =\ 
  (matching M \wedge M \subseteq E \wedge card \ C \leq k * card \ M \wedge (\forall e \in M. \ \forall f \in F. \ e \cap f = G)
{}))
definition invar: 'a set \Rightarrow 'a set set \Rightarrow bool where
\mathit{invar}\ C\ F = (F \subseteq E\ \land\ \mathit{vertex\text{-}cover}\ (E - F)\ C\ \land\ \mathit{finite}\ C\ \land\ (\exists\ M.\ \mathit{inv\text{-}matching}\ C
F(M)
\mathbf{lemma}\ invar\text{-}step\text{:}
  assumes F \neq \{\} invar C F
  shows invar (C \cup some\ F)\ (F - \{e' \in F.\ some\ F \cap e' \neq \{\}\})
\langle proof \rangle
\mathbf{lemma}\ approx\text{-}vertex\text{-}cover\text{-}bnd:
VARS C F
  \{True\}
  C := \{\};
  F := E;
  WHILE F \neq \{\}
  INV \{invar \ C \ F\}
  DO \ C := C \cup some \ F;
      F := F - \{e' \in F. \text{ some } F \cap e' \neq \{\}\}
  \{vertex\text{-}cover\ E\ C\ \land\ (\forall\ C'.\ finite\ C'\ \land\ vertex\text{-}cover\ E\ C'\longrightarrow card\ C\le k*card
C')
\langle proof \rangle
end
end
```

2 Set Cover

```
theory Approx-SC-Hoare
imports
HOL-Hoare.Hoare-Logic
Complex-Main
begin
```

This is a formalization of the set cover algorithm and proof in the book by Kleinberg and Tardos [4].

```
definition harm :: nat \Rightarrow 'a :: real-normed-field where harm n = (\sum k=1..n. inverse (of-nat k))
```

locale Set-Cover =

```
fixes w :: nat \Rightarrow real
    and m :: nat
    and S :: nat \Rightarrow 'a \ set
  assumes S-finite: \forall i \in \{1..m\}. finite (S i)
      and w-nonneg: \forall i. \ 0 \leq w \ i
begin
definition U :: 'a \ set \ \mathbf{where}
  U = (\bigcup i \in \{1..m\}. \ S \ i)
lemma S-subset: \forall i \in \{1..m\}. S \ i \subseteq U
  \langle proof \rangle
lemma U-finite: finite U
  \langle proof \rangle
lemma empty-cover: m = 0 \Longrightarrow U = \{\}
  \langle proof \rangle
definition sc :: nat \ set \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where}
  sc\ C\ X \longleftrightarrow C \subseteq \{1..m\} \land (\bigcup i \in C.\ S\ i) = X
definition cost :: 'a \ set \Rightarrow nat \Rightarrow real \ \mathbf{where}
  cost R i = w i / card (S i \cap R)
lemma cost-nonneg: 0 \le cost R i
     cost R i = 0 if card (S i \cap R) = 0! Needs to be accounted for separately
in min-arg.
fun min-arg :: 'a \ set \Rightarrow nat \Rightarrow nat \ where
  min-arg R \theta = 1
\mid min\text{-}arg\ R\ (Suc\ x) =
   (let j = min-arg R x)
    in if S j \cap R = \{\} \lor (S (Suc x) \cap R \neq \{\} \land cost R (Suc x) < cost R j) then
(Suc\ x)\ else\ j)
lemma min-in-range: k > 0 \Longrightarrow min-arg R \ k \in \{1..k\}
lemma min-empty: S (min-arg R k) \cap R = \{\} \Longrightarrow \forall i \in \{1..k\}. S i \cap R = \{\}
\langle proof \rangle
lemma min-correct: [i \in \{1..k\}; Si \cap R \neq \{\}]] \Longrightarrow cost R (min-arg R k) \leq cost
R i
\langle proof \rangle
```

```
lemma set-cover-correct:
VARS (R :: 'a set) (C :: nat set) (i :: nat)
  \{True\}
  R := U; C := \{\};
  WHILE R \neq \{\} INV \{R \subseteq U \land sc\ C\ (U-R)\} DO
  i := min-arg \stackrel{\frown}{R} m;
  R := R - S i;
  C:=\,C\,\cup\,\{i\}
  OD
  \{sc\ C\ U\}
\langle proof \rangle
definition c-exists :: nat \ set \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where}
  c-exists CR = (\exists c. sum \ w \ C = sum \ c \ (U - R) \land (\forall i. \ 0 \le c \ i)
                 \land (\forall k \in \{1..m\}. sum \ c \ (S \ k \cap (U - R))
                     \leq (\sum j = card (S k \cap R) + 1..card (S k). inverse j) * w k))
definition inv :: nat \ set \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where}
  inv \ C \ R \longleftrightarrow sc \ C \ (U - R) \land R \subseteq U \land c\text{-exists} \ C \ R
lemma invI:
  assumes sc\ C\ (U-R)\ R\subseteq U
          \exists c. sum \ w \ C = sum \ c \ (U - R) \land (\forall i. \ 0 \le c \ i)
        \land (\forall k \in \{1..m\}. \ sum \ c \ (S \ k \cap (U - R)))
                        \leq (\sum j = card (S k \cap R) + 1...card (S k). inverse j) * w k)
    shows inv C R \langle proof \rangle
lemma invD:
  assumes inv \ C \ R
  shows sc\ C\ (U-R)\ R\subseteq U
        \exists \ c. \ sum \ w \ C = sum \ c \ (U - R) \land (\forall \ i. \ 0 \le c \ i)
      \wedge \ (\forall k \in \{1..m\}. \ sum \ c \ (S \ k \cap (U - R))
                      \leq (\sum j = card (S k \cap R) + 1..card (S k). inverse j) * w k)
  \langle proof \rangle
lemma inv-init: inv {} U
\langle proof \rangle
lemma inv-step:
  assumes inv C R R \neq \{\}
  defines [simp]: i \equiv min-arg R m
  shows inv (C \cup \{i\}) (R - (S i))
\langle proof \rangle
lemma cover-sum:
  fixes c :: 'a \Rightarrow real
  assumes sc\ C\ V\ \forall\,i.\ 0\leq c\ i
  shows sum c \ V \le (\sum i \in C. \ sum \ c \ (S \ i))
\langle proof \rangle
```

```
abbreviation H :: nat \Rightarrow real where H \equiv harm
definition d-star :: nat (\langle d^* \rangle) where d^* \equiv Max (card '(S' \{1...m\}))
lemma set-cover-bound:
 assumes inv \ C \ \{\} \ sc \ C' \ U
 shows sum \ w \ C \le H \ d^* * sum \ w \ C'
\langle proof \rangle
theorem set-cover-approx:
VARS (R :: 'a set) (C :: nat set) (i :: nat)
  \{True\}
  R := U; C := \{\};
  WHILE R \neq \{\} INV \{inv \ C \ R\} DO
  i := min\text{-}arg R m;
  R := R - S i;
  C := C \cup \{i\}
  OD
  \{sc\ C\ U\ \land\ (\forall\ C'.\ sc\ C'\ U\longrightarrow sum\ w\ C\leq H\ d^**sum\ w\ C')\}
\langle proof \rangle
end
end
```

3 Independent Set

```
theory Approx-MIS-Hoare
imports
HOL-Hoare.Hoare-Logic
HOL-Library.Disjoint-Sets
begin
```

The algorithm is classical, the proofs are inspired by the ones by Berghammer and Müller-Olm [1]. In particular the approximation ratio is improved from $\Delta+1$ to Δ .

3.1 Graph

A set set is simply a set of edges, where an edge is a 2-element set.

```
definition independent-vertices :: 'a set set \Rightarrow 'a set \Rightarrow bool where independent-vertices E \ S \longleftrightarrow S \subseteq \bigcup E \land (\forall \ v1 \ v2. \ v1 \in S \land v2 \in S \longrightarrow \{v1, \ v2\} \notin E)
```

```
 \begin{aligned} &\textbf{locale} \ \textit{Graph-E} = \\ &\textbf{fixes} \ \textit{E} :: 'a \ \textit{set} \ \textit{set} \\ &\textbf{assumes} \ \textit{finite-E} : \textit{finite} \ \textit{E} \end{aligned}
```

```
assumes edges2: e \in E \Longrightarrow card \ e = 2
begin
fun vertices :: 'a set set \Rightarrow 'a set where
vertices G = \bigcup G
abbreviation V :: 'a \ set \ where
V \equiv vertices E
definition approximation-miv :: nat \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where}
approximation\text{-}miv\;n\;S\longleftrightarrow independent\text{-}vertices\;E\;S\;\wedge\;(\forall\;S'.\;independent\text{-}vertices
E S' \longrightarrow card S' \leq card S * n
fun neighbors :: 'a \Rightarrow 'a \ set \ \mathbf{where}
neighbors v = \{u, \{u,v\} \in E\}
fun degree-vertex :: 'a \Rightarrow nat where
degree\text{-}vertex\ v=card\ (neighbors\ v)
abbreviation \Delta :: nat where
\Delta \equiv Max\{degree\text{-}vertex\ u|u.\ u\in V\}
lemma finite-edges: e \in E \Longrightarrow finite e
  \langle proof \rangle
lemma finite-V: finite V
  \langle proof \rangle
lemma finite-neighbors: finite (neighbors u)
  \langle proof \rangle
lemma independent-vertices-finite: independent-vertices E S \Longrightarrow finite S
  \langle proof \rangle
lemma edge-ex-vertices: e \in E \Longrightarrow \exists u \ v. \ u \neq v \land e = \{u, v\}
\langle proof \rangle
lemma \Delta-pos [simp]: E = \{\} \lor 0 < \Delta
\langle proof \rangle
lemma \Delta-max-degree: u \in V \Longrightarrow degree-vertex u \leq \Delta
\langle proof \rangle
```

3.2 Wei's algorithm: $(\Delta+1)$ -approximation

The 'functional' part of the invariant, used to prove that the algorithm produces an independent set of vertices.

```
definition inv-iv :: 'a set \Rightarrow 'a set \Rightarrow bool where inv-iv S \ X \longleftrightarrow independent-vertices <math>E \ S
```

Strenghten the invariant with an approximation ratio r:

```
definition inv-approx :: 'a set \Rightarrow 'a set \Rightarrow nat \Rightarrow bool where inv-approx S \ X \ r \longleftrightarrow inv-iv \ S \ X \land card \ X \le card \ S * r
```

Preservation of the functional invariant:

```
lemma inv-preserv:
 fixes S :: 'a \ set
   and X :: 'a \ set
   and x :: 'a
 assumes inv: inv-iv S X
     and x-def: x \in V - X
   shows inv-iv (insert x S) (X \cup neighbors x \cup \{x\})
\langle proof \rangle
lemma inv-approx-preserv:
 assumes inv: inv-approx S X (\Delta + 1)
     and x-def: x \in V - X
   shows inv-approx (insert x S) (X \cup neighbors x \cup \{x\}) (\Delta + 1)
\langle proof \rangle
lemma inv-approx: independent-vertices E S \Longrightarrow card \ V \le card \ S * r \Longrightarrow ap
proximation-miv r S
\langle proof \rangle
theorem wei-approx-\Delta-plus-1:
VARS (S :: 'a set) (X :: 'a set) (x :: 'a)
  { True }
 S := \{\};
 X := \{\};
  WHILE\ X \neq V
  INV \{ inv-approx S X (\Delta + 1) \}
  DO x := (SOME x. x \in V - X);
    S := insert \ x \ S;
    X := X \cup neighbors \ x \cup \{x\}
  \{ approximation-miv (\Delta + 1) S \}
```

3.3 Wei's algorithm: Δ -approximation

 $\langle proof \rangle$

The previous approximation uses very little information about the optimal solution (it has at most as many vertices as the set itself). With some extra effort we can improve the ratio to Δ instead of $\Delta+1$. In order to do that we must show that among the vertices removed in each iteration, at most Δ

could belong to an optimal solution. This requires carrying around a set P (via a ghost variable) which records the vertices deleted in each iteration.

```
definition inv-partition :: 'a set \Rightarrow 'a set \Rightarrow 'a set set \Rightarrow bool where
inv-partition S X P \longleftrightarrow inv-iv S X
                       \wedge \bigcup P = X
                        \land \ (\forall \ p \in P. \ \exists \ s \in V. \ p = \{s\} \cup \ neighbors \ s)
                        \land \ \mathit{card} \ P = \mathit{card} \ S
                        \land finite P
\mathbf{lemma}\ inv\text{-}partition\text{-}preserv:
  assumes inv: inv-partition S X P
      and x-def: x \in V - X
      shows inv-partition (insert x S) (X \cup neighbors x \cup \{x\}) (insert (\{x\} \cup x)
neighbors x) P)
\langle proof \rangle
\mathbf{lemma}\ \mathit{card}\text{-}\mathit{Union}\text{-}\mathit{le}\text{-}\mathit{sum}\text{-}\mathit{card}\text{:}
  fixes U :: 'a \ set \ set
  assumes \forall u \in U. finite u
  shows card (\bigcup U) \leq sum \ card \ U
\langle proof \rangle
lemma sum-card:
  fixes U :: 'a \ set \ set
    and n :: nat
  assumes \forall S \in U. card S \leq n
  shows sum \ card \ U \leq card \ U * n
\langle proof \rangle
lemma x-or-neighbors:
  fixes P :: 'a \ set \ set
    and S :: 'a \ set
  assumes inv: \forall p \in P. \exists s \in V. p = \{s\} \cup neighbors s
      and ivS: independent-vertices E S
    shows \forall p \in P. card (S \cap p) \leq \Delta
\langle proof \rangle
lemma inv-partition-approx: inv-partition S \ V \ P \Longrightarrow approximation-miv \ \Delta \ S
\langle proof \rangle
theorem wei-approx-\Delta:
VARS (S :: 'a set) (X :: 'a set) (x :: 'a)
  { True }
  S := \{\};
  X := \{\};
  WHILE X \neq V
```

```
INV \ \{ \ \exists \ P. \ inv-partition \ S \ X \ P \ \} \\ DO \ x := (SOME \ x. \ x \in V - X); \\ S := insert \ x \ S; \\ X := X \cup neighbors \ x \cup \{x\} \\ OD \\ \{ \ approximation-miv \ \Delta \ S \ \} \\ \langle proof \rangle
```

3.4 Wei's algorithm with dynamically computed approximation ratio

In this subsection, we augment the algorithm with a variable used to compute the effective approximation ratio of the solution. In addition, the vertex of smallest degree is picked. With this heuristic, the algorithm achieves an approximation ratio of $(\Delta+2)/3$, but this is not proved here.

```
definition vertex-heuristic :: 'a set \Rightarrow 'a \Rightarrow bool where vertex-heuristic X v = (\forall u \in V - X. \ card \ (neighbors \ v - X) \leq card \ (neighbors \ u - X))
```

```
lemma ex-min-finite-set:
  fixes S :: 'a \ set
   and f :: 'a \Rightarrow nat
   shows finite S \Longrightarrow S \neq \{\} \Longrightarrow \exists x. \ x \in S \land (\forall y \in S. \ f \ x \leq f \ y)
         (is ?P1 \implies ?P2 \implies \exists x. ?minf S x)
\langle proof \rangle
lemma inv-approx-preserv2:
  fixes S :: 'a \ set
   and X :: 'a \ set
   and s :: nat
   and x :: 'a
  assumes inv: inv-approx S X s
     and x-def: x \in V - X
   shows inv-approx (insert x S) (X \cup neighbors x \cup \{x\}) (max (card (neighbors
x \cup \{x\} - X) s
\langle proof \rangle
theorem wei-approx-min-degree-heuristic:
VARS (S :: 'a set) (X :: 'a set) (x :: 'a) (r :: nat)
  { True }
  S := \{\};
  X := \{\};
  r := \theta;
  WHILE X \neq V
  INV \{ inv-approx S X r \}
  DO x := (SOME x. x \in V - X \land vertex-heuristic X x);
    S := insert \ x \ S;
```

```
\begin{array}{l} r:=\max\;(card\;(neighbors\;x\cup\{x\}-X))\;r;\\ X:=X\cup neighbors\;x\cup\{x\}\\ OD\\ \{\;approximation\text{-}miv\;r\;S\;\}\\ \langle proof\rangle \end{array} end end
```

4 Load Balancing

```
theory Approx-LB-Hoare imports Complex-Main HOL—Hoare.Hoare-Logic begin
```

This is a formalization of the load balancing algorithms and proofs in the book by Kleinberg and Tardos [4].

hide-const (open) sorted

```
lemma sum-le-card-Max: \llbracket finite A; A \neq \{\} \rrbracket \implies sum f A \leq card A * Max (f ')
A)
\langle proof \rangle
lemma Max\text{-}const[simp]: [ finite\ A;\ A \neq \{\} ]] \Longrightarrow Max\ ((\lambda -.\ c)\ `A) = c
\langle proof \rangle
abbreviation Max_0 :: nat \ set \Rightarrow nat \ where
Max_0 \ N \equiv (if \ N = \{\} \ then \ 0 \ else \ Max \ N)
fun f-Max_0 :: (nat \Rightarrow nat) \Rightarrow nat \Rightarrow nat where
  f-Max_0 f \theta = \theta
| f\text{-}Max_0 f (Suc x) = max (f (Suc x)) (f\text{-}Max_0 f x)
lemma f-Max_0-equiv: f-Max_0 f n = Max_0 (f ` \{1..n\})
  \langle proof \rangle
lemma f-Max_0-correct:
  \forall x \in \{1..m\}. \ T \ x \leq f\text{-}Max_0 \ T \ m
  m > 0 \Longrightarrow \exists x \in \{1..m\}. \ T \ x = f\text{-}Max_0 \ T \ m
   \langle proof \rangle
lemma f-Max_0-mono:
  y \le T x \Longrightarrow f\text{-}Max_0 \ (T \ (x := y)) \ m \le f\text{-}Max_0 \ T \ m
  T \ x \leq y \Longrightarrow f\text{-}Max_0 \ T \ m \leq f\text{-}Max_0 \ (T \ (x := y)) \ m
  \langle proof \rangle
lemma f-Max_0-out-of-range [simp]:
```

```
x \notin \{1..k\} \Longrightarrow f\text{-}Max_0 \ (T \ (x := y)) \ k = f\text{-}Max_0 \ T \ k \langle proof \rangle lemma fun\text{-}upd\text{-}f\text{-}Max_0: assumes x \in \{1..m\} \ T \ x \leq y shows f\text{-}Max_0 \ (T \ (x := y)) \ m = max \ y \ (f\text{-}Max_0 \ T \ m) \langle proof \rangle locale LoadBalancing = fixes t :: nat \Rightarrow nat and m :: nat and n :: nat assumes m\text{-}gt\text{-}\theta : m > \theta begin
```

4.1 Formalization of a Correct Load Balancing

4.1.1 Definition

```
definition lb :: (nat \Rightarrow nat) \Rightarrow (nat \Rightarrow nat \ set) \Rightarrow nat \Rightarrow bool \ \mathbf{where}
  lb T A j = ((\forall x \in \{1..m\}. \ \forall y \in \{1..m\}. \ x \neq y \longrightarrow A \ x \cap A \ y = \{\}) — No job
is assigned to more than one machine
               \wedge (\bigcup x \in \{1..m\}. \ A \ x) = \{1..j\} — Every job is assigned
               \land (\forall x \in \{1..m\}. (\sum j \in A \ x. \ t \ j) = T \ x) — The processing times sum
up to the correct load)
abbreviation makespan :: (nat \Rightarrow nat) \Rightarrow nat where
  makespan T \equiv f\text{-}Max_0 T m
\mathbf{lemma}\ \mathit{makespan-def':}\ \mathit{makespan}\ \mathit{T} = \mathit{Max}\ (\mathit{T}\ `\{1..m\})
  \langle proof \rangle
lemma makespan-correct:
  \forall x \in \{1..m\}. T x \leq makespan T
  \exists x \in \{1..m\}. \ T \ x = makespan \ T
  \langle proof \rangle
lemma lbE:
  assumes lb T A j
  shows \forall x \in \{1..m\}. \ \forall y \in \{1..m\}. \ x \neq y \longrightarrow A \ x \cap A \ y = \{\}
         (\bigcup x \in \{1..m\}. \ A \ x) = \{1..j\}
         \forall x \in \{1..m\}. (\sum y \in A x. t y) = T x
  \langle proof \rangle
lemma lbI:
  assumes \forall x \in \{1..m\}. \ \forall y \in \{1..m\}. \ x \neq y \longrightarrow A \ x \cap A \ y = \{\}
            (\bigcup x \in \{1..m\}. \ A \ x) = \{1..j\}
            \forall x \in \{1..m\}. (\sum y \in A \ x. \ t \ y) = T \ x
  shows lb \ T \ A \ j \ \langle proof \rangle
```

```
lemma A-lb-finite [simp]:
assumes lb T A j x \in \{1..m\}
shows finite (A x)
\langle proof \rangle
```

If A x is pairwise disjoint for all $x \in \{1..m\}$, then the sum over the sums of the individual A x is equal to the sum over the union of all A x.

lemma sum-sum-eq-sum-Un:

```
fixes A :: nat \Rightarrow nat \ set assumes \forall x \in \{1..m\}. \ \forall y \in \{1..m\}. \ x \neq y \longrightarrow A \ x \cap A \ y = \{\} and \forall x \in \{1..m\}. \ finite \ (A \ x) shows (\sum x \in \{1..m\}. \ (\sum y \in A \ x. \ t \ y)) = (\sum x \in (\bigcup y \in \{1..m\}. \ A \ y). \ t \ x) \langle proof \rangle
```

If T and A are a correct load balancing for j jobs and m machines, then the sum of the loads has to be equal to the sum of the processing times of the jobs

```
lemma lb-impl-job-sum:
assumes lb T A j
shows (\sum x \in \{1..m\}, T x) = (\sum x \in \{1..j\}, t x)
\langle proof \rangle
```

4.1.2 Lower Bounds for the Makespan

If T and A are a correct load balancing for j jobs and m machines, then the processing time of any job $x \in \{1..j\}$ is a lower bound for the load of some machine $y \in \{1..m\}$

```
lemma job-lower-bound-machine: assumes lb\ T\ A\ j\ x \in \{1..j\} shows \exists\ y \in \{1..m\}.\ t\ x \le T\ y \langle proof \rangle
```

As the load of any machine is a lower bound for the makespan, the processing time of any job $x \in \{1..j\}$ has to also be a lower bound for the makespan. Follows from job-lower-bound-machine and makespan-correct.

 ${\bf lemma}\ job{-}lower{-}bound{-}makespan:$

```
assumes lb \ T \ A \ j \ x \in \{1..j\}
shows t \ x \le makespan \ T
\langle nroof \rangle
```

The makespan over j jobs is a lower bound for the makespan of any correct load balancing for j jobs.

```
lemma max-job-lower-bound-makespan:
assumes lb\ T\ A\ j
shows Max_0\ (t\ `\{1..j\}) \le makespan\ T
\langle proof \rangle
```

```
lemma job-dist-lower-bound-makespan: assumes lb\ T\ A\ j shows (\sum x \in \{1..j\}.\ t\ x)\ /\ m \le makespan\ T\ \langle proof \rangle
```

4.2 The Greedy Approximation Algorithm

This function will perform a linear scan from $k \in \{1..m\}$ and return the index of the machine with minimum load assuming m > 0

```
index of the machine with minimum load assuming m > 0
fun min-arg :: (nat \Rightarrow nat) \Rightarrow nat \Rightarrow nat where
  min-arg T \theta = 1
\mid min\text{-}arg\ T\ (Suc\ x) =
   (\mathit{let}\ k = \mathit{min}\text{-}\mathit{arg}\ T\ x
    in if T (Suc x) < T k then (Suc x) else k)
lemma min-correct:
 \forall x \in \{1..m\}. \ T \ (min\text{-}arg \ T \ m) \leq T \ x
  \langle proof \rangle
lemma min-in-range:
  k > 0 \Longrightarrow (min\text{-}arg\ T\ k) \in \{1..k\}
  \langle proof \rangle
lemma add-job:
 assumes lb \ T \ A \ j \ x \in \{1..m\}
  shows lb (T (x := T x + t (Suc j))) (A (x := A x \cup \{Suc j\})) (Suc j)
    (is \langle lb ?T ?A \rightarrow \rangle)
\langle proof \rangle
lemma makespan-mono:
  y \le T x \Longrightarrow makespan (T (x := y)) \le makespan T
  T \ x \leq y \Longrightarrow makespan \ T \leq makespan \ (T \ (x := y))
  \langle proof \rangle
lemma smaller-optimum:
  assumes lb \ T \ A \ (Suc \ j)
 shows \exists T' A'. b T' A' j \land makespan T' \leq makespan T
\langle proof \rangle
    If the processing time y does not contribute to the makespan, we can
ignore it.
lemma remove-small-job:
  assumes makespan (T(x := Tx + y)) \neq Tx + y
  shows makespan (T (x := T x + y)) = makespan T
\langle proof \rangle
lemma greedy-makespan-no-jobs [simp]:
  makespan (\lambda -. \theta) = \theta
  \langle proof \rangle
```

```
lemma min-avg: m * T (min-arg T m) \leq (\sum i \in \{1..m\}, T i)
            (\mathbf{is} \leftarrow * ?T \leq ?S)
\langle proof \rangle
definition inv_1 :: (nat \Rightarrow nat) \Rightarrow (nat \Rightarrow nat \ set) \Rightarrow nat \Rightarrow bool \ \mathbf{where}
  inv_1 \ T \ A \ j = (lb \ T \ A \ j \ \land j \le n \ \land (\forall \ T' \ A'. \ lb \ T' \ A' \ j \longrightarrow makespan \ T \le 2 \ *
makespan T')
lemma inv_1E:
  assumes inv_1 T A j
  shows lb \ T \ A \ j \ j \le n
        lb\ T'\ A'\ j \Longrightarrow makespan\ T \le 2* makespan\ T'
  \langle proof \rangle
lemma inv_1I:
 assumes lb\ T\ A\ j\ j \le n\ \forall\ T'\ A'.\ lb\ T'\ A'\ j \longrightarrow makespan\ T \le 2* makespan\ T'
  shows inv_1 \ T \ A \ j \ \langle proof \rangle
lemma inv_1-step:
  assumes inv_1 T A j j < n
  shows inv_1 (T ((min-arg T m) := T (min-arg T m) + t (Suc j)))
               (A ((min-arg \ T \ m) := A (min-arg \ T \ m) \cup \{Suc \ j\})) (Suc \ j)
    (is \langle inv_1 ?T ?A \rightarrow \rangle)
\langle proof \rangle
lemma simple-greedy-approximation:
VARS T A i j
\{True\}
T := (\lambda - . \ \theta);
A := (\lambda -. \{\});
j := 0;
WHILE j < n \text{ INV } \{inv_1 \text{ } T \text{ } A \text{ } j\} \text{ } DO
  i := min-arg T m;
 j := (Suc \ j);
  A := A \ (i := A(i) \cup \{j\});
  T := T (i := T(i) + t j)
\{lb\ T\ A\ n \land (\forall\ T'\ A'.\ lb\ T'\ A'\ n \longrightarrow makespan\ T \leq 2 * makespan\ T')\}
\langle proof \rangle
definition sorted :: nat \Rightarrow bool where
  sorted j = (\forall x \in \{1..j\}. \ \forall y \in \{1..x\}. \ t \ x \le t \ y)
lemma sorted-smaller [simp]: [sorted j; j \ge j'] \implies sorted j'
  \langle proof \rangle
lemma j-gt-m-pigeonhole:
  assumes lb T A j j > m
```

```
shows \exists x \in \{1..j\}. \exists y \in \{1..j\}. \exists z \in \{1..m\}. x \neq y \land x \in A \ z \land y \in A \ z \land y
```

If T and A are a correct load balancing for j jobs and m machines with j > m, and the jobs are sorted in descending order, then there exists a machine $x \in \{1..m\}$ whose load is at least twice as large as the processing time of job j.

```
{f lemma}\ sorted-job-lower-bound-machine:
  assumes lb T A j j > m  sorted j
  shows \exists x \in \{1..m\}. \ 2 * t j \leq T x
     Reasoning analogous to job-lower-bound-makespan.
lemma sorted-job-lower-bound-makespan:
  assumes lb T A j j > m sorted j
  shows 2 * t j \leq makespan T
\langle proof \rangle
lemma min-zero:
 assumes x \in \{1..k\} T x = 0
  shows T (min-arg T k) = \theta
  \langle proof \rangle
lemma min-zero-index:
  assumes x \in \{1..k\} T x = 0
  shows min-arg T k \leq x
  \langle proof \rangle
definition inv_2 :: (nat \Rightarrow nat) \Rightarrow (nat \Rightarrow nat set) \Rightarrow nat \Rightarrow bool where
  inv_2 \ T \ A \ j = (lb \ T \ A \ j \land j \le n
                \land (\forall T' A'. lb \ T' A' j \longrightarrow makespan \ T \leq 3 / 2 * makespan \ T')
                \wedge \ (\forall x > j. \ T \ x = 0)
                \land (j \leq m \longrightarrow makespan \ T = Max_0 \ (t \ `\{1..j\})))
lemma inv_2E:
  assumes inv_2 T A j
  shows lb \ T \ A \ j \ j \le n
        lb\ T'\ A'\ j \Longrightarrow makespan\ T \le 3\ /\ 2*makespan\ T'
        \forall x > j. T x = 0 \ j \le m \Longrightarrow makespan \ T = Max_0 \ (t `\{1..j\})
  \langle proof \rangle
lemma inv_2I:
  assumes lb \ T \ A \ j \ j \le n
          \forall T' A'. \ lb \ T' A' j \longrightarrow makespan \ T \leq 3 \ / \ 2 * makespan \ T'
          \forall \, x>j. \ T \ x=0
          j \leq m \Longrightarrow makespan \ T = Max_0 \ (t ` \{1..j\})
  shows inv_2 T A j
  \langle proof \rangle
```

```
lemma inv_2-step:
  assumes sorted \ n \ inv_2 \ T \ A \ j \ j < n
  \mathbf{shows} \ inv_2 \ (\textit{T} \ (\textit{min-arg} \ \textit{T} \ \textit{m} := \textit{T}(\textit{min-arg} \ \textit{T} \ \textit{m}) + \textit{t}(\textit{Suc} \ \textit{j})))
                  (A (min-arg \ T \ m := A(min-arg \ T \ m) \cup \{Suc \ j\})) (Suc \ j)
     (is \langle inv_2 ?T ?A \rightarrow \rangle)
\langle proof \rangle
lemma sorted-greedy-approximation:
sorted n \Longrightarrow VARS \ T \ A \ i \ j
\{True\}
T := (\lambda - . \ \theta);
A := (\lambda -. \{\});
j := 0;
WHILE j < n \text{ INV } \{inv_2 \text{ } T \text{ } A \text{ } j\} \text{ } DO
  i := min-arg T m;
  j := (Suc \ j);
  A := A \ (i := A(i) \cup \{j\});
   T := T (i := T(i) + t j)
\{lb\ T\ A\ n \land (\forall\ T'\ A'.\ lb\ T'\ A'\ n \longrightarrow makespan\ T \leq 3\ /\ 2*makespan\ T')\}
\langle proof \rangle
end
```

5 Bin Packing

end

```
{\bf theory}\ Approx-BP-Hoare\\ {\bf imports}\ Complex-Main\ HOL-Hoare. Hoare-Logic\ HOL-Library. Disjoint-Sets\\ {\bf begin}
```

The algorithm and proofs are based on the work by Berghammer and Reuter [2].

5.1 Formalization of a Correct Bin Packing

Definition of the unary operator $[\cdot]$ from the article. B will only be wrapped into a set if it is non-empty.

```
definition wrap :: 'a \ set \Rightarrow 'a \ set \ set where wrap \ B = (if \ B = \{\} \ then \ \{\} \ else \ \{B\})
lemma wrap\text{-}card : card \ (wrap \ B) \le 1 \langle proof \rangle
```

If M and N are pairwise disjoint with V and not yet contained in V, then the union of M and N is also pairwise disjoint with V.

```
lemma pairwise-disjnt-Un:
 assumes pairwise disjnt (\{M\} \cup \{N\} \cup V) \ M \notin V \ N \notin V
 shows pairwise disjnt (\{M \cup N\} \cup V)
    A Bin Packing Problem is defined like in the article:
locale BinPacking =
 fixes U :: 'a \ set — A finite, non-empty set of objects
    and w :: 'a \Rightarrow real — A mapping from objects to their respective weights
(positive real numbers)
   and c :: nat — The maximum capacity of a bin (a natural number)
   and S: 'a set — The set of small objects (weight no larger than 1/2 of c)
   and L :: 'a \ set — The set of large objects (weight larger than 1/2 of c)
 assumes weight: \forall u \in U. \ 0 < w(u) \land w(u) \leq c
     and U-Finite: finite U
     and U-NE: U \neq \{\}
    and S-def: S = \{u \in U. \ w(u) \le c / 2\}
    and L-def: L = U - S
begin
```

In the article, this is defined as w as well. However, to avoid ambiguity, we will abbreviate the weight of a bin as W.

```
abbreviation W :: 'a \ set \Rightarrow real \ \mathbf{where} W \ B \equiv (\sum u \in B. \ w(u))
```

P constitutes as a correct bin packing if P is a partition of U (as defined in partition-on-def) and the weights of the bins do not exceed their maximum capacity c.

```
\begin{array}{l} \textbf{definition} \ bp :: 'a \ set \ set \ \Rightarrow \ bool \ \textbf{where} \\ bp \ P \longleftrightarrow partition\text{-}on \ U \ P \land (\forall B \in P. \ W(B) \leq c) \\ \\ \textbf{lemma} \ bpE: \\ \textbf{assumes} \ bp \ P \\ \textbf{shows} \ pairwise \ disjnt \ P \ \{\} \notin P \ \bigcup P = U \ \forall B \in P. \ W(B) \leq c \\ \langle proof \rangle \\ \\ \textbf{lemma} \ bpI: \\ \textbf{assumes} \ pairwise \ disjnt \ P \ \{\} \notin P \ \bigcup P = U \ \forall B \in P. \ W(B) \leq c \\ \textbf{shows} \ bp \ P \\ \langle proof \rangle \end{array}
```

Although we assume the S and L sets as given, manually obtaining them from U is trivial and can be achieved in linear time. Proposed by the article [2].

```
lemma S-L-set-generation:

VARS \ S \ L \ W \ u

\{True\}

S := \{\}; \ L := \{\}; \ W := U;

WHILE \ W \neq \{\}
```

```
INV \ \{W \subseteq U \land S = \{v \in U - W. \ w(v) \le c \ / \ 2\} \land L = \{v \in U - W. \ w(v) > c \ / \ 2\} \} \ DO
u := (SOME \ u. \ u \in W);
IF \ 2 * w(u) \le c
THEN \ S := S \cup \{u\}
ELSE \ L := L \cup \{u\} \ FI;
W := W - \{u\}
OD
\{S = \{v \in U. \ w(v) \le c \ / \ 2\} \land L = \{v \in U. \ w(v) > c \ / \ 2\} \}
\langle proof \rangle
```

5.2 The Proposed Approximation Algorithm

5.2.1 Functional Correctness

According to the article, inv_1 holds if $P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \mid v.\ v \in V\}$ is a correct solution for the bin packing problem [2]. However, various assumptions made in the article seem to suggest that more information is demanded from this invariant and, indeed, mere correctness (as defined in bp-def) does not appear to suffice. To amend this, four additional conjuncts have been added to this invariant, whose necessity will be explained in the following proofs. It should be noted that there may be other (shorter) ways to amend this invariant. This approach, however, makes for rather straight-forward proofs, as these conjuncts can be utilized and proved in relatively few steps.

```
definition inv_1:: 'a set set \Rightarrow 'a set set \Rightarrow 'a set \Rightarrow 'a set \Rightarrow 'a set \Rightarrow bool where inv_1 P_1 P_2 B_1 B_2 V \longleftrightarrow bp (P_1 \cup wrap\ B_1 \cup P_2 \cup wrap\ B_2 \cup \{\{v\}\ | v.\ v \in V\}) — A correct solution to the bin packing problem
```

 $\wedge \bigcup (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2) = U - V - \text{The partial solution does not contain objects that have not yet been assigned}$

 $\land B_1 \notin (P_1 \cup P_2 \cup wrap B_2) - B_1$ is distinct from all the other

bins

 \land $B_2 \notin (P_1 \cup wrap \ B_1 \cup P_2) \longrightarrow B_2$ is distinct from all the other

bins

 $\land (P_1 \cup wrap \ B_1) \cap (P_2 \cup wrap \ B_2) = \{\}$ — The first and second partial solutions are disjoint from each other.

```
lemma inv_1E:
```

```
assumes inv_1 P_1 P_2 B_1 B_2 V shows bp (P_1 \cup wrap B_1 \cup P_2 \cup wrap B_2 \cup \{\{v\} \mid v. \ v \in V\}) and \bigcup (P_1 \cup wrap B_1 \cup P_2 \cup wrap B_2) = U - V and B_1 \notin (P_1 \cup P_2 \cup wrap B_2) and B_2 \notin (P_1 \cup wrap B_1 \cup P_2) and (P_1 \cup wrap B_1) \cap (P_2 \cup wrap B_2) = \{\} \langle proof \rangle
```

lemma inv_1I :

```
assumes bp (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v.\ v \in V\})
```

```
and \bigcup (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2) = U - V

and B_1 \notin (P_1 \cup P_2 \cup wrap \ B_2)

and B_2 \notin (P_1 \cup wrap \ B_1 \cup P_2)

and (P_1 \cup wrap \ B_1) \cap (P_2 \cup wrap \ B_2) = \{\}

shows inv_1 \ P_1 \ P_2 \ B_1 \ B_2 \ V

\langle proof \rangle

lemma wrap-Un \ [simp]: wrap \ (M \cup \{x\}) = \{M \cup \{x\}\} \ \langle proof \rangle

lemma wrap-not-empty \ [simp]: wrap \ \{\} = \{\} \ \langle proof \rangle

lemma wrap-not-empty \ [simp]: M \neq \{\} \leftarrow wrap M = \{M} \leftarrow proof \rangle \leftarrow wrap M \neq \{M} \l
```

If inv_1 holds for the current partial solution, and the weight of an object $u \in V$ added to B_1 does not exceed its capacity, then inv_1 also holds if B_1 and $\{u\}$ are replaced by $B_1 \cup \{u\}$.

```
lemma inv_1-stepA:

assumes inv_1 \ P_1 \ P_2 \ B_1 \ B_2 \ V \ u \in V \ W(B_1) + w(u) \le c

shows inv_1 \ P_1 \ P_2 \ (B_1 \cup \{u\}) \ B_2 \ (V - \{u\})

\langle proof \rangle
```

If inv_1 holds for the current partial solution, and the weight of an object $u \in V$ added to B_2 does not exceed its capacity, then inv_1 also holds if B_2 and $\{u\}$ are replaced by $B_2 \cup \{u\}$.

```
lemma inv_1-stepB:
assumes inv_1 P_1 P_2 B_1 B_2 V u \in V W B_2 + w u \leq c
shows inv_1 (P_1 \cup wrap\ B_1) P_2 \{\} (B_2 \cup \{u\}) (V - \{u\}) \langle proof \rangle
```

If inv_1 holds for the current partial solution, then inv_1 also holds if B_1 and B_2 are added to P_1 and P_2 respectively, B_1 is emptied and B_2 initialized with $u \in V$.

```
lemma inv_1-stepC:
assumes inv_1 P_1 P_2 B_1 B_2 V u \in V
shows inv_1 (P_1 \cup wrap\ B_1) (P_2 \cup wrap\ B_2) \{\} \{u\} (V - \{u\}) \langle proof \rangle
```

A simplified version of the bin packing algorithm proposed in the article. It serves as an introduction into the approach taken, and, while it does not provide the desired approximation factor, it does ensure that P is a correct solution of the bin packing problem.

```
lemma simple-bp-correct: 

VARS\ P\ P_1\ P_2\ B_1\ B_2\ V\ u {True} 

P_1:=\{\};\ P_2:=\{\};\ B_1:=\{\};\ B_2:=\{\};\ V:=U; 

WHILE\ V\cap S\neq \{\}\ INV\ \{inv_1\ P_1\ P_2\ B_1\ B_2\ V\}\ DO 

u:=(SOME\ u.\ u\in V);\ V:=V-\{u\}; 

IF\ W(B_1)+w(u)\leq c 

THEN\ B_1:=B_1\cup \{u\} 

ELSE\ IF\ W(B_2)+w(u)\leq c
```

```
THEN \ B_2 := B_2 \cup \{u\} \\ ELSE \ P_2 := P_2 \cup wrap \ B_2; \ B_2 := \{u\} \ FI; \\ P_1 := P_1 \cup wrap \ B_1; \ B_1 := \{\} \ FI \\ OD; \\ P := P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \mid v. \ v \in V\} \\ \{bp \ P\} \\ \langle proof \rangle
```

5.2.2 Lower Bounds for the Bin Packing Problem

```
lemma bp-bins-finite [simp]:
assumes bp P
shows \forall B \in P. finite B
\langle proof \rangle
lemma bp-sol-finite [simp]:
assumes bp P
shows finite P
\langle proof \rangle
```

If P is a solution of the bin packing problem, then no bin in P may contain more than one large object.

```
lemma only-one-L-per-bin:

assumes bp\ P\ B\in P

shows \forall\ x\in B.\ \forall\ y\in B.\ x\neq y\longrightarrow x\notin L\ \lor\ y\notin L

\langle\ proof\ \rangle
```

If P is a solution of the bin packing problem, then the amount of large objects is a lower bound for the amount of bins in P.

```
lemma L-lower-bound-card: assumes bp\ P shows card\ L \leq card\ P \langle proof \rangle
```

If P is a solution of the bin packing problem, then the amount of bins of a subset of P in which every bin contains a large object is a lower bound on the amount of large objects.

```
lemma subset-bp-card:

assumes bp\ P\ M\subseteq P\ \forall\ B\in M.\ B\cap L\neq \{\}

shows card\ M\leq card\ L

\langle proof \rangle
```

If P is a correct solution of the bin packing problem, inv_1 holds for the partial solution, and every bin in $P_1 \cup wrap \ B_1$ contains a large object, then the amount of bins in $P_1 \cup wrap \ B_1 \cup \{\{v\} \mid v.\ v \in V \cap L\}$ is a lower bound for the amount of bins in P.

```
lemma L-bins-lower-bound-card: assumes bp\ P\ inv_1\ P_1\ P_2\ B_1\ B_2\ V\ \forall\ B\in P_1\cup\ wrap\ B_1.\ B\cap\ L\neq\{\}
```

```
shows card (P_1 \cup wrap \ B_1 \cup \{\{v\} \mid v. \ v \in V \cap L\}) \leq card \ P \langle proof \rangle
```

If P is a correct solution of the bin packing problem, then the sum of the weights of the objects is equal to the sum of the weights of the bins in P.

```
lemma sum-Un-eq-sum-sum:
assumes bp P
shows (\sum u \in U. \ w \ u) = (\sum B \in P. \ W \ B)
\langle proof \rangle
```

If P is a correct solution of the bin packing problem, then the sum of the weights of the items is a lower bound of amount of bins in P multiplied by their maximum capacity.

```
lemma sum-lower-bound-card:
   assumes bp\ P
   shows (\sum u \in U.\ w\ u) \le c * card\ P
\langle proof \rangle

lemma bp-NE:
   assumes bp\ P
   shows P \ne \{\}
\langle proof \rangle

lemma sum-Un-ge:
   fixes f :: - \Rightarrow real
   assumes finite\ M\ finite\ N\ \forall\ B \in M\ \cup\ N.\ 0 < f\ B
   shows sum\ f\ M \le sum\ f\ (M\ \cup\ N)
\langle proof \rangle
```

If bij-exists holds, one can obtain a function which is bijective between the bins in P and the objects in V such that an object returned by the function would cause the bin to exceed its capacity.

```
definition bij-exists :: 'a set set \Rightarrow 'a set \Rightarrow bool where bij-exists P \ V = (\exists f. \ bij-betw \ f \ P \ V \ \land (\forall B \in P. \ W \ B + w \ (f \ B) > c))
```

If P is a functionally correct solution of the bin packing problem, inv_1 holds for the partial solution, and such a bijective function exists between the bins in P_1 and the objects in $P_2 \cup wrap \ B_2$, the following strict lower bound can be shown:

```
lemma P_1-lower-bound-card:

assumes bp\ P\ inv_1\ P_1\ P_2\ B_1\ B_2\ V\ bij-exists P_1\ (\bigcup\ (P_2\cup\ wrap\ B_2))

shows card\ P_1+1\leq card\ P

\langle proof \rangle
```

As $card\ (wrap\ ?B) \le 1$ holds, it follows that the amount of bins in $P_1 \cup wrap\ B_1$ are a lower bound for the amount of bins in P.

lemma P_1 - B_1 -lower-bound-card:

```
assumes bp P inv<sub>1</sub> P_1 P_2 B_1 B_2 V bij-exists P_1 (\bigcup (P_2 \cup wrap \ B_2)) shows card (P_1 \cup wrap \ B_1) \leq card \ P
```

If inv_1 holds, there are at most half as many bins in P_2 as there are objects in P_2 , and we can again obtain a bijective function between the bins in P_1 and the objects of the second partial solution, then the amount of bins in the second partial solution are a strict lower bound for half the bins of the first partial solution.

```
lemma P_2-B_2-lower-bound-P_1:
assumes inv_1 P_1 P_2 B_1 B_2 V 2 * card P_2 \le card (\bigcup P_2) bij-exists P_1 (\bigcup (P_2 \cup wrap \ B_2))
shows 2 * card (P_2 \cup wrap \ B_2) \le card P_1 + 1
```

5.2.3 Proving the Approximation Factor

We define inv_2 as it is defined in the article. These conjuncts allow us to prove the desired approximation factor.

definition $inv_2 :: 'a \ set \ set \Rightarrow 'a \ set \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where}$ $inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ V \longleftrightarrow inv_1 \ P_1 \ P_2 \ B_1 \ B_2 \ V \smile inv_1 \ holds \ for \ the partial solution$

$$\land (V \cap L \neq \{\} \longrightarrow (\forall B \in P_1 \cup wrap \ B_1. \ B \cap L \neq \{\})) \longrightarrow$$

If there are still large objects left, then every bin of the first partial solution must contain a large object

 \wedge bij-exists P_1 ($\bigcup (P_2 \cup wrap \ B_2)$) — There exists a bijective function between the bins of the first partial solution and the objects of the second one

 $\land \ (2*card\ P_2 \leq card\ (\bigcup P_2)) \ -- \ \text{There are at most twice as many bins in } P_2 \ \text{as there are objects in } P_2$

```
lemma inv_2E:
assumes inv_2 P_1 P_2 B_1 B_2 V
shows inv_1 P_1 P_2 B_1 B_2 V
and V \cap L \neq \{\} \Longrightarrow \forall B \in P_1 \cup wrap \ B_1. B \cap L \neq \{\}
and bij-exists P_1 (\bigcup (P_2 \cup wrap \ B_2))
and 2 * card \ P_2 \leq card (\bigcup P_2)
\langle proof \rangle

lemma inv_2I:
assumes inv_1 P_1 P_2 B_1 B_2 V
and V \cap L \neq \{\} \Longrightarrow \forall B \in P_1 \cup wrap \ B_1. B \cap L \neq \{\}
and bij-exists P_1 (\bigcup (P_2 \cup wrap \ B_2))
and 2 * card \ P_2 \leq card (\bigcup P_2)
shows inv_2 P_1 P_2 P_1 P_2 P_1 P_2 P_2 P_2 P_3 P_3 P_3 P_3 P_3
```

If P is a correct solution of the bin packing problem, inv_2 holds for the partial solution, and there are no more small objects left to be distributed,

then the amount of bins of the partial solution is no larger than 3 / 2 of the amount of bins in P. This proof strongly follows the proof in *Theorem* 4.1 of the article [2].

```
lemma bin-packing-lower-bound-card:
```

```
assumes V \cap S = \{\} inv<sub>2</sub> P_1 P_2 B_1 B_2 V bp P shows card (P_1 \cup wrap\ B_1 \cup P_2 \cup wrap\ B_2 \cup \{\{v\}\ | v.\ v \in V\}) \leq 3 \ / \ 2*card\ P \langle proof \rangle
```

We define inv_3 as it is defined in the article. This final conjunct allows us to prove that the invariant will be maintained by the algorithm.

```
definition inv_3 :: 'a \ set \ set \Rightarrow 'a \ set \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow bool \ \mathbf{where} inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V \longleftrightarrow inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ V \land B_2 \subseteq S
```

lemma inv_3E :

```
assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V
shows inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ V and B_2 \subseteq S
\langle proof \rangle
```

lemma inv_3I :

```
assumes inv_2 P_1 P_2 B_1 B_2 V and B_2 \subseteq S shows inv_3 P_1 P_2 B_1 B_2 V \langle proof \rangle
```

lemma loop-init:

```
inv_3 {} {} {} {} {} {} {}
```

If B_1 is empty and there are no large objects left, then inv_3 will be maintained if B_1 is initialized with $u \in V \cap S$.

$\mathbf{lemma}\ loop\text{-}stepA\text{:}$

```
assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V \ B_1 = \{\} \ V \cap L = \{\} \ u \in V \cap S

shows inv_3 \ P_1 \ P_2 \ \{u\} \ B_2 \ (V - \{u\})
```

If B_1 is empty and there are large objects left, then inv_3 will be maintained if B_1 is initialized with $u \in V \cap L$.

lemma loop-stepB:

```
assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V \ B_1 = \{\} \ u \in V \cap L  shows inv_3 \ P_1 \ P_2 \ \{u\} \ B_2 \ (V - \{u\}) \langle proof \rangle
```

If B_1 is not empty and $u \in V \cap S$ does not exceed its maximum capacity, then inv_3 will be maintained if B_1 and $\{u\}$ are replaced with $B_1 \cup \{u\}$.

lemma loop-step C:

```
assumes inv_3 P_1 P_2 B_1 B_2 V B_1 \neq \{\} u \in V \cap S W B_1 + w(u) \leq c shows inv_3 P_1 P_2 (B_1 \cup \{u\}) B_2 (V - \{u\}) \langle proof \rangle
```

If B_1 is not empty and $u \in V \cap S$ does exceed its maximum capacity but not the capacity of B_2 , then inv_3 will be maintained if B_1 is added to P_1 and emptied, and B_2 and $\{u\}$ are replaced with $B_2 \cup \{u\}$.

lemma loop-stepD:

```
assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V \ B_1 \neq \{\} \ u \in V \cap S \ W \ B_1 + w(u) > c \ W \ B_2 + w(u) \leq c

shows inv_3 \ (P_1 \cup wrap \ B_1) \ P_2 \ \{\} \ (B_2 \cup \{u\}) \ (V - \{u\})

\langle proof \rangle
```

If the maximum capacity of B_2 is exceeded by $u \in V \cap S$, then B_2 must contain at least two objects.

```
lemma B_2-at-least-two-objects:

assumes inv_3 P_1 P_2 B_1 B_2 V u \in V \cap S W B_2 + w(u) > c

shows 2 \leq card B_2

\langle proof \rangle
```

If B_1 is not empty and $u \in V \cap S$ exceeds the maximum capacity of both B_1 and B_2 , then inv_3 will be maintained if B_1 and B_2 are added to P_1 and P_2 respectively, emptied, and B_2 initialized with u.

lemma loop-stepE:

```
assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V \ B_1 \neq \{\} \ u \in V \cap S \ W \ B_1 + w(u) > c \ W \ B_2 + w(u) > c

shows inv_3 \ (P_1 \cup wrap \ B_1) \ (P_2 \cup wrap \ B_2) \ \{\} \ \{u\} \ (V - \{u\}) \setminus proof \}
```

The bin packing algorithm as it is proposed in the article [2]. P will not only be a correct solution of the bin packing problem, but the amount of bins will be a lower bound for 3 / 2 of the amount of bins of any correct solution Q, and thus guarantee an approximation factor of 3 / 2 for the optimum.

```
lemma bp-approx:
```

```
VARS P P_1 P_2 B_1 B_2 V u
 P_1 := \{\}; P_2 := \{\}; B_1 := \{\}; B_2 := \{\}; V := U;
 WHILE V \cap S \neq \{\} INV \{inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ V\} DO
   IF B_1 \neq \{\}
   THEN u := (SOME \ u. \ u \in V \cap S)
   ELSE IF V \cap L \neq \{\}
        THEN u := (SOME \ u. \ u \in V \cap L)
        ELSE \ u := (SOME \ u. \ u \in V \cap S) \ FI \ FI;
   V:=\,V\,-\,\{u\};
   IF W(B_1) + w(u) \le c
   THEN\ B_1 := B_1 \cup \{u\}
   ELSE IF W(B_2) + w(u) \le c
        THEN B_2 := B_2 \cup \{u\}
        ELSE \ P_2 := P_2 \cup wrap \ B_2; \ B_2 := \{u\} \ FI;
        P_1 := P_1 \cup wrap \ B_1; \ B_1 := \{\} \ FI
 OD;
```

```
P := P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \mid v. \ v \in V\} \}\{bp \ P \land (\forall Q. \ bp \ Q \longrightarrow card \ P \leq 3 \ / \ 2 * card \ Q)\}\langle proof \rangle
```

end

5.3 The Full Linear Time Version of the Proposed Algorithm

Finally, we prove the Algorithm proposed on page 78 of the article [2]. This version generates the S and L sets beforehand and uses them directly to calculate the solution, thus removing the need for intersection operations, and ensuring linear time if we can perform *insertion*, removal, and selection of an element, the union of two sets, and the emptiness test in constant time [2].

```
locale BinPacking-Complete =
    fixes U :: 'a \ set — A finite, non-empty set of objects
          and w :: 'a \Rightarrow real — A mapping from objects to their respective weights
(positive real numbers)
        and c :: nat — The maximum capacity of a bin (as a natural number)
    assumes weight: \forall u \in U. \ 0 < w(u) \land w(u) \leq c
            and U-Finite: finite U
            and U-NE: U \neq \{\}
begin
          The correctness proofs will be identical to the ones of the simplified
algorithm.
abbreviation W :: 'a \ set \Rightarrow real \ \mathbf{where}
     W B \equiv (\sum u \in B. \ w(u))
definition bp :: 'a \ set \ set \Rightarrow bool \ \mathbf{where}
    bp \ P \longleftrightarrow partition-on \ U \ P \land (\forall B \in P. \ W(B) < c)
lemma bpE:
    assumes bp P
    shows pairwise disjnt P \{\} \notin P \bigcup P = U \ \forall B \in P. \ W(B) \le c
    \langle proof \rangle
lemma bpI:
    assumes pairwise disjnt P \{\} \notin P \bigcup P = U \ \forall B \in P. \ W(B) \le c
   shows bp P
    \langle proof \rangle
definition inv_1 :: 'a \ set \ set \Rightarrow 'a \ set \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow bool \ where
     inv_1 \ P_1 \ P_2 \ B_1 \ B_2 \ V \longleftrightarrow bp \ (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_1 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in P_2 \cup wrap \ B_2 \cup v. \}\}\}
 V}) — A correct solution to the bin packing problem
                                              \wedge \bigcup (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2) = U - V— The partial
solution does not contain objects that have not yet been assigned
```

```
bins
                     \land B_2 \notin (P_1 \cup wrap \ B_1 \cup P_2) \longrightarrow B_2 is distinct from all the other
bins
                          \land (P_1 \cup wrap \ B_1) \cap (P_2 \cup wrap \ B_2) = \{\} — The first and
second partial solutions are disjoint from each other.
lemma inv_1E:
  assumes inv_1 P_1 P_2 B_1 B_2 V
  shows by (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v. \ v \in V\})
    and \bigcup (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2) = U - V
    and B_1 \notin (P_1 \cup P_2 \cup wrap B_2)
    and B_2 \notin (P_1 \cup wrap \ B_1 \cup P_2)
    and (P_1 \cup wrap \ B_1) \cap (P_2 \cup wrap \ B_2) = \{\}
lemma inv_1I:
  assumes bp (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v.\ v \in V\})
    and \bigcup (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2) = U - V
    and B_1 \notin (P_1 \cup P_2 \cup wrap \ B_2)
    and B_2 \notin (P_1 \cup wrap \ B_1 \cup P_2)
    and (P_1 \cup wrap \ B_1) \cap (P_2 \cup wrap \ B_2) = \{\}
  shows inv_1 P_1 P_2 B_1 B_2 V
  \langle proof \rangle
lemma wrap-Un [simp]: wrap (M \cup \{x\}) = \{M \cup \{x\}\} \setminus proof \}
lemma wrap-empty [simp]: wrap \{\} = \{\} \langle proof \rangle
lemma wrap-not-empty [simp]: M \neq \{\} \longleftrightarrow wrap \ M = \{M\} \langle proof \rangle
lemma inv_1-stepA:
  assumes inv_1 P_1 P_2 B_1 B_2 V u \in V W(B_1) + w(u) \leq c
 shows inv_1 \ P_1 \ P_2 \ (B_1 \cup \{u\}) \ B_2 \ (V - \{u\})
\langle proof \rangle
lemma inv_1-stepB:
  assumes inv_1 P_1 P_2 B_1 B_2 V u \in V W B_2 + w u \leq c
  shows inv_1 (P_1 \cup wrap B_1) P_2 \{\} (B_2 \cup \{u\}) (V - \{u\})
\langle proof \rangle
lemma inv_1-stepC:
  assumes inv_1 P_1 P_2 B_1 B_2 V u \in V
  shows inv_1 (P_1 \cup wrap \ B_1) (P_2 \cup wrap \ B_2) \{\} \{u\} (V - \{u\})
```

 $\land B_1 \notin (P_1 \cup P_2 \cup wrap B_2) - B_1$ is distinct from all the other

From this point onward, we will require a different approach for proving lower bounds. Instead of fixing and assuming the definitions of the S and L sets, we will introduce the abbreviations S_U and L_U for any occurrences of the original S and L sets. The union of S and L can be interpreted as V. As a result, occurrences of $V \cap S$ become $(S \cup L) \cap S = S$, and $V \cap L$

become $(S \cup L) \cap L = L$. Occurrences of these sets will have to be replaced appropriately.

```
abbreviation S_U where S_U \equiv \{u \in U. \ w \ u \leq c \ / \ 2\} abbreviation L_U where L_U \equiv \{u \in U. \ c \ / \ 2 < w \ u\}
```

As we will remove elements from S and L, we will only be able to show that they remain subsets of S_U and L_U respectively.

```
abbreviation SL where
  SL \ S \ L \equiv S \subseteq S_U \land L \subseteq L_U
lemma bp-bins-finite [simp]:
  assumes bp P
  shows \forall B \in P. finite B
  \langle proof \rangle
lemma bp-sol-finite [simp]:
  assumes bp P
  shows finite P
  \langle proof \rangle
lemma only-one-L-per-bin:
  assumes bp P B \in P
  shows \forall x \in B. \ \forall y \in B. \ x \neq y \longrightarrow x \notin L_U \lor y \notin L_U
\langle proof \rangle
\mathbf{lemma}\ L\text{-}lower\text{-}bound\text{-}card:
  assumes bp P
  shows card L_U \leq card P
\langle proof \rangle
lemma subset-bp-card:
  assumes bp \ P \ M \subseteq P \ \forall B \in M. \ B \cap L_U \neq \{\}
  shows card M \leq card L_U
\langle proof \rangle
lemma L-bins-lower-bound-card:
  assumes by P inv<sub>1</sub> P_1 P_2 B_1 B_2 (S \cup L) \forall B \in P_1 \cup wrap B_1. B \cap L_U \neq \{\}
      and SL-def: SL S L
  shows card (P_1 \cup wrap \ B_1 \cup \{\{v\} \mid v. \ v \in L\}) \leq card \ P
\langle proof \rangle
lemma sum-Un-eq-sum-sum:
  assumes bp P
  shows (\sum u \in U. \ w \ u) = (\sum B \in P. \ W \ B)
\langle proof \rangle
```

```
lemma sum-lower-bound-card:
  assumes bp P
  shows (\sum u \in U. \ w \ u) \leq c * card P
lemma bp-NE:
  assumes bp P
  shows P \neq \{\}
  \langle proof \rangle
lemma sum-Un-ge:
  fixes f :: - \Rightarrow real
  assumes finite M finite N \ \forall B \in M \cup N. \ 0 < f B
  shows sum f M \leq sum f (M \cup N)
\langle proof \rangle
definition bij-exists :: 'a set set \Rightarrow 'a set \Rightarrow bool where
  bij-exists P \ V = (\exists f. \ bij-betw \ f \ P \ V \land (\forall B \in P. \ W \ B + w \ (f \ B) > c))
lemma P_1-lower-bound-card:
  assumes bp P inv<sub>1</sub> P<sub>1</sub> P<sub>2</sub> B<sub>1</sub> B<sub>2</sub> (S \cup L) bij-exists P<sub>1</sub> (\bigcup (P<sub>2</sub> \cup wrap B<sub>2</sub>))
  shows card P_1 + 1 \le card P
\langle proof \rangle
lemma P_1-B_1-lower-bound-card:
  assumes by P inv_1 P_1 P_2 B_1 B_2 (S \cup L) bij-exists P_1 (\bigcup (P_2 \cup wrap B_2))
  shows card (P_1 \cup wrap B_1) \leq card P
\langle proof \rangle
lemma P_2-B_2-lower-bound-P_1:
  assumes inv_1 P_1 P_2 B_1 B_2 (S \cup L) 2 * card P_2 \leq card (\bigcup P_2) bij-exists P_1
(\bigcup (P_2 \cup wrap \ B_2))
 shows 2 * card (P_2 \cup wrap B_2) \le card P_1 + 1
     We add SL S L to inv_2 to ensure that the S and L sets only contain
objects with correct weights.
definition inv_2 :: 'a \ set \ set \Rightarrow 'a \ set \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow 'a \ set \Rightarrow
bool where
  inv_2 P_1 P_2 B_1 B_2 S L \longleftrightarrow inv_1 P_1 P_2 B_1 B_2 (S \cup L) \longrightarrow inv_1 holds for the
partial solution
                      \land (L \neq \{\} \longrightarrow (\forall B \in P_1 \cup wrap \ B_1. \ B \cap L_U \neq \{\})) — If there
are still large objects left, then every bin of the first partial solution must contain
a large object
                         \land bij\text{-}exists\ P_1\ (\bigcup (P_2 \cup wrap\ B_2)) — There exists a bijective
function between the bins of the first partial solution and the objects of the second
one
                         \wedge (2 * card P_2 \leq card (\bigcup P_2)) — There are at most twice as
many bins in P_2 as there are objects in P_2
```

```
lemma inv_2E:
  assumes inv_2 P_1 P_2 B_1 B_2 S L
  shows inv_1 P_1 P_2 B_1 B_2 (S \cup L)
    and L \neq \{\} \Longrightarrow \forall B \in P_1 \cup wrap \ B_1. \ B \cap L_U \neq \{\}
    and bij-exists P_1 (\bigcup (P_2 \cup wrap B_2))
    and 2 * card P_2 \leq card (\bigcup P_2)
    and SL\ S\ L
  \langle proof \rangle
lemma inv_2I:
  assumes inv_1 P_1 P_2 B_1 B_2 (S \cup L)
    and L \neq \{\} \Longrightarrow \forall B \in P_1 \cup wrap \ B_1. \ B \cap L_U \neq \{\}
    and bij-exists P_1 (\bigcup (P_2 \cup wrap B_2))
    and 2 * card P_2 \le card (\bigcup P_2)
    and SL S L
  shows inv_2 P_1 P_2 B_1 B_2 S L
  \langle proof \rangle
lemma bin-packing-lower-bound-card:
  assumes S = \{\} inv<sub>2</sub> P_1 P_2 B_1 B_2 S L bp P
  shows card (P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2 \cup \{\{v\} \ | v.\ v \in S \cup L\}) \le 3 \ / \ 2 *
card P
\langle proof \rangle
definition inv_3 :: 'a set set \Rightarrow 'a set set \Rightarrow 'a set \Rightarrow 'a set \Rightarrow 'a set \Rightarrow 'a set \Rightarrow
bool where
  inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \longleftrightarrow inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \wedge B_2 \subseteq S_U
lemma inv_3E:
  assumes inv_3 P_1 P_2 B_1 B_2 S L
  shows inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ and \ B_2 \subseteq S_U
  \langle proof \rangle
lemma inv_3I:
  assumes inv_2 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ \text{and} \ B_2 \subseteq S_U
  shows inv_3 P_1 P_2 B_1 B_2 S L
  \langle proof \rangle
lemma loop-init:
  inv_3 {} {} {} {} {} {} {} {}
\langle proof \rangle
lemma loop-step A:
  assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ B_1 = \{\} \ L = \{\} \ u \in S
  shows inv_3 \ P_1 \ P_2 \ \{u\} \ B_2 \ (S - \{u\}) \ L
\langle proof \rangle
```

```
lemma loop-stepB:
  assumes inv_3 P_1 P_2 B_1 B_2 S L B_1 = \{\} u \in L
  shows inv_3 \ P_1 \ P_2 \ \{u\} \ B_2 \ S \ (L - \{u\})
\langle proof \rangle
lemma loop-step C:
 assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ B_1 \neq \{\} \ u \in S \ W \ B_1 + w(u) \leq c
  shows inv_3 \ P_1 \ P_2 \ (B_1 \cup \{u\}) \ B_2 \ (S - \{u\}) \ L
\langle proof \rangle
lemma loop-stepD:
  assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ B_1 \neq \{\} \ u \in S \ W \ B_1 + w(u) > c \ W \ B_2 +
 shows inv_3 (P_1 \cup wrap \ B_1) \ P_2 \ \{\} \ (B_2 \cup \{u\}) \ (S - \{u\}) \ L
\langle proof \rangle
lemma B_2-at-least-two-objects:
 assumes inv_3 P_1 P_2 B_1 B_2 S L u \in S W B_2 + w(u) > c
 shows 2 \leq card B_2
\langle proof \rangle
lemma loop-stepE:
  assumes inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \ B_1 \neq \{\} \ u \in S \ W \ B_1 + w(u) > c \ W \ B_2 +
  shows inv_3 (P_1 \cup wrap B_1) (P_2 \cup wrap B_2) \{\} \{u\} (S - \{u\}) L
\langle proof \rangle
```

The bin packing algorithm as it is proposed on page 78 of the article [2]. P will not only be a correct solution of the bin packing problem, but the amount of bins will be a lower bound for 3 / 2 of the amount of bins of any correct solution Q, and thus guarantee an approximation factor of 3 / 2 for the optimum.

```
lemma bp-approx:
VARS P P_1 P_2 B_1 B_2 V S L u
  \{True\}
  S := \{\}; L := \{\}; V := U;
  WHILE V \neq \{\} INV \{V \subseteq U \land S = \{u \in U - V. w(u) \le c / 2\} \land L = \{u \in U \cap V. w(u) \le c / 2\}
U - V. c / 2 < w(u) \} \} DO
    u := (SOME \ u. \ u \in V);
    IF w(u) < c / 2
    THEN S := S \cup \{u\}
    ELSE\ L := L \cup \{u\}\ FI;
    V := V - \{u\}
  OD;
  P_1 := \{\}; P_2 := \{\}; B_1 := \{\}; B_2 := \{\};
  \textit{WHILE S} \neq \{\} \textit{ INV } \{\textit{inv}_3 \textit{ P}_1 \textit{ P}_2 \textit{ B}_1 \textit{ B}_2 \textit{ S} \textit{ L}\} \textit{ DO}
    IF B_1 \neq \{\}
    THEN u := (SOME \ u. \ u \in S); \ S := S - \{u\}
    ELSE IF L \neq \{\}
```

```
THEN u := (SOME \ u. \ u \in L); \ L := L - \{u\}
          ELSE\ u := (SOME\ u.\ u \in S);\ S := S - \{u\}\ FI\ FI;
    IF\ W(B_1) + w(u) \le c
    THEN B_1 := B_1 \cup \{u\}
    ELSE IF W(B_2) + w(u) \le c
          THEN B_2 := B_2 \cup \{u\}
         ELSE P_2 := P_2 \cup wrap \ B_2; \ B_2 := \{u\} \ FI;

P_1 := P_1 \cup wrap \ B_1; \ B_1 := \{\} \ FI
  OD:
  P := P_1 \cup wrap \ B_1 \cup P_2 \cup wrap \ B_2; \ V := L;
  WHILE V \neq \{\}
  INV \{S = \{\} \land inv_3 \ P_1 \ P_2 \ B_1 \ B_2 \ S \ L \land V \subseteq L \land P = P_1 \cup wrap \ B_1 \cup P_2 \cup P_3 \}
wrap B_2 \cup \{\{v\} | v. \ v \in L - V\}\}\ DO
    u := (SOME \ u. \ u \in V); \ P := P \cup \{\{u\}\}; \ V := V - \{u\}\}
  \{bp\ P \land (\forall\ Q.\ bp\ Q \longrightarrow card\ P \leq 3\ /\ 2* card\ Q)\}
\langle proof \rangle
end
```

CHU

end

6 Center Selection

```
theory Center-Selection
imports Complex-Main HOL-Hoare.Hoare-Logic
begin
```

The Center Selection (or metric k-center) problem. Given a set of *sites* S in a metric space, find a subset $C \subseteq S$ that minimizes the maximal distance from any $s \in S$ to some $c \in C$. This theory presents a verified 2-approximation algorithm. It is based on Section 11.2 in the book by Kleinberg and Tardos [4]. In contrast to the proof in the book, our proof is a standard invariant proof.

```
locale Center-Selection =
    fixes S:: ('a::metric\text{-}space) \ set
    and k::nat
    assumes finite-sites: finite S
    and non\text{-}empty\text{-}sites: S \neq \{\}
and non\text{-}zero\text{-}k: k > 0
begin

definition distance :: ('a::metric-space) set \Rightarrow ('a::metric-space) \Rightarrow real where distance C s = Min (dist s 'C)

definition radius :: ('a :: metric-space) set \Rightarrow real where radius C = Max (distance C 'S)
```

```
lemma distance-mono:
assumes C_1 \subseteq C_2 and C_1 \neq \{\} and finite C_2
shows distance C_1 s \ge distance C_2 s
lemma finite-distances: finite (distance C 'S)
  \langle proof \rangle
lemma non-empty-distances: distance C 'S \neq \{\}
  \langle proof \rangle
\mathbf{lemma}\ \mathit{radius\text{-}contained}\colon \mathit{radius}\ C\in \mathit{distance}\ C\ `S
  \langle proof \rangle
lemma radius-def2: \exists s \in S. distance C s = radius C
  \langle proof \rangle
lemma dist-lemmas-aux:
  assumes finite C
      and C \neq \{\}
  shows finite (dist s 'C)
    and finite (dist s ' C) \Longrightarrow distance C s \in dist s ' C
    and distance C \ s \in dist \ s \ `C \Longrightarrow \exists \ c \in C. \ dist \ s \ c = \ distance \ C \ s
and \exists c \in C. dist s \ c = distance \ C \ s \Longrightarrow distance \ C \ s \ge 0
\langle proof \rangle
lemma dist-lemmas:
  assumes finite C
      and C \neq \{\}
  shows finite (dist s 'C)
    and distance\ C\ s\in dist\ s ' C
    and \exists c \in C. dist s c = distance C s
    and distance C s \ge 0
  \langle proof \rangle
lemma radius-max-prop: (\forall s \in S. \ distance \ C \ s \leq r) \Longrightarrow (radius \ C \leq r)
  \langle proof \rangle
lemma dist-ins:
assumes \forall c_1 \in C. \ \forall c_2 \in C. \ c_1 \neq c_2 \longrightarrow x < dist \ c_1 \ c_2
and distance C s > x
and finite C
and C \neq \{\}
shows \forall c_1 \in (C \cup \{s\}). \ \forall c_2 \in (C \cup \{s\}). \ c_1 \neq c_2 \longrightarrow x < dist \ c_1 \ c_2
\langle proof \rangle
```

6.1 A Preliminary Algorithm and Proof

This subsection verifies an auxiliary algorithm by Kleinberg and Tardos. Our proof of the main algorithm does not does not rely on this auxiliary algorithm at all but we do reuse part off its invariant proof later on.

```
definition inv :: ('a :: metric-space) set \Rightarrow ('a :: metric-space set) \Rightarrow real \Rightarrow bool
where
inv\ S'\ C\ r =
  ((\forall s \in (S - S'). \ distance \ C \ s \leq 2*r) \land S' \subseteq S \land C \subseteq S \land C
   (\forall c \in C. \ \forall s \in S'. \ S' \neq \{\} \longrightarrow \textit{dist } c \ s > 2 * r) \land (S' = S \lor C \neq \{\}) \land 
   (\forall c_1 \in C. \ \forall c_2 \in C. \ c_1 \neq c_2 \longrightarrow dist \ c_1 \ c_2 > 2 * r))
lemma inv-init: inv S \{ \} r
  \langle proof \rangle
lemma inv-step:
  assumes S' \neq \{\}
and IH: inv S' C r
defines[simp]: s \equiv (SOME \ s. \ s \in S')
shows inv (S' - \{s' : s' \in S' \land dist \ s \ s' \leq 2*r\}) \ (C \cup \{s\}) \ r
\langle proof \rangle
lemma inv-last-1:
  assumes \forall s \in (S - S'). distance C \le 2 * r
    and S' = \{\}
  shows radius C \leq 2*r
  \langle proof \rangle
lemma inv-last-2:
  assumes finite C
  and card C > n
  and C \subseteq S
  and \forall c_1 \in C. \ \forall c_2 \in C. \ c_1 \neq c_2 \longrightarrow dist \ c_1 \ c_2 > 2 * r
  shows \forall C'. card C' \leq n \land card C' > 0 \longrightarrow radius C' > r (is ?P)
\langle proof \rangle
lemma inv-last:
  assumes inv \{\} C r
  shows (card C \leq k \longrightarrow radius \ C \leq 2*r) \land (card C > k \longrightarrow (\forall C'. card \ C' > k)
0 \land card C' \leq k \longrightarrow radius C' > r)
  \langle proof \rangle
{\bf theorem}\ {\it Center-Selection-r}:
   VARS (S' :: ('a :: metric-space) set) (C :: ('a :: metric-space) set) (r :: real) (s
:: 'a)
  \{True\}
  S' := S;
  C := \{\};
  WHILE S' \neq \{\} INV \{inv \ S' \ C \ r\} DO
    s := (SOME \ s. \ s \in S');
```

```
\begin{array}{l} C := \ C \ \cup \ \{s\}; \\ S' := \ S' \ - \ \{s' \ . \ s' \in \ S' \ \wedge \ dist \ s \ s' \leq \ 2*r\} \end{array}
  \{(card\ C \leq k \longrightarrow radius\ C \leq 2*r) \land (card\ C > k \longrightarrow (\forall\ C'.\ card\ C' > 0 \land C')\}
card C' \leq k \longrightarrow radius C' > r))
\langle proof \rangle
6.2
         The Main Algorithm
definition invar :: ('a :: metric-space) set <math>\Rightarrow bool where
invar C = (C \neq \{\} \land card \ C \leq k \land C \subseteq S \land A\}
  (\forall \ C'. \ (\forall \ c_1 \in C. \ \forall \ c_2 \in C. \ c_1 \neq c_2 \longrightarrow \textit{dist } c_1 \ c_2 > \textit{2} * \textit{radius } C')
        \lor (\forall s \in S. \ distance \ C \ s \leq 2 * radius \ C')))
abbreviation some where some A \equiv (SOME \ s. \ s \in A)
lemma invar-init: invar {some S}
\langle proof \rangle
abbreviation furthest-from where
furthest-from C \equiv (SOME \ s. \ s \in S \land distance \ C \ s = Max \ (distance \ C \ `S))
lemma invar-step:
assumes invar C
and card C < k
shows invar (C \cup \{furthest\text{-}from \ C\})
\langle proof \rangle
lemma invar-last:
assumes invar C and \neg card C < k
shows card C = k and card C' > 0 \land card C' \le k \longrightarrow radius C \le 2 * radius C'
\langle proof \rangle
theorem Center-Selection:
VARS\ (C::('a::metric-space)\ set)\ (s::('a::metric-space))
  \{k \leq card S\}
  C := \{some \ S\};
  WHILE card C < k INV \{invar\ C\} DO
    C := C \cup \{furthest-from \ C\}
  \{card\ C=k \land (\forall\ C'.\ card\ C'>0 \land card\ C'\leq k \longrightarrow radius\ C\leq 2*radius\}
C')
```

end end

 $\langle proof \rangle$

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